

Optimization of Composite Structures by Estimation of Distribution Algorithms

Paris Research Center, October 5, 2004

Laurent Grosset

`grosset@emse.fr`

Advisors:

Raphael T. Haftka, Department of Mechanical and Aerospace Engineering, University of Florida

Rodolphe Le Riche, Département Mécanique et Matériaux, École Nationale Supérieure des Mines de Saint-Étienne

Outline

- Résumé des travaux (en français)

Outline

- Résumé des travaux (en français)
- Introduction to composite laminate optimization

Outline

- Résumé des travaux (en français)
- Introduction to composite laminate optimization
- Introduction to **Estimation of Distribution Algorithms** (EDA)

Outline

- Résumé des travaux (en français)
- Introduction to composite laminate optimization
- Introduction to **Estimation of Distribution Algorithms** (EDA)
 - Principles

Outline

- Résumé des travaux (en français)
- Introduction to composite laminate optimization
- Introduction to **Estimation of Distribution Algorithms** (EDA)
 - Principles
 - Importance of the statistical model

Outline

- Résumé des travaux (en français)
- Introduction to composite laminate optimization
- Introduction to **Estimation of Distribution Algorithms** (EDA)
 - Principles
 - Importance of the statistical model
- Application of a simple EDA to laminate optimization

Outline

- Résumé des travaux (en français)
- Introduction to composite laminate optimization
- Introduction to **Estimation of Distribution Algorithms** (EDA)
 - Principles
 - Importance of the statistical model
- Application of a simple EDA to laminate optimization
- Introduction of variable dependencies through auxiliary variables and the **Double-Distribution Optimization Algorithm**

Outline

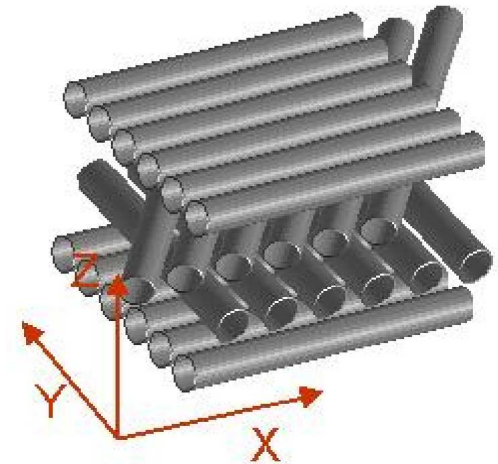
- Résumé des travaux (en français)
- Introduction to composite laminate optimization
- Introduction to **Estimation of Distribution Algorithms** (EDA)
 - Principles
 - Importance of the statistical model
- Application of a simple EDA to laminate optimization
- Introduction of variable dependencies through auxiliary variables and the **Double-Distribution Optimization Algorithm**
- Conclusions

Résumé des Travaux

Problématique:

Optimisation de stratifiés composites

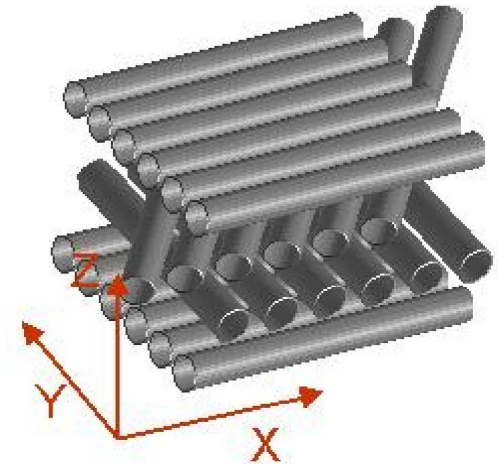
- Stratifié composite : empilement de couches de renforts (fibres) noyées dans la résine (polymère)



Problématique:

Optimisation de stratifiés composites

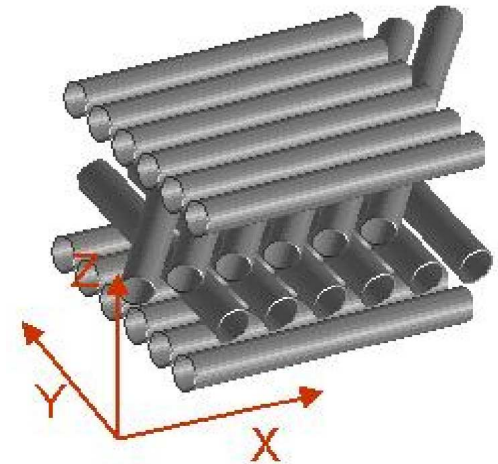
- Stratifié composite : empilement de couches de renforts (fibres) noyées dans la résine (polymère)
- Exemples : aéronautique (ex. Boeing 7E7), construction navale, équipements sportifs, . . .



Problématique:

Optimisation de stratifiés composites

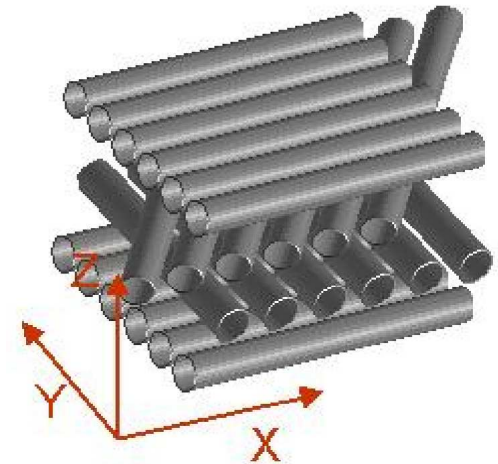
- Stratifié composite : empilement de couches de renforts (fibres) noyées dans la résine (polymère)
- Exemples : aéronautique (ex. Boeing 7E7), construction navale, équipements sportifs, . . .
- La réponse dépend de l'orientation des fibres



Problématique:

Optimisation de stratifiés composites

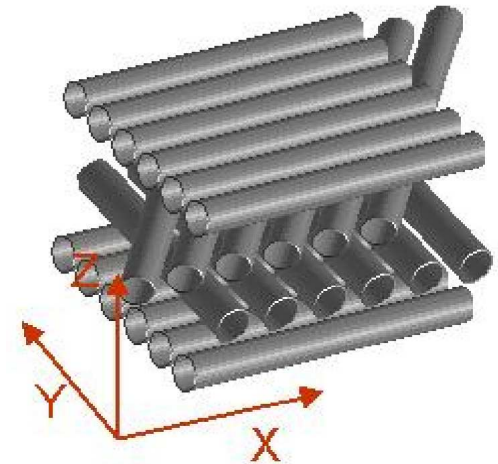
- Stratifié composite : empilement de couches de renforts (fibres) noyées dans la résine (polymère)
- Exemples : aéronautique (ex. Boeing 7E7), construction navale, équipements sportifs, ...
- La réponse dépend de l'orientation des fibres
- **But de l'optimisation** = déterminer l'orientation optimale de toutes les couches pour une application particulière :



Problématique:

