

Stability evaluation of a railway timetable at the station level

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Presentation overview

- ❑ Railroad infrastructure operation planning
- ❑ RECIFE project
- ❑ Stability evaluation model
- ❑ Example of stability evaluation
- ❑ Conclusion

Rail transport context

Rail transport

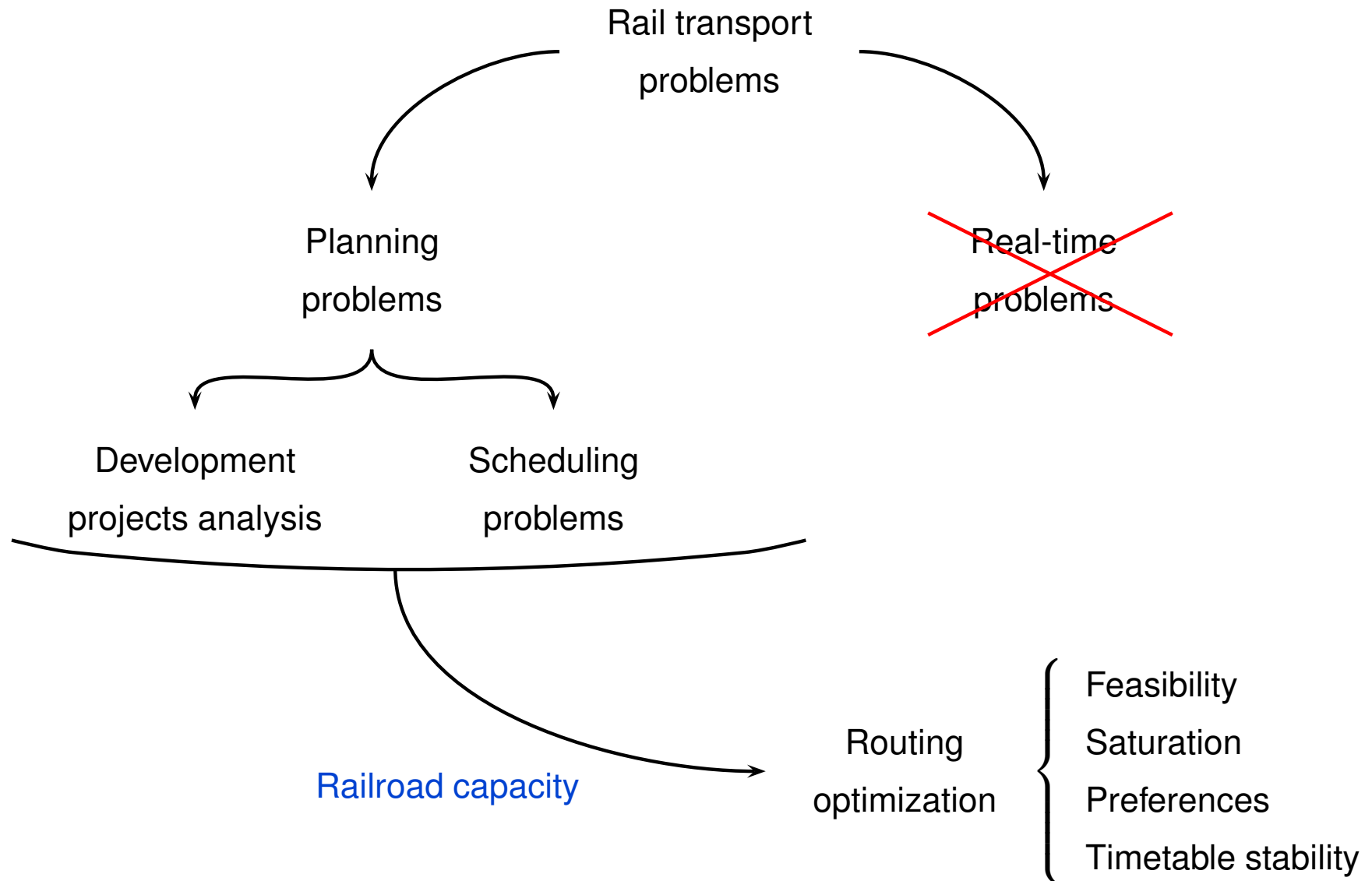
- ❑ Interest revival as road alternative
 - ❑ Competition with other transport modes
- ⇒ Traffic increase and evolution

Tools are needed for

- ❑ evaluating networks limits
- ❑ studying modifications of the network
- ❑ determining a commercial strategy

How to plan railroad infrastructure operation ?

Main questions considered



Existing softwares

Homogeneous zones (lines)

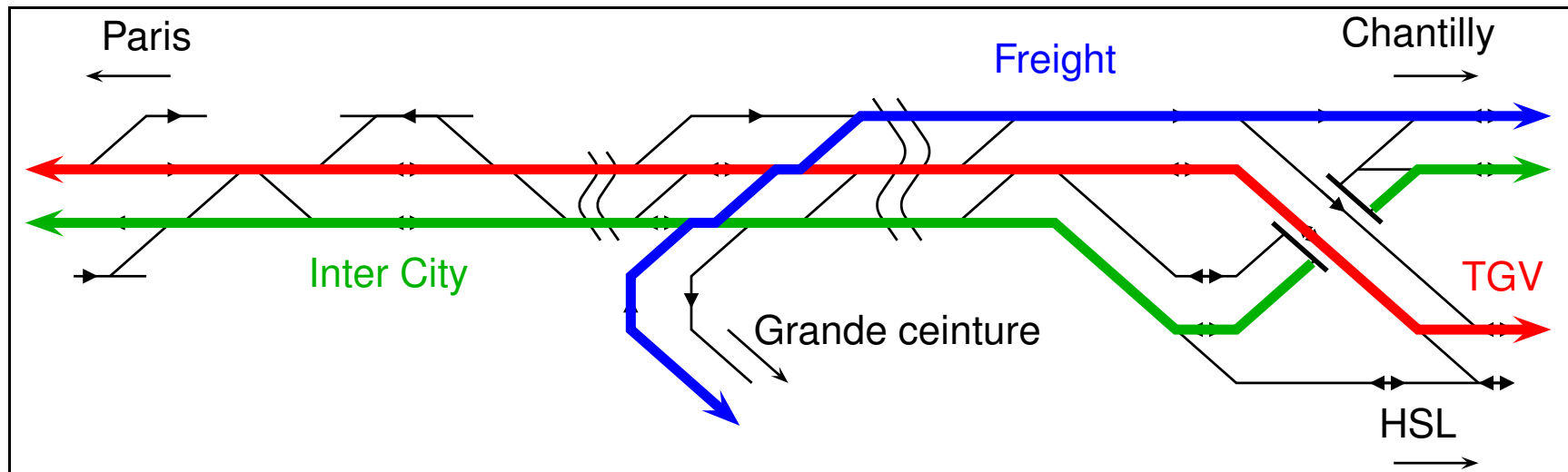
- ❑ Analytical methods [UIC, 1978]

Heterogeneous zones (junction, station, network)

- ❑ Simulation
 - ❑ Constructive methods
 - DONS [van den Berg and Odijk, 1994]
 - CAPRES [Hachemane, 1997]
 - DÉMIURGE [Labouisse and Djellab, 2001]
- ⇒ mainly on network level

Railroad infrastructure capacity

Given :



+ {
Safety rules
Rolling stock technical characteristics
Service quality

- ❑ How many trains can be routed through the junction within a time interval ?
- ❑ What is the best solution to route these trains ?