Optimisation de stratifiés composites

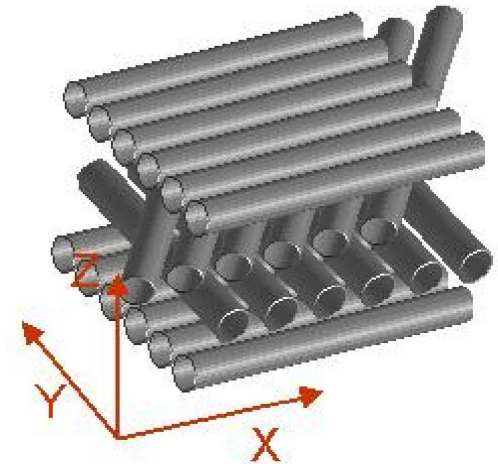
- Stratifié composite : empilement de couches de renforts (fibres) noyées dans la résine (polymère)
- Exemples : aéronautique (ex. Boeing 7E7), construction navale, équipements sportifs, ...
- La réponse dépend de l'orientation des fibres
- **But de l'optimisation** = déterminer l'orientation optimale de toutes les couches pour une application particulière :
 - maximiser la résistance d'un élément de structure d'un avion



Problématique:

Optimisation de stratifiés composites

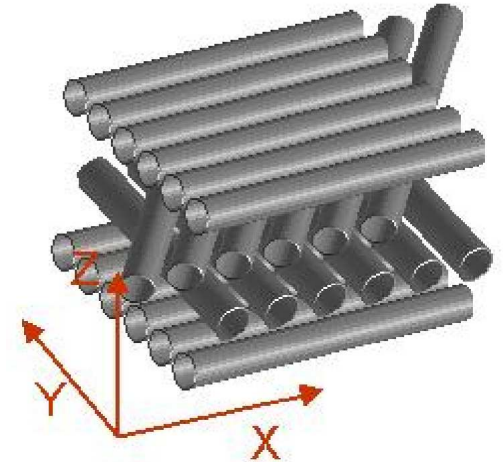
- Stratifié composite : empilement de couches de renforts (fibres) noyées dans la résine (polymère)
- Exemples : aéronautique (ex. Boeing 7E7), construction navale, équipements sportifs, ...
- La réponse dépend de l'orientation des fibres
- **But de l'optimisation** = déterminer l'orientation optimale de toutes les couches pour une application particulière :
 - maximiser la résistance d'un élément de structure d'un avion
 - minimiser le poids



Problématique:

Optimisation de stratifiés composites

- Stratifié composite : empilement de couches de renforts (fibres) noyées dans la résine (polymère)
- Exemples : aéronautique (ex. Boeing 7E7), construction navale, équipements sportifs, ...
- La réponse dépend de l'orientation des fibres
- **But de l'optimisation** = déterminer l'orientation optimale de toutes les couches pour une application particulière :
 - maximiser la résistance d'un élément de structure d'un avion
 - minimiser le poids
 - déterminer la séquence d'empilement de la coque d'une voiture de course de manière à minimiser les vibrations



État de l'art, objectifs de la thèse

- Méthodes traditionnelles basées sur les gradients mais problèmes **continus** uniquement et **recherche locale**

État de l'art, objectifs de la thèse

- Méthodes traditionnelles basées sur les gradients mais problèmes **continus** uniquement et **recherche locale**
- Optimisation stochastique pour globalité (algorithmes génétiques, années 90)

État de l'art, objectifs de la thèse

- Méthodes traditionnelles basées sur les gradients mais problèmes **continus** uniquement et **recherche locale**
- Optimisation stochastique pour globalité (algorithmes génétiques, années 90)
- La thèse fait suite à des travaux du groupe de Prof. Haftka:

État de l'art, objectifs de la thèse

- Méthodes traditionnelles basées sur les gradients mais problèmes **continus** uniquement et **recherche locale**
- Optimisation stochastique pour globalité (algorithmes génétiques, années 90)
- La thèse fait suite à des travaux du groupe de Prof. Haftka:
 - R. Le Riche : application d'algorithmes évolutionnaires à l'optimisation de structures composites (1994)

État de l'art, objectifs de la thèse

- Méthodes traditionnelles basées sur les gradients mais problèmes **continus** uniquement et **recherche locale**
- Optimisation stochastique pour globalité (algorithmes génétiques, années 90)
- La thèse fait suite à des travaux du groupe de Prof. Haftka:
 - R. Le Riche : application d'algorithmes évolutionnaires à l'optimisation de structures composites (1994)
 - B. Liu: optimisation globale de structures composites par algorithmes multi-niveaux (2001)

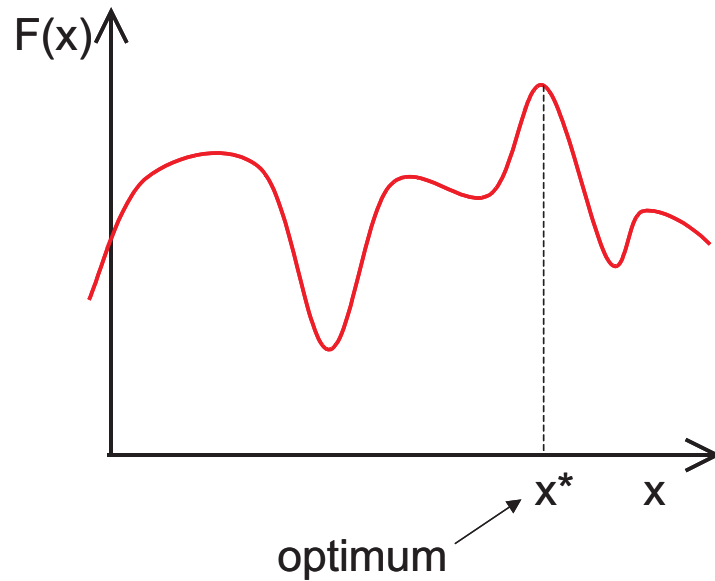
État de l'art, objectifs de la thèse

- Méthodes traditionnelles basées sur les gradients mais problèmes **continus** uniquement et **recherche locale**
- Optimisation stochastique pour globalité (algorithmes génétiques, années 90)
- La thèse fait suite à des travaux du groupe de Prof. Haftka:
 - R. Le Riche : application d'algorithmes évolutionnaires à l'optimisation de structures composites (1994)
 - B. Liu: optimisation globale de structures composites par algorithmes multi-niveaux (2001)

Objectifs de la thèse :

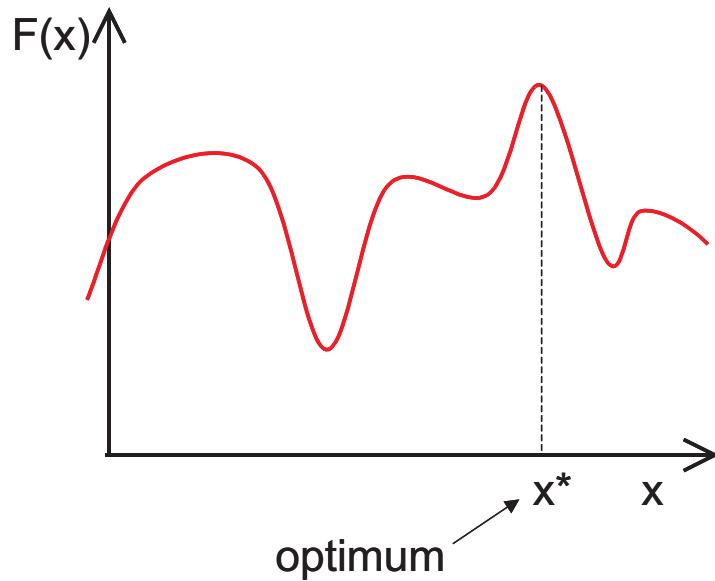
- Maturation des méthodes évolutionnaires depuis 20 ans (ES, EDA)
- Transférer ces nouvelles méthodes à l'optimisation de composites :
 - utilisation plus simple
 - méthodes plus efficaces

Algorithmes à estimation de distribution



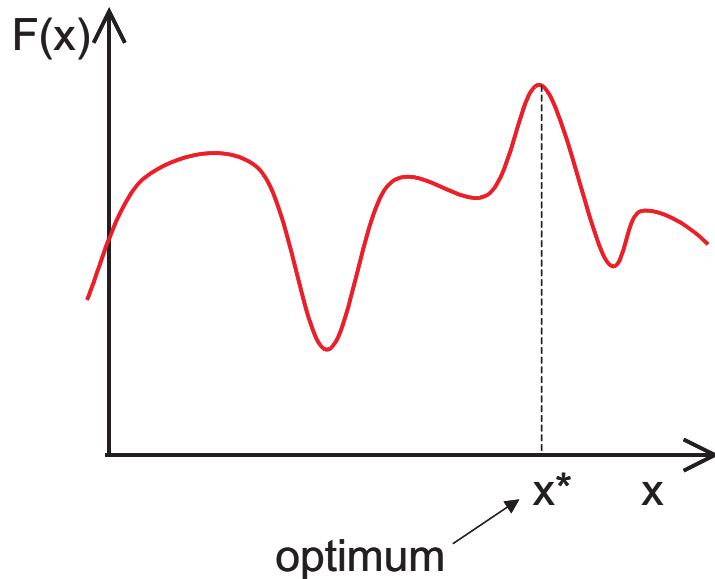
- But : trouver le point de plus élevé d'une "fonction coût" F sur un domaine \mathcal{D}

Algorithmes à estimation de distribution



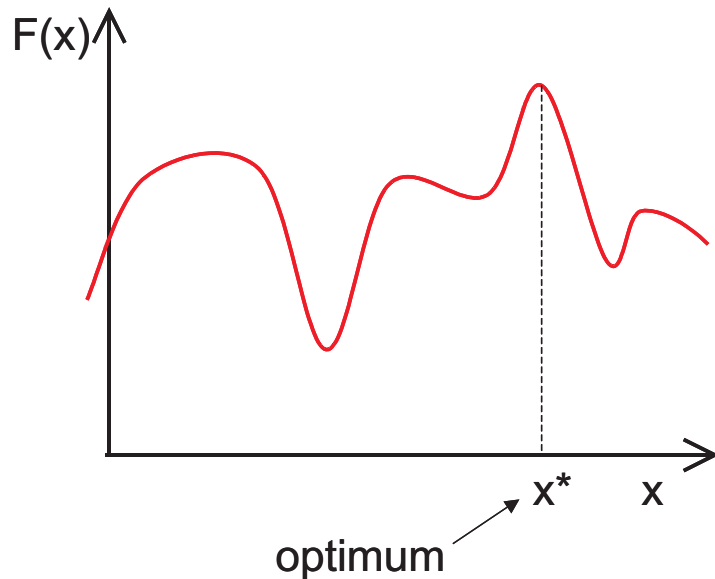
- But : trouver le point de plus élevé d'une "fonction coût" F sur un domaine \mathcal{D}
- Difficulté : on ne dispose que d'un budget limité de N évaluations de la fonction F (on ne peut pas calculer toutes les combinaisons pour choisir la meilleure!)

Algorithmes à estimation de distribution



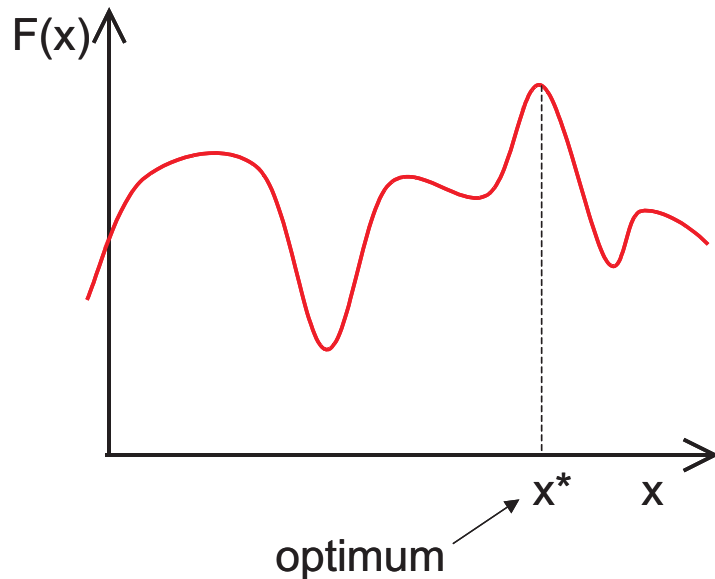
- But : trouver le point de plus élevé d'une "fonction coût" F sur un domaine \mathcal{D}
- Difficulté : on ne dispose que d'un budget limité de N évaluations de la fonction F (on ne peut pas calculer toutes les combinaisons pour choisir la meilleure!)
- On représente notre croyance que l'optimum est dans une région de \mathcal{D} par une densité de probabilité $p(\mathbf{x})$

Algorithmes à estimation de distribution



- But : trouver le point de plus élevé d'une "fonction coût" F sur un domaine \mathcal{D}
- Difficulté : on ne dispose que d'un budget limité de N évaluations de la fonction F (on ne peut pas calculer toutes les combinaisons pour choisir la meilleure!)
- On représente notre croyance que l'optimum est dans une région de \mathcal{D} par une densité de probabilité $p(\mathbf{x})$
- $p(\mathbf{x})$ est utilisée pour créer de nouveaux points

Algorithmes à estimation de distribution



- But : trouver le point de plus élevé d'une "fonction coût" F sur un domaine \mathcal{D}
- Difficulté : on ne dispose que d'un budget limité de N évaluations de la fonction F (on ne peut pas calculer toutes les combinaisons pour choisir la meilleure!)
- On représente notre croyance que l'optimum est dans une région de \mathcal{D} par une densité de probabilité $p(\mathbf{x})$
- $p(\mathbf{x})$ est utilisée pour créer de nouveaux points
- les nouveaux points sont utilisés pour mettre à jour $p(\mathbf{x})$

Enjeux, améliorations proposées et résultats

Éléments critiques de l'algorithme

- Adaptation aux problèmes de composites (alphabet non binaire, nombre de variables réduit, évaluations coûteuses)

Enjeux, améliorations proposées et résultats

Éléments critiques de l'algorithme

- Adaptation aux problèmes de composites (alphabet non binaire, nombre de variables réduit, évaluations coûteuses)
- Représentation de la distribution $p(\mathbf{x})$: mauvais choix de la forme de $p(\mathbf{x})$ \Rightarrow gaspillage d'évaluations dans des régions médiocres

Enjeux, améliorations proposées et résultats

Éléments critiques de l'algorithme

- Adaptation aux problèmes de composites (alphabet non binaire, nombre de variables réduit, évaluations coûteuses)
- Représentation de la distribution $p(\mathbf{x})$: mauvais choix de la forme de $p(\mathbf{x})$ \Rightarrow gaspillage d'évaluations dans des régions médiocres