- ❑ Railroad infrastructure operation planning
- ❑ **RECIFE project**
- ❑ Stability evaluation model
- ❑ Example of stability evaluation
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The RECIFE project

Objective of RECIFE

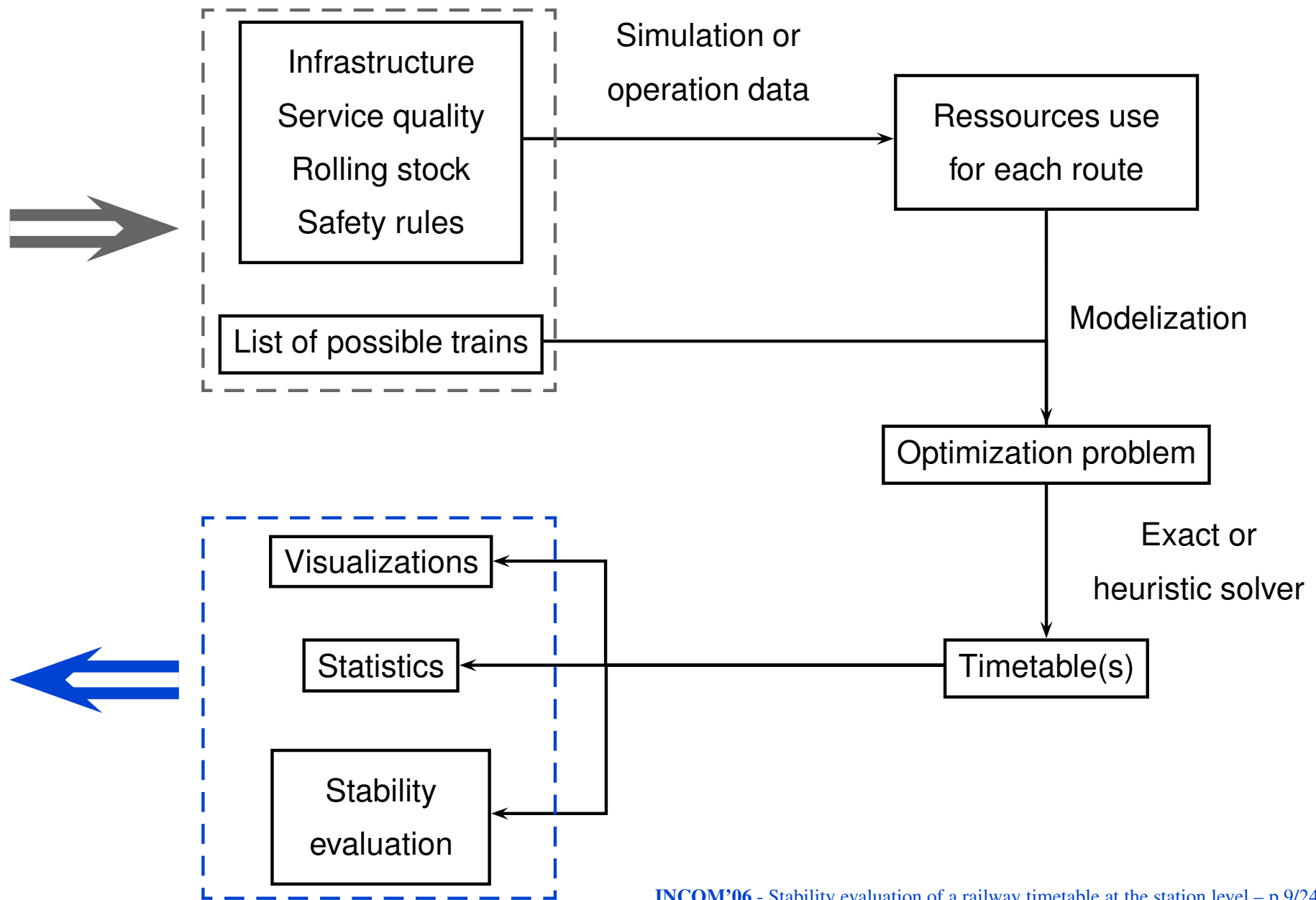
- ❑ Models to evaluate railroad infrastructure capacity of junction or station
- ❑ Solvers based on combinatorial optimization algorithms
- ❑ Application on Pierrefitte-Gonesse node and Lille-Flandres station

⇒ Decision support software

Partners involved

- ❑ French institute on transport (INRETS)
- ❑ French railway society (SNCF)
- ❑ Ecole des mines de Saint-Etienne
- ❑ Nantes university
- ❑ Valenciennes university

Global scheme of the RECIFE software



Model for capacity evaluation

Assumptions

- ❑ All possible routes are given
- ❑ All possible arrival-date are given

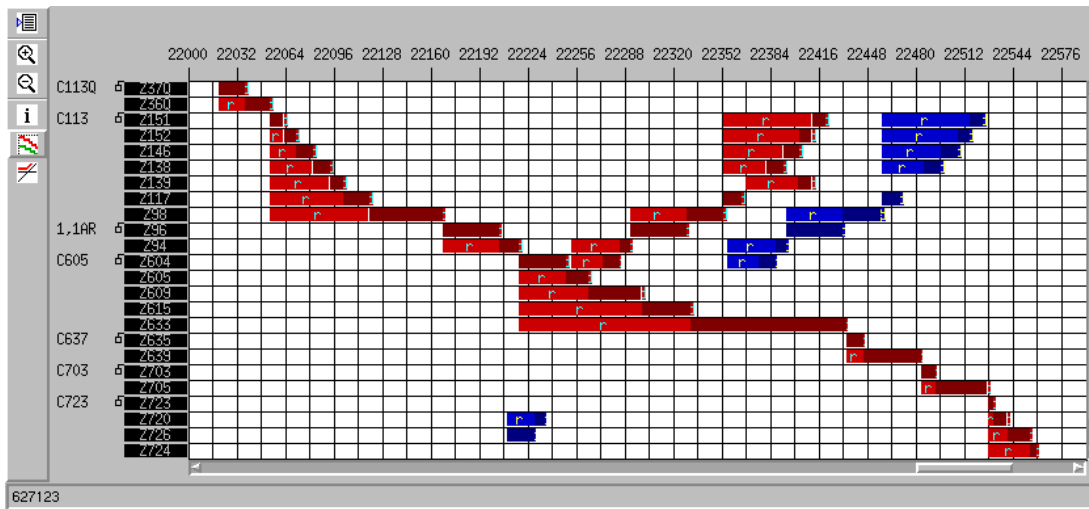
Combinatorial optimization model [Delorme, 2003]

- ❑ multiobjective extension of STATIONS model [Zwaneveld et al, 1996]
- ❑ based on binary decision variables

$$x_{t,r,\delta} = \begin{cases} 1 & \text{if the train } t \text{ is assigned to the route } r \text{ on clear-line} \\ & \text{with a delay } \delta \text{ on its arrival-date} \\ 0 & \text{otherwise} \end{cases}$$

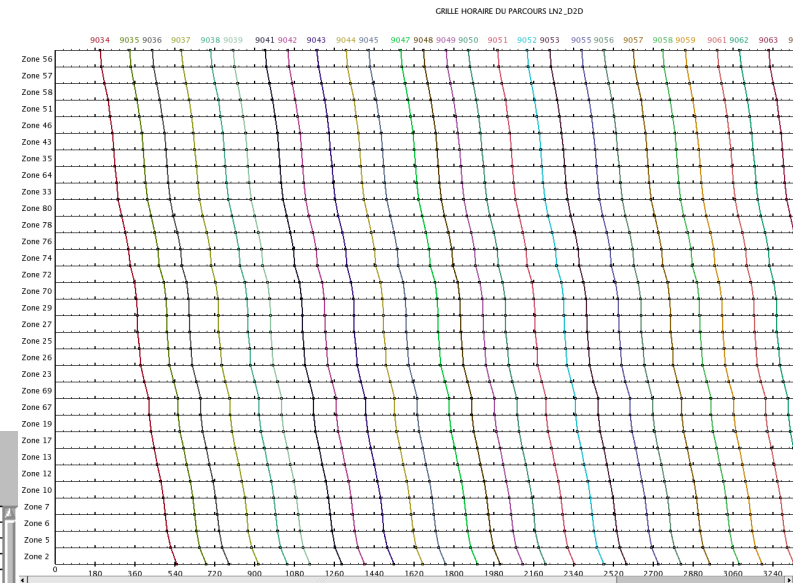
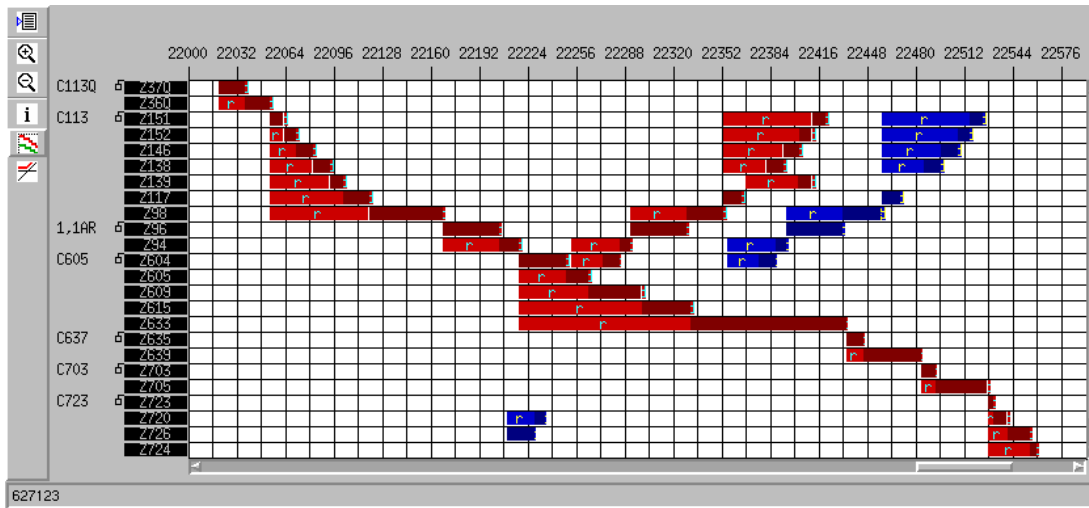
Visualization of timetables

☐ Gantt chart



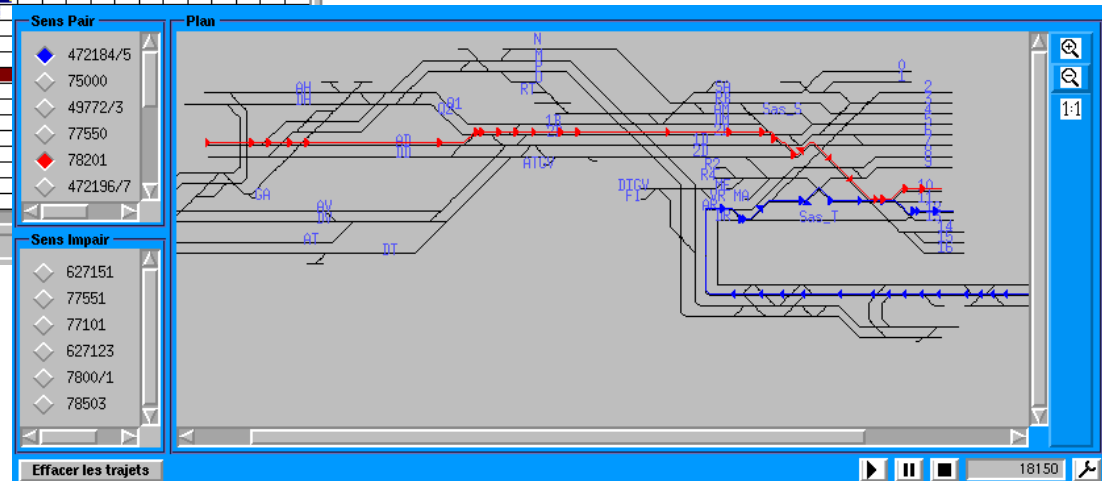
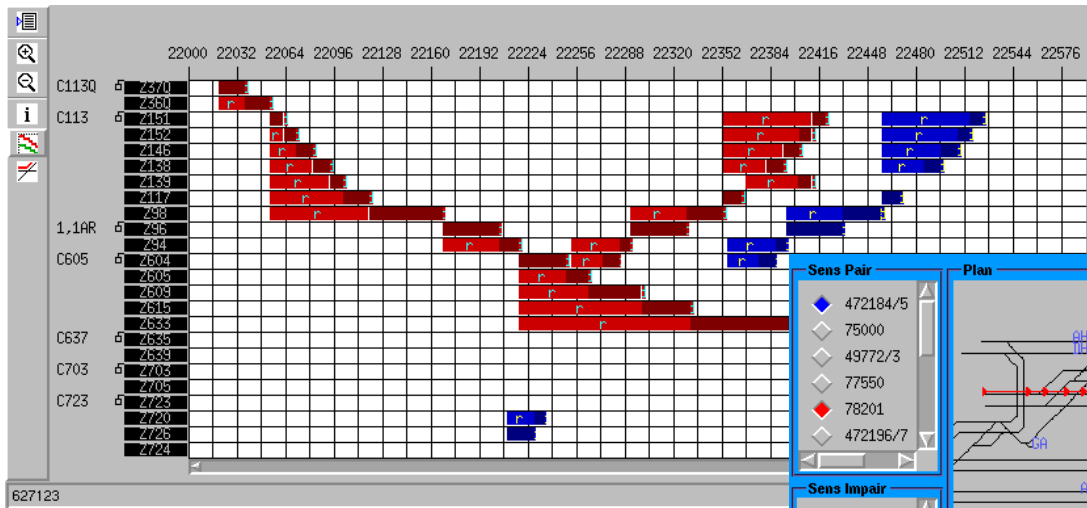
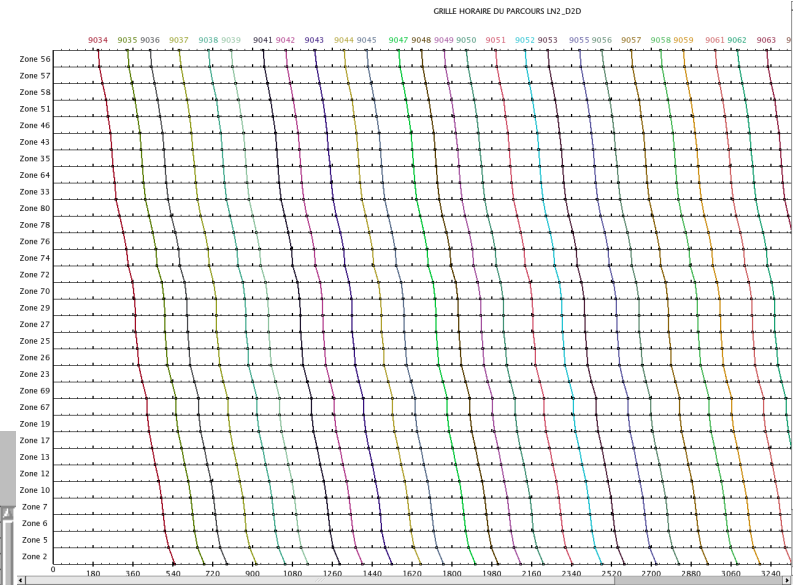
Visualization of timetables