Solutions proposées

Enjeux, améliorations proposées et résultats

Éléments critiques de l'algorithme

- Adaptation aux problèmes de composites (alphabet non binaire, nombre de variables réduit, évaluations coûteuses)
- Représentation de la distribution $p(\mathbf{x})$: mauvais choix de la forme de $p(\mathbf{x})$ \Rightarrow gaspillage d'évaluations dans des régions médiocres

Solutions proposées

- Amélioration du modèle statistique par injection de connaissance sur la structure du problème

Enjeux, améliorations proposées et résultats

Éléments critiques de l'algorithme

- Adaptation aux problèmes de composites (alphabet non binaire, nombre de variables réduit, évaluations coûteuses)
- Représentation de la distribution $p(\mathbf{x})$: mauvais choix de la forme de $p(\mathbf{x})$ \Rightarrow gaspillage d'évaluations dans des régions médiocres

Solutions proposées

- Amélioration du modèle statistique par injection de connaissance sur la structure du problème
- Mécanismes de contrôle de l'exploration

Enjeux, améliorations proposées et résultats

Éléments critiques de l'algorithme

- Adaptation aux problèmes de composites (alphabet non binaire, nombre de variables réduit, évaluations coûteuses)
- Représentation de la distribution $p(\mathbf{x})$: mauvais choix de la forme de $p(\mathbf{x})$ \Rightarrow gaspillage d'évaluations dans des régions médiocres

Solutions proposées

- Amélioration du modèle statistique par injection de connaissance sur la structure du problème
- Mécanismes de contrôle de l'exploration

Résultats

Enjeux, améliorations proposées et résultats

Éléments critiques de l'algorithme

- Adaptation aux problèmes de composites (alphabet non binaire, nombre de variables réduit, évaluations coûteuses)
- Représentation de la distribution $p(\mathbf{x})$: mauvais choix de la forme de $p(\mathbf{x})$ \Rightarrow gaspillage d'évaluations dans des régions médiocres

Solutions proposées

- Amélioration du modèle statistique par injection de connaissance sur la structure du problème
- Mécanismes de contrôle de l'exploration

Résultats

- Les EDAs sont facilement applicables à l'optimisation de stratifiés

Enjeux, améliorations proposées et résultats

Éléments critiques de l'algorithme

- Adaptation aux problèmes de composites (alphabet non binaire, nombre de variables réduit, évaluations coûteuses)
- Représentation de la distribution $p(\mathbf{x})$: mauvais choix de la forme de $p(\mathbf{x})$ \Rightarrow gaspillage d'évaluations dans des régions médiocres

Solutions proposées

- Amélioration du modèle statistique par injection de connaissance sur la structure du problème
- Mécanismes de contrôle de l'exploration

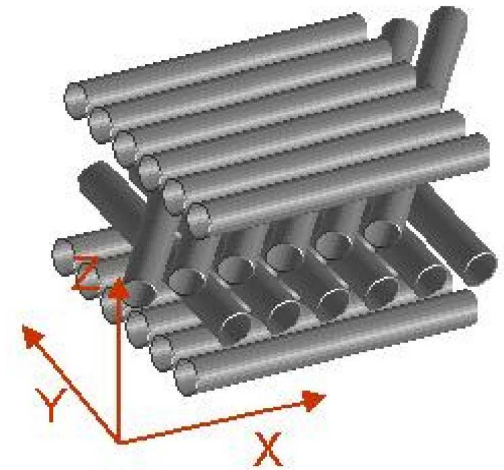
Résultats

- Les EDAs sont facilement applicables à l'optimisation de stratifiés
- La stratégie proposée conduit à une amélioration de l'efficacité sur les problèmes testés

Introduction to Composite Laminate Optimization

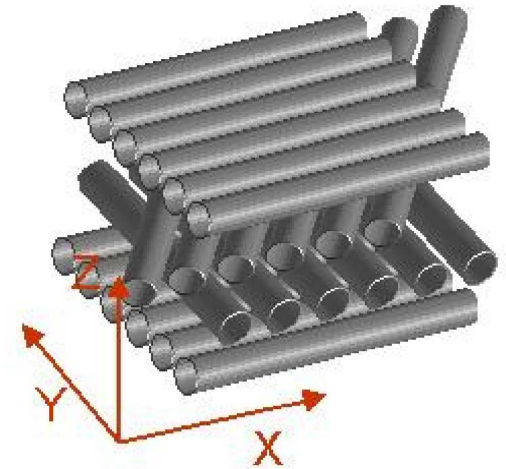
Composite Laminates

- Composite laminate: structure made of layers (plies) of fibrous material embedded in a matrix



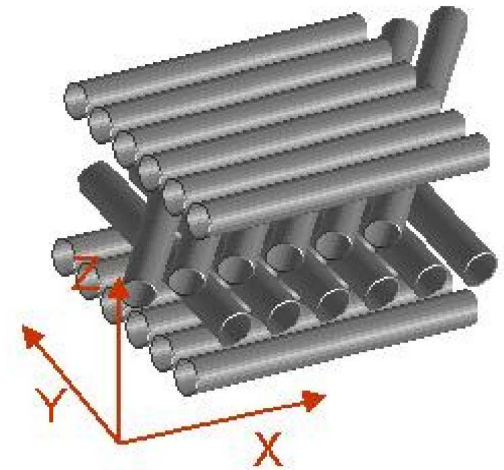
Composite Laminates

- Composite laminate: structure made of layers (plies) of fibrous material embedded in a matrix
- The fibers (graphite, glass, . . .) provide the mechanical properties, the matrix (polymer) hold the fibers together



Composite Laminates

- Composite laminate: structure made of layers (plies) of fibrous material embedded in a matrix
- The fibers (graphite, glass, . . .) provide the mechanical properties, the matrix (polymer) hold the fibers together
- Applications:
 - aerospace industry (rudder, wing box, flying control surfaces, helicopter blades, . . .)
 - sporting goods (skis, sailing, tennis)
 - wind turbines
 - motorsports and performance cars



Optimization of Composite Laminates

- Each layer is orthotropic: its mechanical properties depend on the direction

Optimization of Composite Laminates

- Each layer is orthotropic: its mechanical properties depend on the direction
- Overall response F (stiffness, strength, natural frequency, buckling load, . . .) of the whole laminate depends on the stacking sequence $[\theta_1, \theta_2, \dots, \theta_n]$:

$$F = F(\theta_1, \theta_2, \dots, \theta_n)$$

Optimization of Composite Laminates

- Each layer is orthotropic: its mechanical properties depend on the direction
- Overall response F (stiffness, strength, natural frequency, buckling load, ...) of the whole laminate depends on the stacking sequence $[\theta_1, \theta_2, \dots, \theta_n]$:

$$F = F(\theta_1, \theta_2, \dots, \theta_n)$$

- Goal of the optimization: maximize F

Optimization of Composite Laminates

- Each layer is orthotropic: its mechanical properties depend on the direction
- Overall response F (stiffness, strength, natural frequency, buckling load, ...) of the whole laminate depends on the stacking sequence $[\theta_1, \theta_2, \dots, \theta_n]$:

$$F = F(\theta_1, \theta_2, \dots, \theta_n)$$

- Goal of the optimization: maximize F
- Difficulty:

Optimization of Composite Laminates

- Each layer is orthotropic: its mechanical properties depend on the direction
- Overall response F (stiffness, strength, natural frequency, buckling load, ...) of the whole laminate depends on the stacking sequence $[\theta_1, \theta_2, \dots, \theta_n]$:

$$F = F(\theta_1, \theta_2, \dots, \theta_n)$$

- Goal of the optimization: maximize F
- Difficulty:
 - θ_k discrete (e.g. $\theta_k \in \{0^\circ, 45^\circ, 90^\circ\}$) \Rightarrow **combinatorial problems**

Optimization of Composite Laminates

- Each layer is orthotropic: its mechanical properties depend on the direction
- Overall response F (stiffness, strength, natural frequency, buckling load, ...) of the whole laminate depends on the stacking sequence $[\theta_1, \theta_2, \dots, \theta_n]$:

$$F = F(\theta_1, \theta_2, \dots, \theta_n)$$

- Goal of the optimization: maximize F
- Difficulty:
 - θ_k discrete (e.g. $\theta_k \in \{0^\circ, 45^\circ, 90^\circ\}$) \Rightarrow **combinatorial problems**
 - F non-convex in general \Rightarrow **many local optima**

Optimization of Composite Laminates

- Each layer is orthotropic: its mechanical properties depend on the direction
- Overall response F (stiffness, strength, natural frequency, buckling load, ...) of the whole laminate depends on the stacking sequence $[\theta_1, \theta_2, \dots, \theta_n]$:

$$F = F(\theta_1, \theta_2, \dots, \theta_n)$$

- Goal of the optimization: maximize F
- Difficulty:
 - θ_k discrete (e.g. $\theta_k \in \{0^\circ, 45^\circ, 90^\circ\}$) \Rightarrow **combinatorial problems**
 - F non-convex in general \Rightarrow **many local optima**
- \Rightarrow Require specific optimization methods

Laminate Optimization Methods

- **Gradient-based continuous optimization** using ply thicknesses as design variables (Schmit and Farshi, 1977) or a penalty approach to force discreteness of the ply angles (Shin et al., 1990)

Laminate Optimization Methods

- **Gradient-based continuous optimization** using ply thicknesses as design variables (Schmit and Farshi, 1977) or a penalty approach to force discreteness of the ply angles (Shin et al., 1990)
- ⇒ can use well-established methods, but no guaranty to find the global optimum

Laminate Optimization Methods

- **Gradient-based continuous optimization** using ply thicknesses as design variables (Schmit and Farshi, 1977) or a penalty approach to force discreteness of the ply angles (Shin et al., 1990)
 - ⇒ can use well-established methods, but no guaranty to find the global optimum
- **Stochastic optimization: Genetic Algorithms** (Hajela and Lin, 1992; Le Riche and Haftka, 1993)

Laminate Optimization Methods

- **Gradient-based continuous optimization** using ply thicknesses as design variables (Schmit and Farshi, 1977) or a penalty approach to force discreteness of the ply angles (Shin et al., 1990)
 - ⇒ can use well-established methods, but no guaranty to find the global optimum
- **Stochastic optimization: Genetic Algorithms** (Hajela and Lin, 1992; Le Riche and Haftka, 1993)
 - ⇒ stochastic search + discrete variables: can solve the problem directly, but

Laminate Optimization Methods

- **Gradient-based continuous optimization** using ply thicknesses as design variables (Schmit and Farshi, 1977) or a penalty approach to force discreteness of the ply angles (Shin et al., 1990)
 - ⇒ can use well-established methods, but no guaranty to find the global optimum
- **Stochastic optimization: Genetic Algorithms** (Hajela and Lin, 1992; Le Riche and Haftka, 1993)
 - ⇒ stochastic search + discrete variables: can solve the problem directly, but
 - can be **difficult to use** (many problem-dependent parameters to tune),

Laminate Optimization Methods

- **Gradient-based continuous optimization** using ply thicknesses as design variables (Schmit and Farshi, 1977) or a penalty approach to force discreteness of the ply angles (Shin et al., 1990)
 - ⇒ can use well-established methods, but no guaranty to find the global optimum
- **Stochastic optimization: Genetic Algorithms** (Hajela and Lin, 1992; Le Riche and Haftka, 1993)
 - ⇒ stochastic search + discrete variables: can solve the problem directly, but
 - can be **difficult to use** (many problem-dependent parameters to tune),
 - and **computationally expensive**

Purpose of this work

Our goal is to

1. investigate the application of a new class of algorithms called “**Estimation of Distribution Algorithms**” (EDAs) to the field of laminate optimization;

Purpose of this work

Our goal is to

1. investigate the application of a new class of algorithms called “**Estimation of Distribution Algorithms**” (EDAs) to the field of laminate optimization;
2. propose improvements to EDAs in the context of laminate optimization:
use **physics-based knowledge** to improve efficiency

Purpose of this work

Our goal is to

1. investigate the application of a new class of algorithms called “**Estimation of Distribution Algorithms**” (EDAs) to the field of laminate optimization;
2. propose improvements to EDAs in the context of laminate optimization:
use **physics-based knowledge** to improve efficiency
3. study the general behavior of EDAs and propose improvements to EDAs that can be used for other fields.

Introduction to Estimation of Distribution Algorithms

Recall: Genetic Algorithms (GA)

- Inspiration: Darwin's theory of Evolution (“survival of the fittest”)

Recall: Genetic Algorithms (GA)

- Inspiration: Darwin's theory of Evolution (“survival of the fittest”)

A species can adapt to an environment because those individuals that possess features that give them a competitive advantage over other individuals are more likely to have offspring, and therefore to pass on their advantageous traits to the next generation.

Recall: Genetic Algorithms (GA)

- Inspiration: Darwin's theory of Evolution (“survival of the fittest”)

A species can adapt to an environment because those individuals that possess features that give them a competitive advantage over other individuals are more likely to have offspring, and therefore to pass on their advantageous traits to the next generation.

- Application to function optimization:

Idea: **let a population of candidate solutions evolve to adapt to a task to perform**

Recall: Genetic Algorithms (GA)

- Inspiration: Darwin's theory of Evolution (“survival of the fittest”)

A species can adapt to an environment because those individuals that possess features that give them a competitive advantage over other individuals are more likely to have offspring, and therefore to pass on their advantageous traits to the next generation.

- Application to function optimization:

Idea: **let a population of candidate solutions evolve to adapt to a task to perform**

- Environment → Function $F(\mathbf{x})$ to maximize (“fitness”)

Recall: Genetic Algorithms (GA)

- Inspiration: Darwin's theory of Evolution (“survival of the fittest”)

A species can adapt to an environment because those individuals that possess features that give them a competitive advantage over other individuals are more likely to have offspring, and therefore to pass on their advantageous traits to the next generation.

- Application to function optimization:

Idea: **let a population of candidate solutions evolve to adapt to a task to perform**

- Environment \rightarrow Function $F(\mathbf{x})$ to maximize (“fitness”)
- Population of individuals \rightarrow population of points $\mathbf{x}_i, i = 1, \dots, \lambda$

Recall: Genetic Algorithms (GA)

- Inspiration: Darwin's theory of Evolution (“survival of the fittest”)

A species can adapt to an environment because those individuals that possess features that give them a competitive advantage over other individuals are more likely to have offspring, and therefore to pass on their advantageous traits to the next generation.