- ☐ Gantt chart
- ☐ Space-time diagram



Visualization of timetables

- ☐ Gantt chart
- ☐ Space-time diagram
- ☐ Tracks map
- ☐ Simulation



Stability evaluation model

- ❑ Railroad infrastructure operation planning
- ❑ RECIFE project
- ❑ **Stability evaluation model**
- ❑ Example of stability evaluation
- ❑ Conclusion

Previous works on stability

Classic methods are based on :

- ❑ either Petri nets
- ❑ or Max-plus algebra

Type of stability evaluation

- ❑ Recovering time for a cyclic timetable
⇒ impossible if non-cyclic
- ❑ Time margin of the trains
⇒ nearly null for saturated timetable

New model based on delay propagation

Delay propagation

2 types of delay

- ❑ primary delay caused by a disruption
- ❑ secondary delay due to interactions between trains

Impact of a primary delay

- ❑ secondary delays generated directly or indirectly

How to prevent conflicts

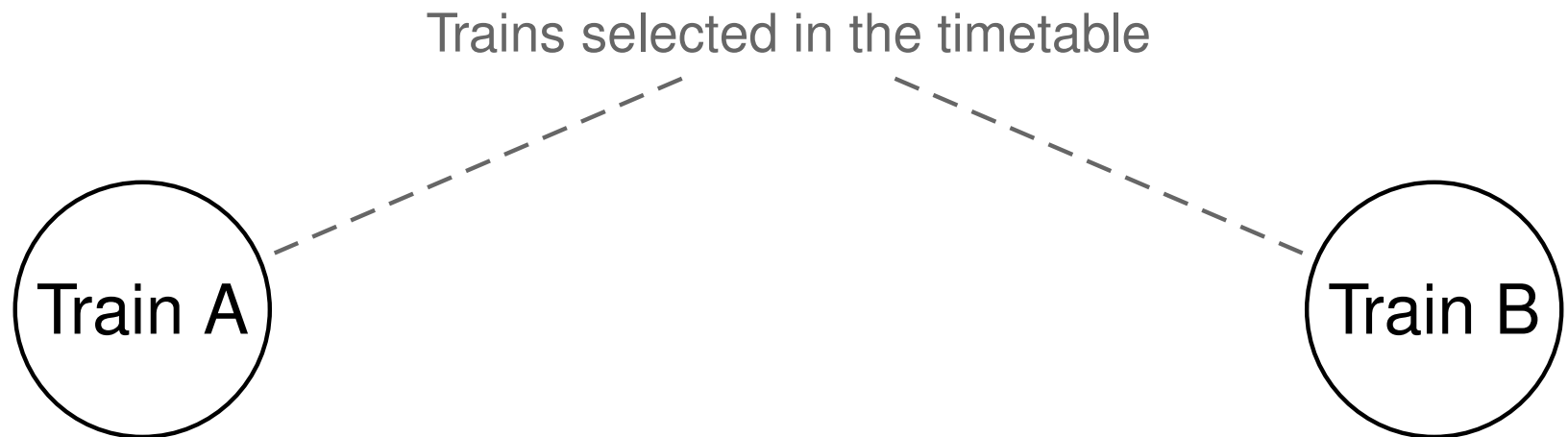
- ❑ delay of arrival-date of other trains
- ❑ Same routes and scheduling (no on-line Re-optimizing)

⇒ only short primary delay

Graph of potential direct conflicts

Use of potential direct conflict

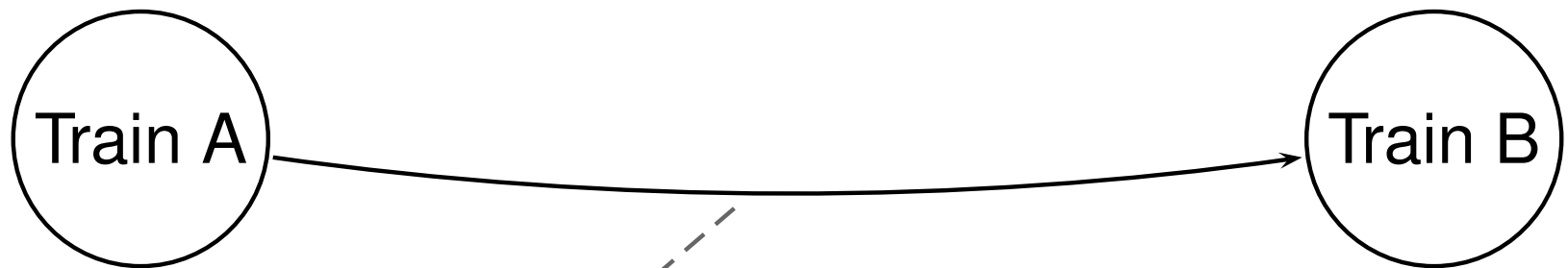
Represented with a graph $G(V, E, w)$



Graph of potential direct conflicts

Use of potential direct conflict

Represented with a graph $G(V, E, w)$

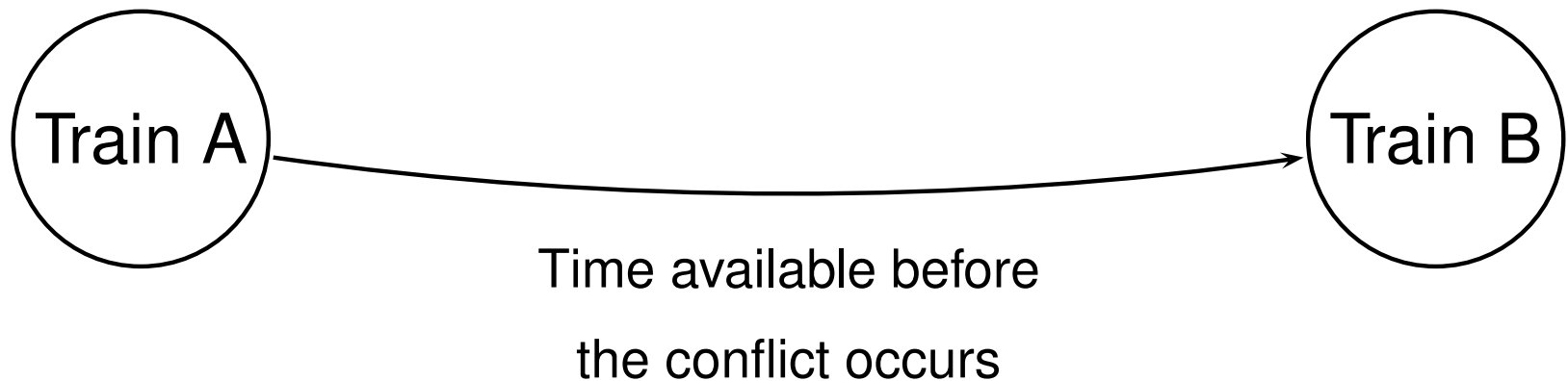


There is a potential
conflict if the train A is delayed

Graph of potential direct conflicts

Use of potential direct conflict

Represented with a graph $G(V, E, w)$



Computation of stability evaluation

Computation of the secondary delays generated

- ❑ Time margin between Train A and B =
shortest path in $G(V, E, w)$
- ❑ Secondary delay generated by a primary delay of Train A on Train B =

$$\max(0, \text{Primary delay}(A) - \text{Shortest path}(A, B))$$

Stability evaluation of a timetable

- ❑ Sum of all the secondary delays generated by each train
- ❑ Inspired by the know-how
- ❑ Importance of the primary delay
 \Rightarrow several values considered

Example of stability evaluation

- ❑ Railroad infrastructure operation planning
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Description of the example

Didactic instance on Pierrefitte-Gonesse node

- ❑ 6 possible trains considered
- ❑ 450s between the first and last arrival dates

Optimization problem

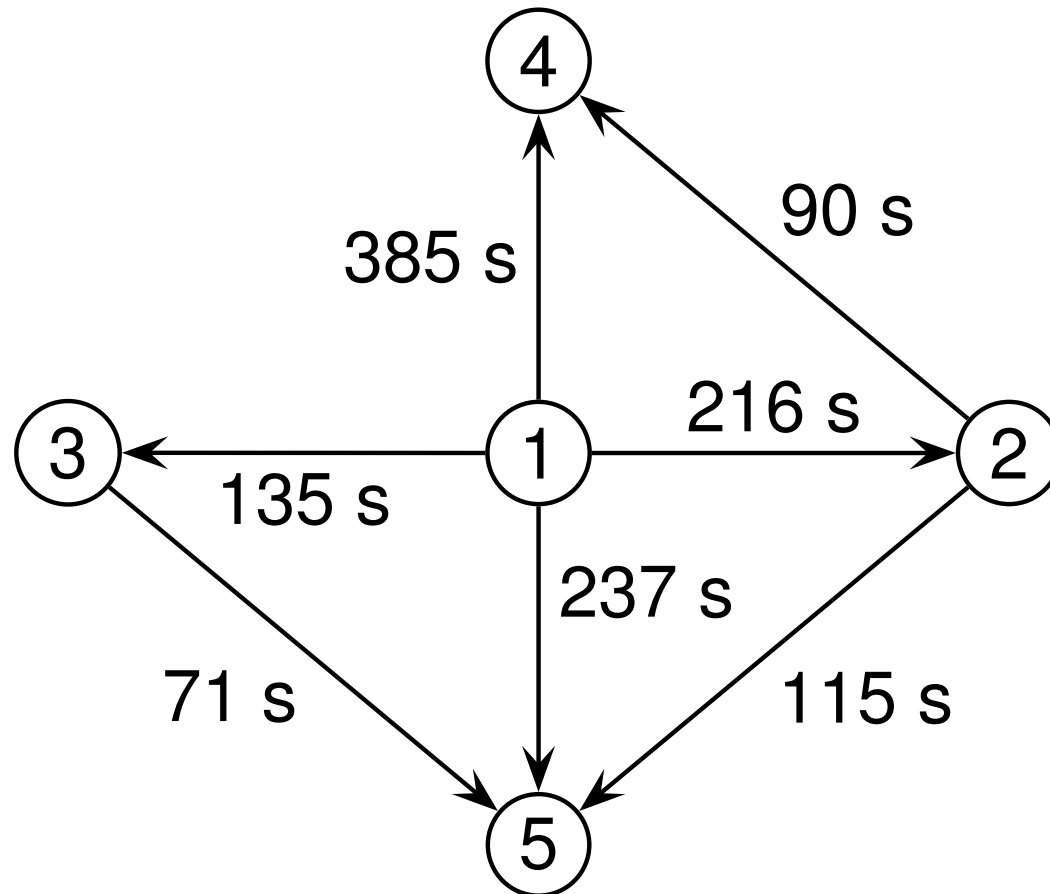
- ❑ Conflicts determined with SYSIFE simulator [Fontaine and Gauyacq, 2001]
- ❑ Heuristic solver GRASP [Delorme et al, 2004]

⇒ $\left\{ \begin{array}{l} 5 \text{ trains routed (optimal solution)} \\ 15 \text{ different timetables generated} \end{array} \right.$