- Application to function optimization:

Idea: **let a population of candidate solutions evolve to adapt to a task to perform**

- Environment \rightarrow Function $F(\mathbf{x})$ to maximize (“fitness”)
- Population of individuals \rightarrow population of points $\mathbf{x}_i, i = 1, \dots, \lambda$
- Natural selection \rightarrow Selection based on F

Recall: Genetic Algorithms (GA)

- Inspiration: Darwin's theory of Evolution (“survival of the fittest”)

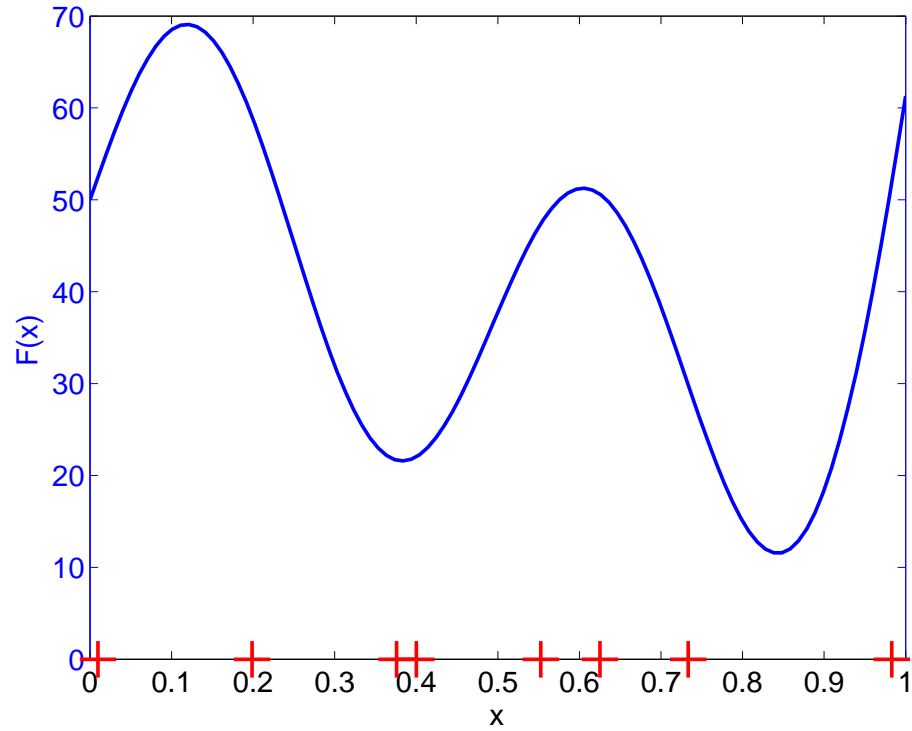
A species can adapt to an environment because those individuals that possess features that give them a competitive advantage over other individuals are more likely to have offspring, and therefore to pass on their advantageous traits to the next generation.

- Application to function optimization:

Idea: **let a population of candidate solutions evolve to adapt to a task to perform**

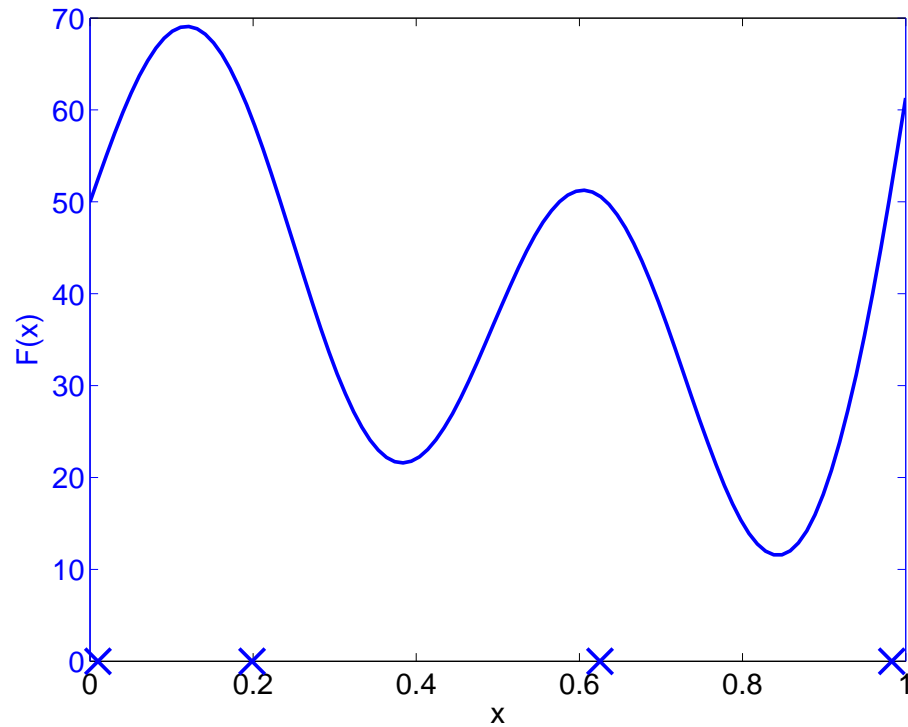
- Environment → Function $F(\mathbf{x})$ to maximize (“fitness”)
- Population of individuals → population of points $\mathbf{x}_i, i = 1, \dots, \lambda$
- Natural selection → Selection based on F
- Reproduction → recombination (crossover) and perturbation (mutation) operators