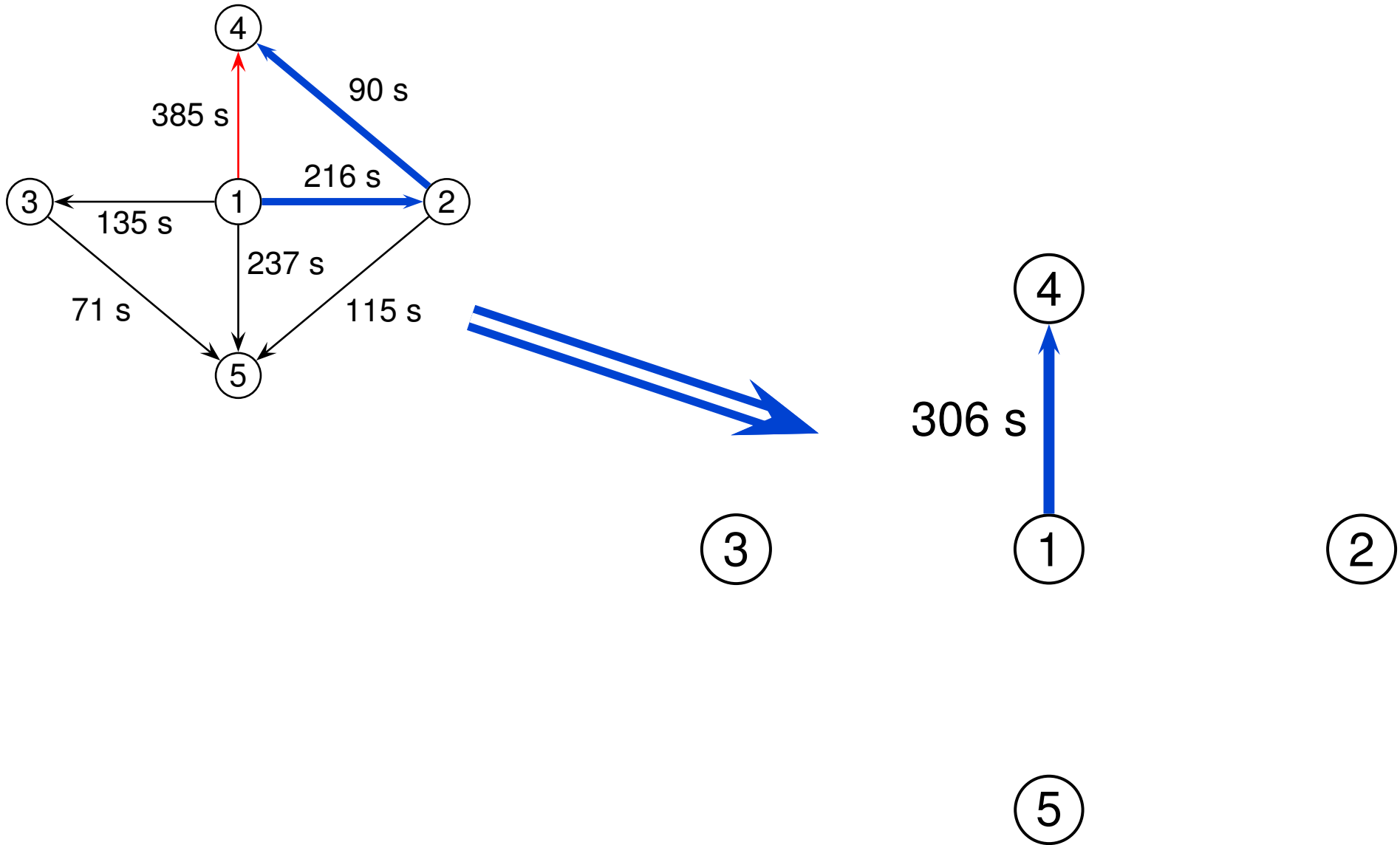
Stability evaluation of one timetable

One graph generated for each timetable

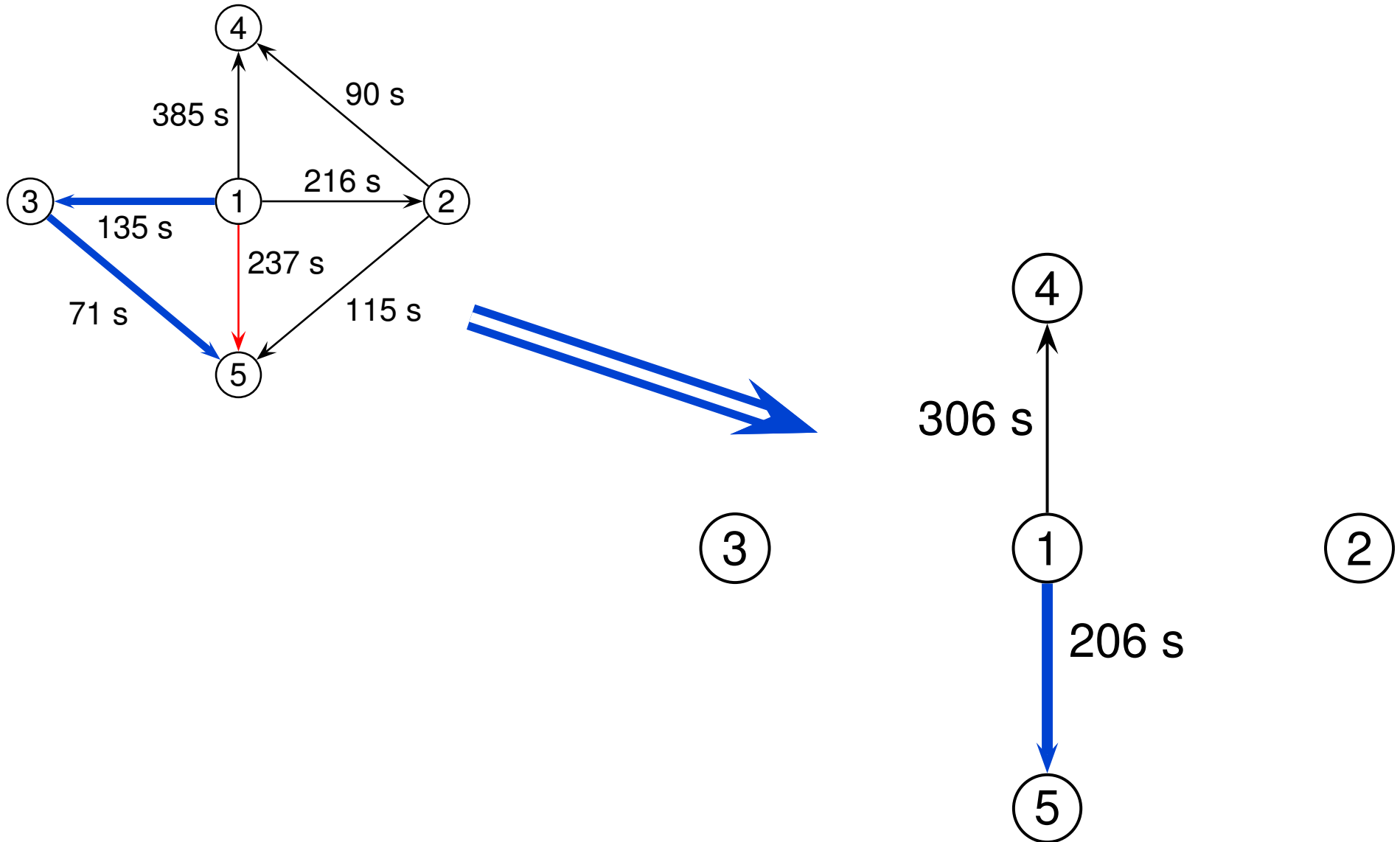
□ Graph of potential direct conflicts :