GA Mechanism



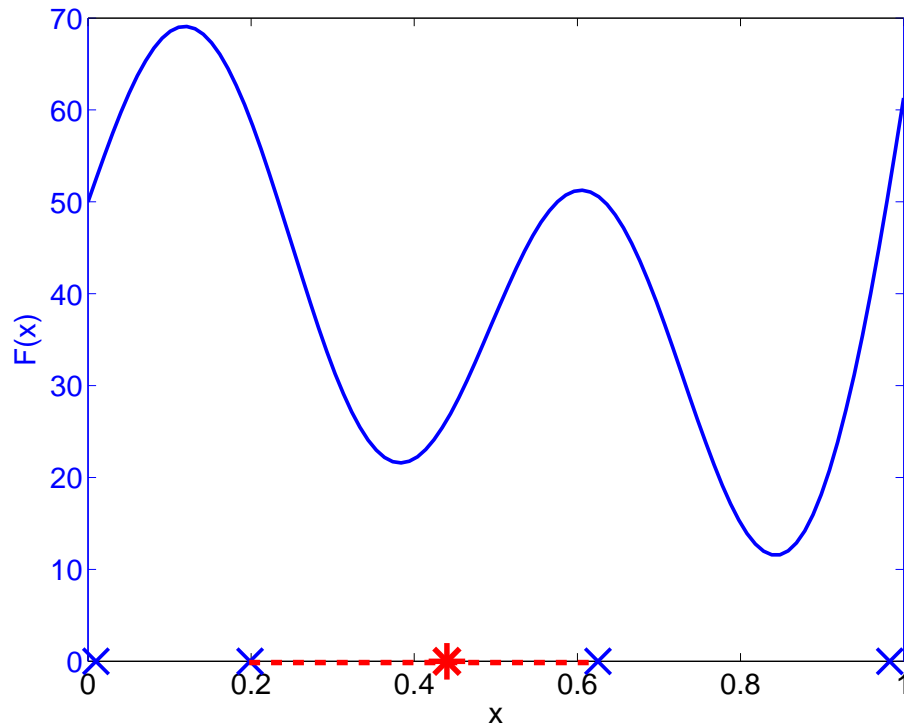
● Initial population: uniform

GA Mechanism



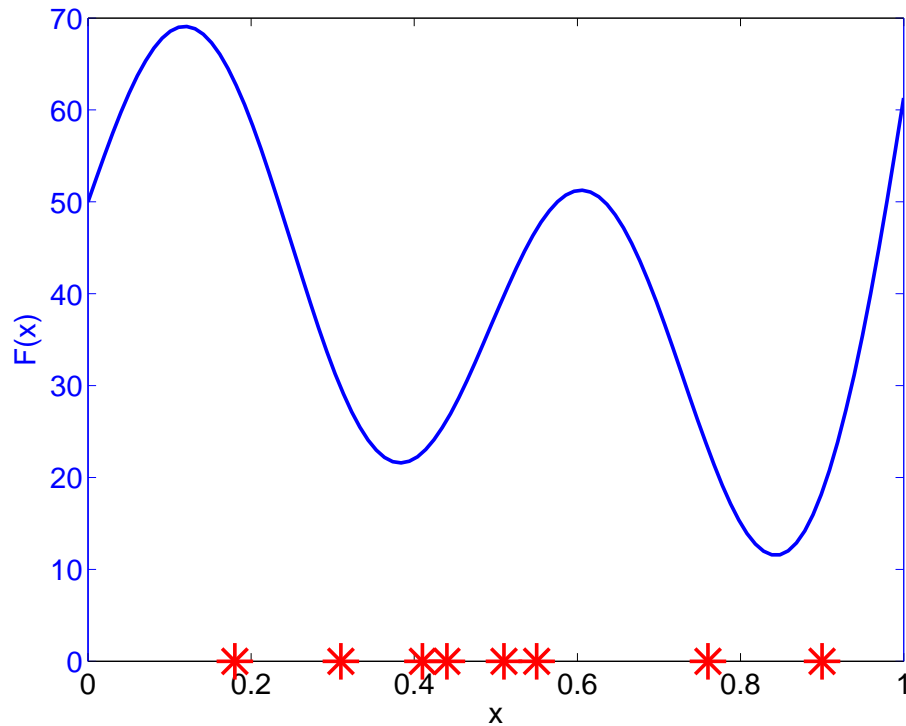
- Initial population: uniform
- Points obtained by selection ➡ parents

GA Mechanism



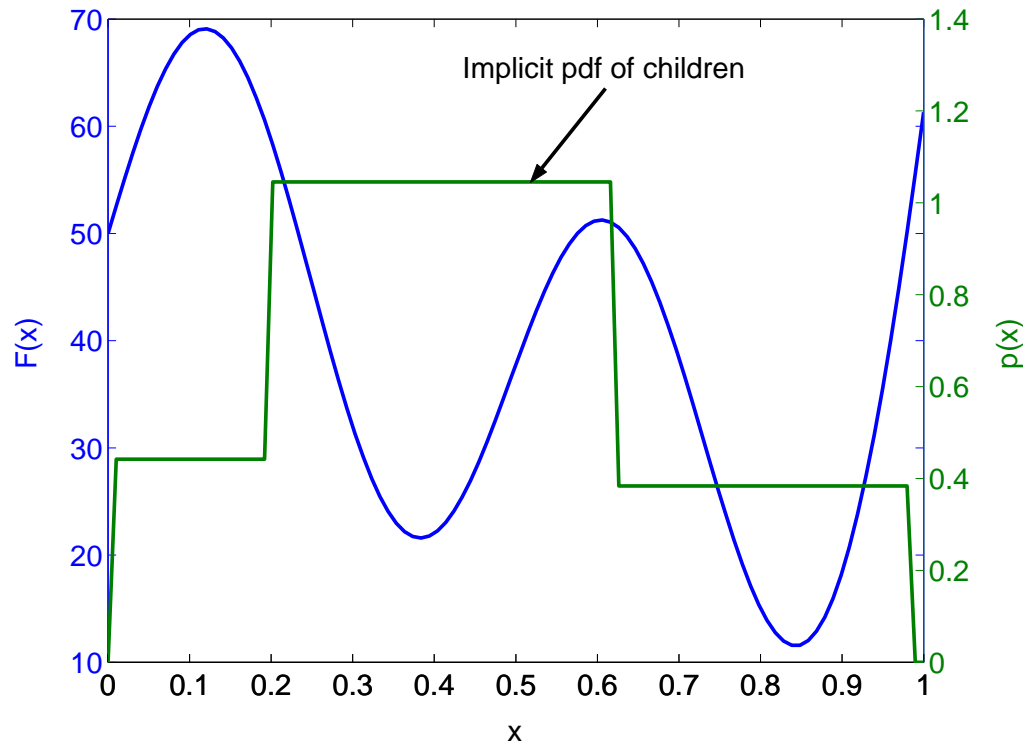
- Initial population: uniform
- Points obtained by selection \Rightarrow parents
- Creation of new points by recombination (e.g. weighted average in \mathbb{R}^n) \Rightarrow children

GA Mechanism



- Initial population: uniform
- Points obtained by selection \Rightarrow parents
- Creation of new points by recombination (e.g. weighted average in \mathbb{R}^n) \Rightarrow children
- Resulting new population

GA Mechanism



- Initial population: uniform
- Points obtained by selection \Rightarrow parents
- Creation of new points by recombination (e.g. weighted average in \mathbb{R}^n) \Rightarrow children
- Resulting new population

fitness function F	} \Rightarrow implicit probability distribution $p(\mathbf{x})$ over the design space
+ selection procedure	
+ variation operators	

Formalization of GAs \Rightarrow Estimation of Distribution Algorithms

- Goal: control the way the search distribution $p(\mathbf{x})$ is constructed so that it learns information about “promising regions”

Formalization of GAs \Rightarrow Estimation of Distribution Algorithms

- Goal: control the way the search distribution $p(\mathbf{x})$ is constructed so that it learns information about “promising regions”

Principle: express **explicitly** $p(\mathbf{x})$ and use it to create new points in high-fitness areas

Formalization of GAs \Rightarrow Estimation of Distribution Algorithms

- Goal: control the way the search distribution $p(\mathbf{x})$ is constructed so that it learns information about “promising regions”

Principle: express **explicitly** $p(\mathbf{x})$ and use it to create new points in high-fitness areas

- Potential advantages:

Formalization of GAs \Rightarrow Estimation of Distribution Algorithms

- Goal: control the way the search distribution $p(\mathbf{x})$ is constructed so that it learns information about “promising regions”

Principle: express **explicitly** $p(\mathbf{x})$ and use it to create new points in high-fitness areas

- Potential advantages:
 - Better understanding of the algorithm (based on statistical principles, not nature imitation)
 - \Rightarrow improve efficiency