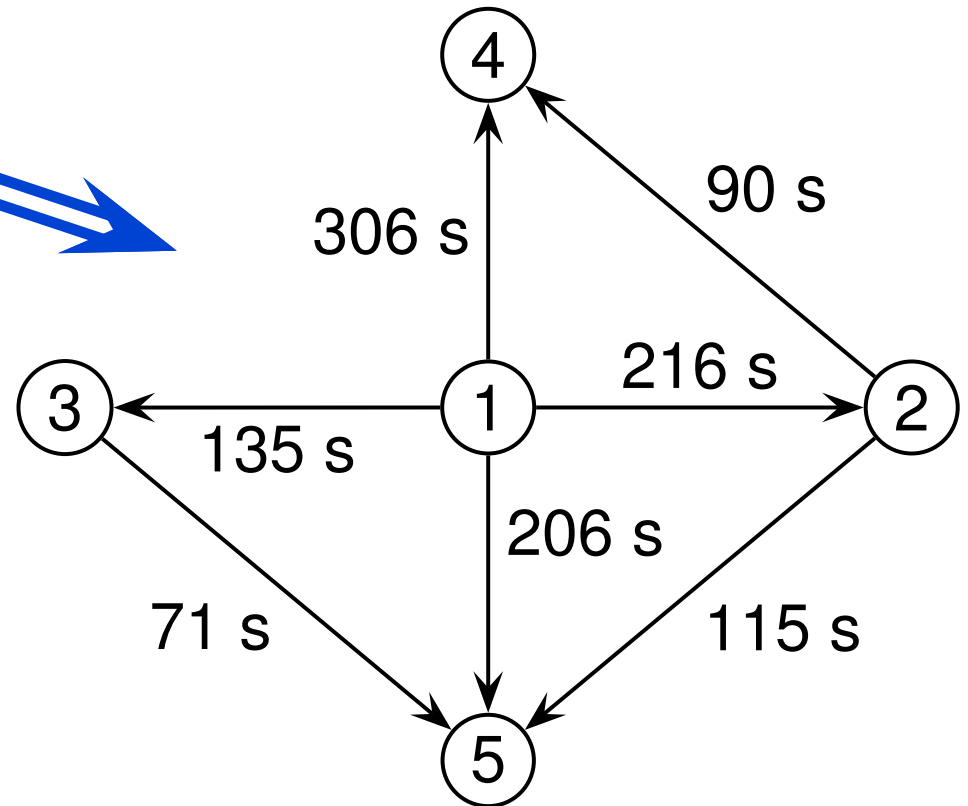
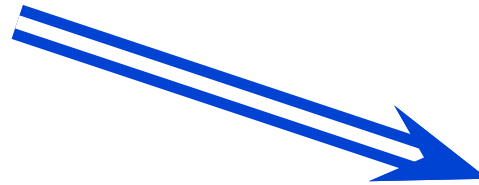
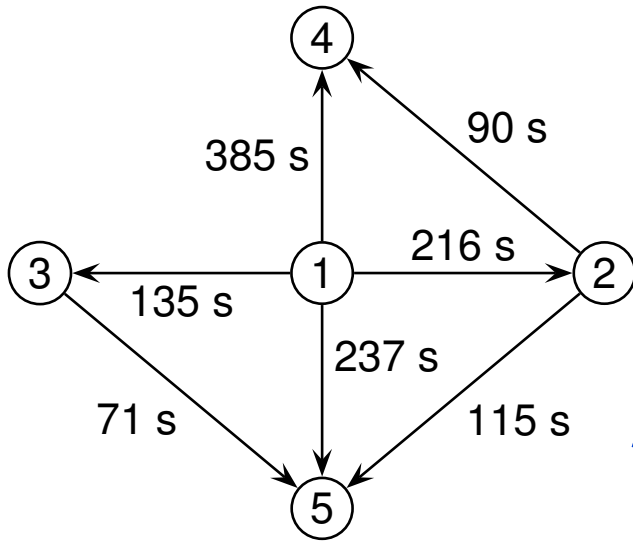
Shortest path computation



Shortest path computation



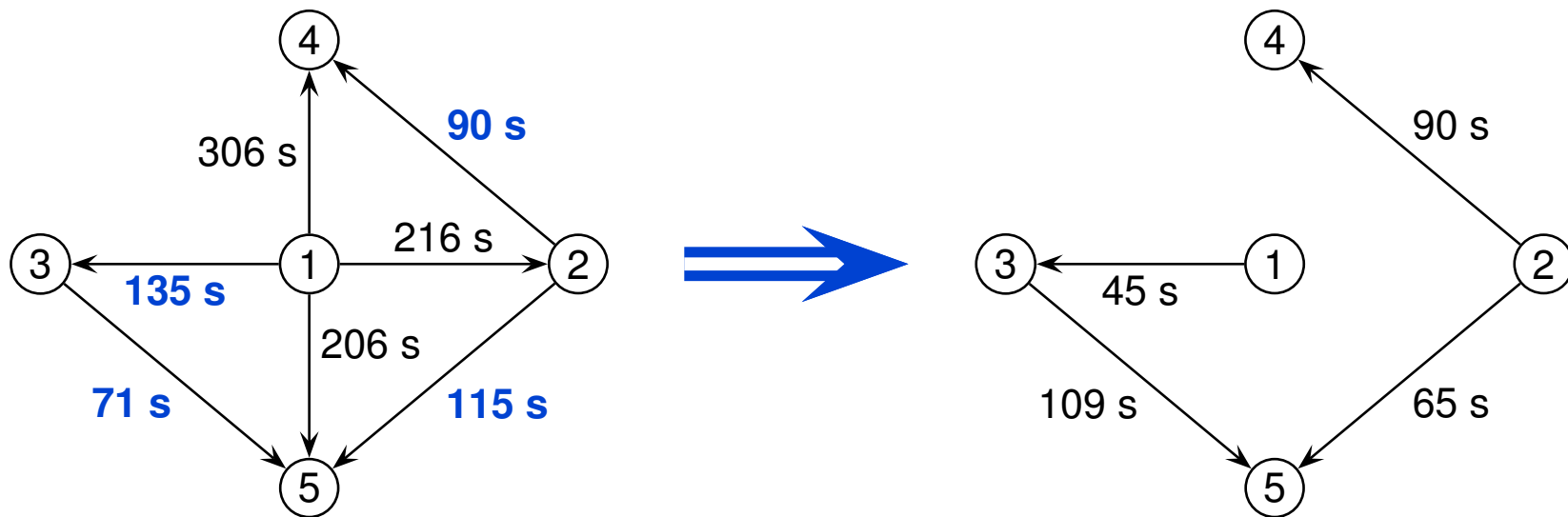
Shortest path computation



Resulting stability evaluation

Secondary delays computation

□ for a primary delay of 180 s

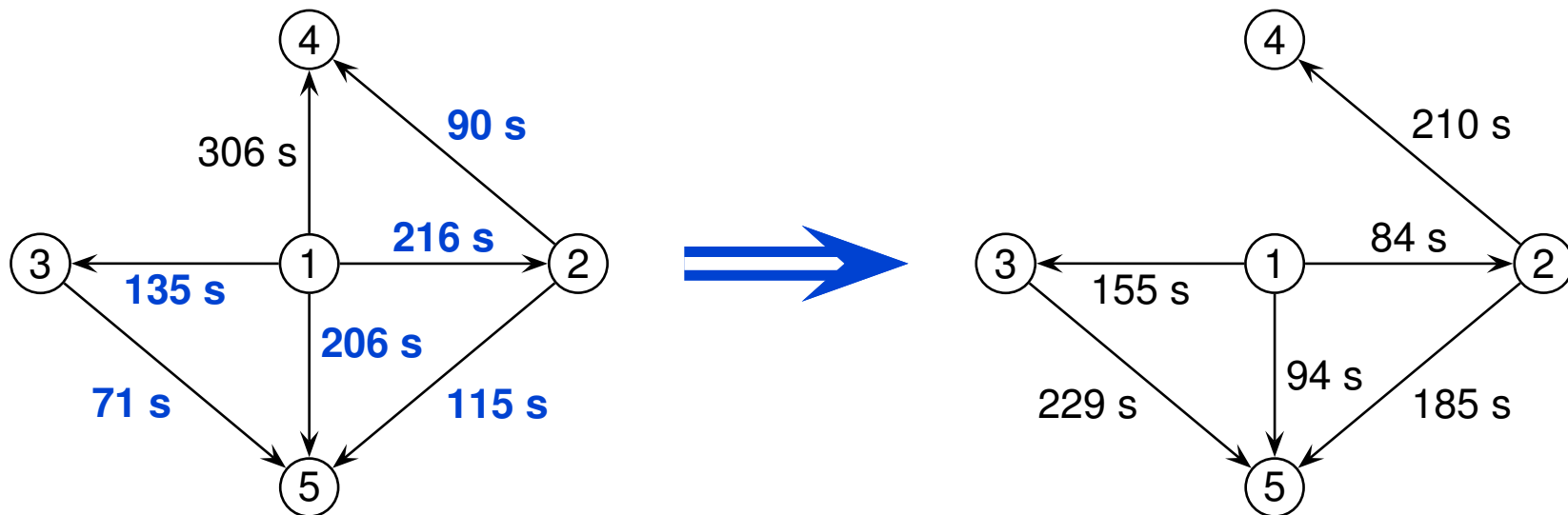


Total delay generated by train 1	:	45 s
Total delay generated by train 2	:	155 s
Total delay generated by train 3	:	109 s
Total delay generated by train 4 and 5	:	0 s
Stability evaluation =		309 s

Resulting stability evaluation

Secondary delays computation

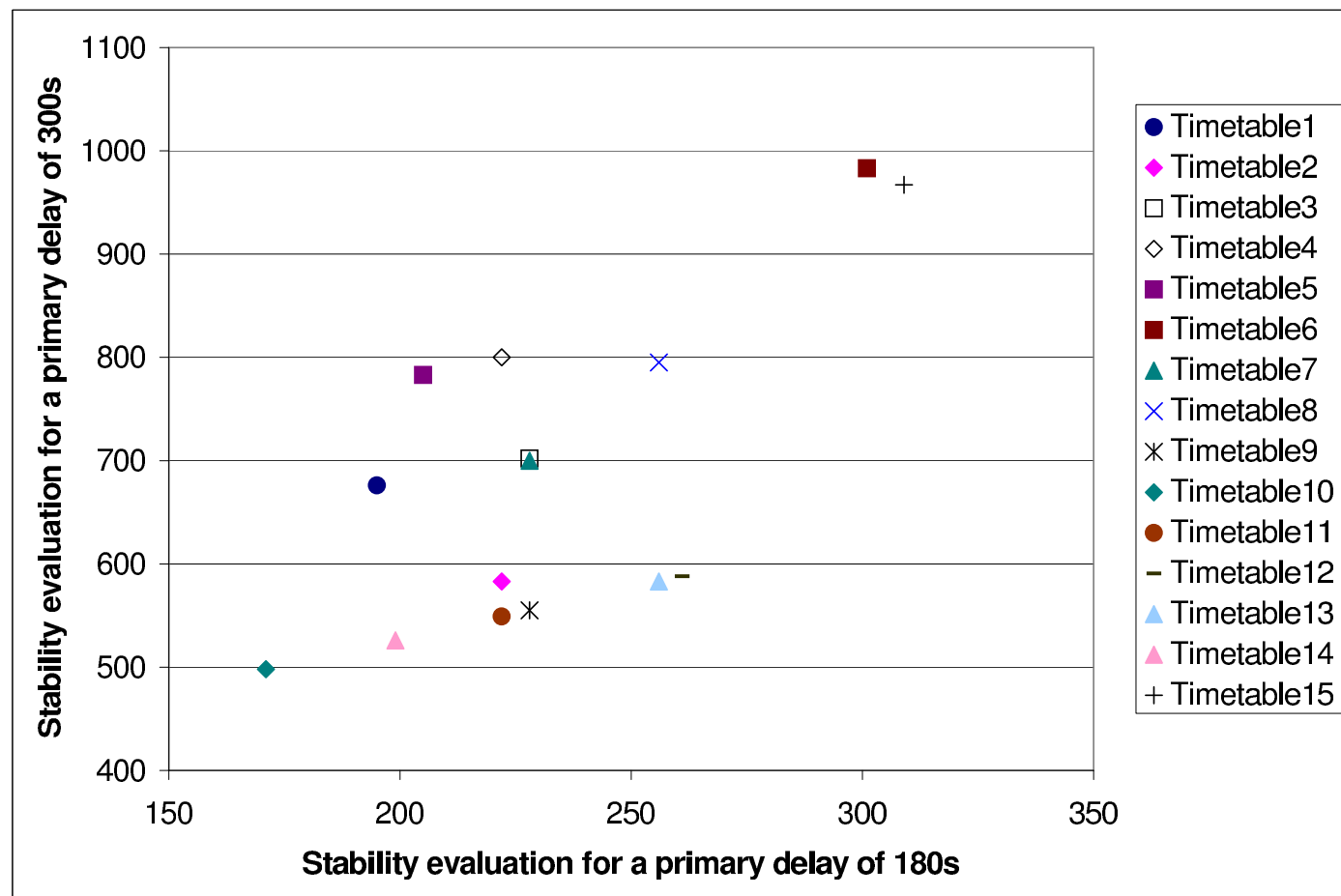
- ❑ for a primary delay of 180 s : 309 s
- ❑ for a primary delay of 300 s



Total delay generated by train 1	:	333 s
Total delay generated by train 2	:	395 s
Total delay generated by train 3	:	229 s
Total delay generated by train 4 and 5	:	0 s
Stability evaluation =		957 s

Comparison of the timetables

2 stability evaluation for each timetable



- ❑ Railroad infrastructure operation planning
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A new model for stability evaluation

- ❑ railroad timetable of junction or station
 - ❑ delay propagation method
 - ❑ using shortest path computation
- ⇒ integrated in a decision support system for railroad capacity evaluation

Future research works

- ❑ integratation of multi-criteria analysis
- ❑ stability optimization