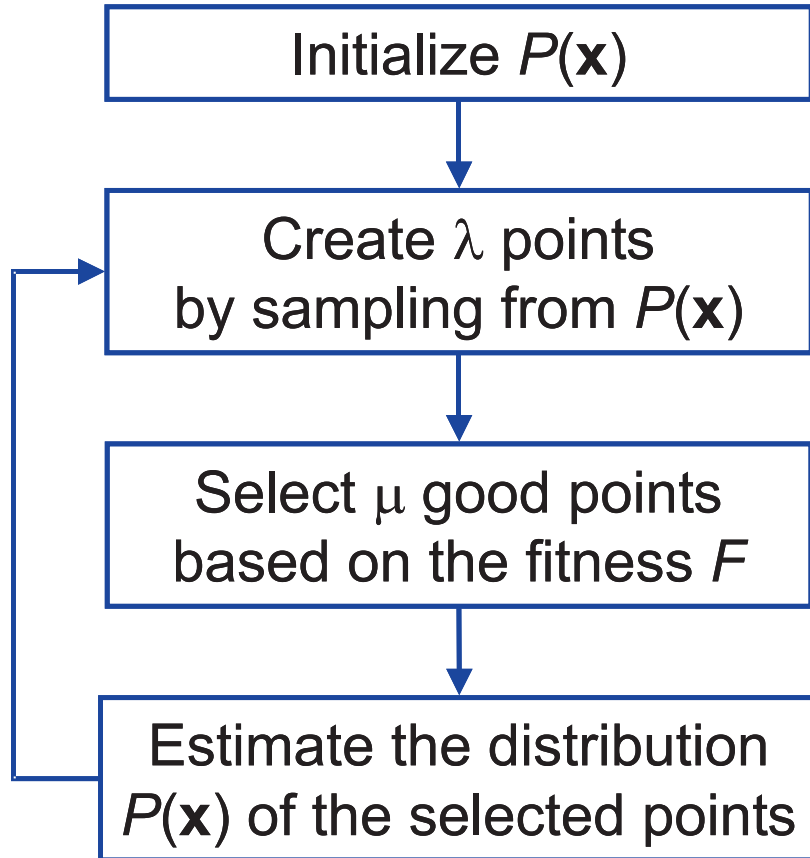
Formalization of GAs \Rightarrow Estimation of Distribution Algorithms

- Goal: control the way the search distribution $p(\mathbf{x})$ is constructed so that it learns information about “promising regions”

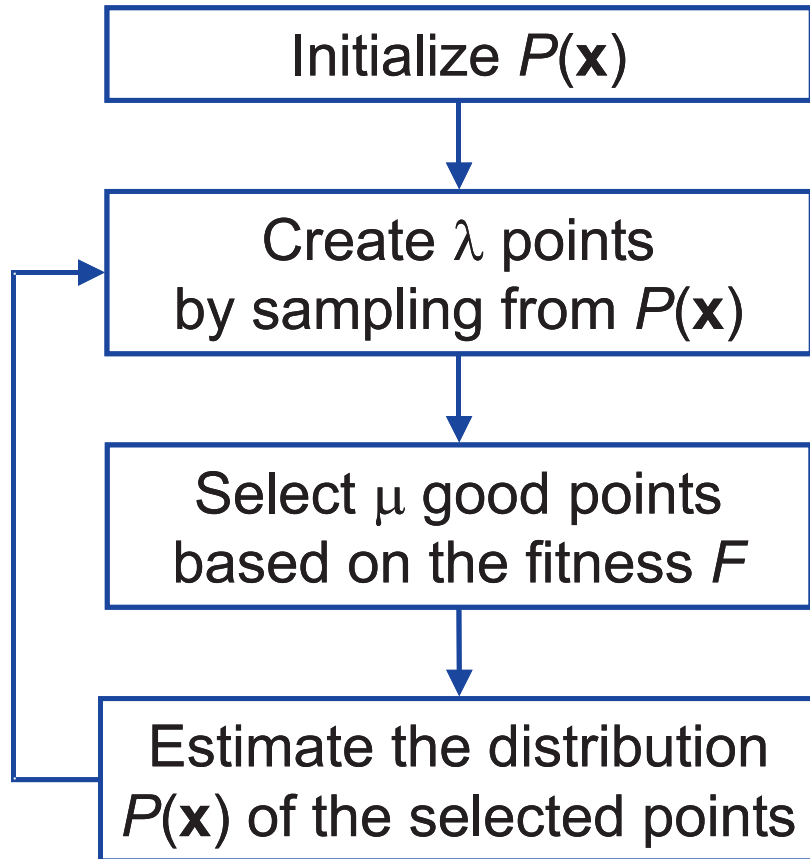
Principle: express **explicitly** $p(\mathbf{x})$ and use it to create new points in high-fitness areas

- Potential advantages:
 - Better understanding of the algorithm (based on statistical principles, not nature imitation)
 - \Rightarrow improve efficiency
 - Potentially fewer parameters (avoid many ad hoc operators)
 - \Rightarrow algorithm easier to use

The Estimation of Distribution Algorithm (EDA)

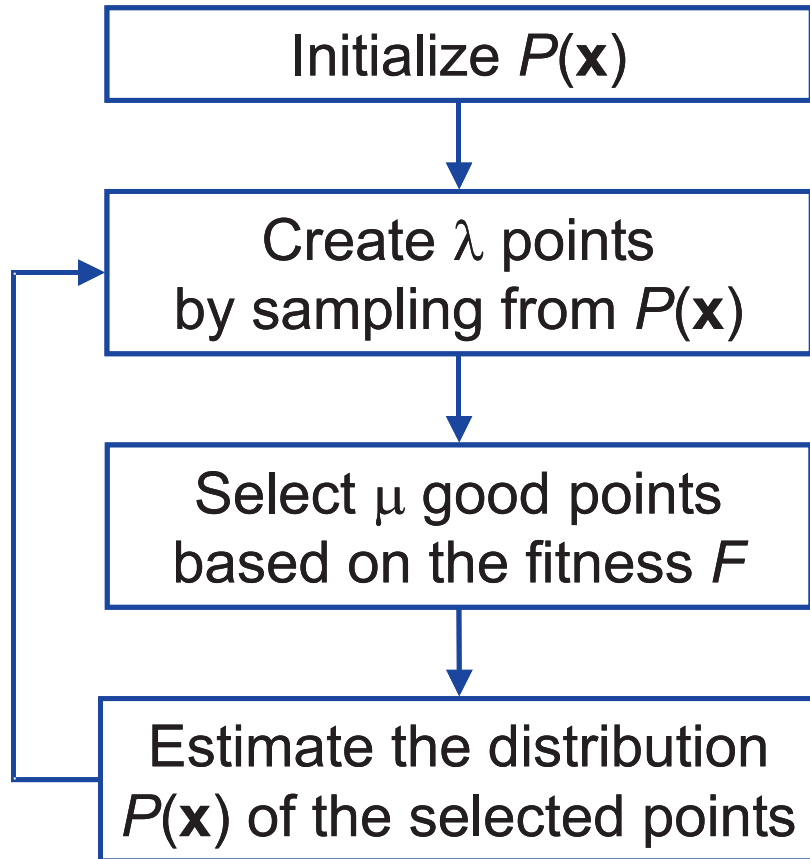


The Estimation of Distribution Algorithm (EDA)



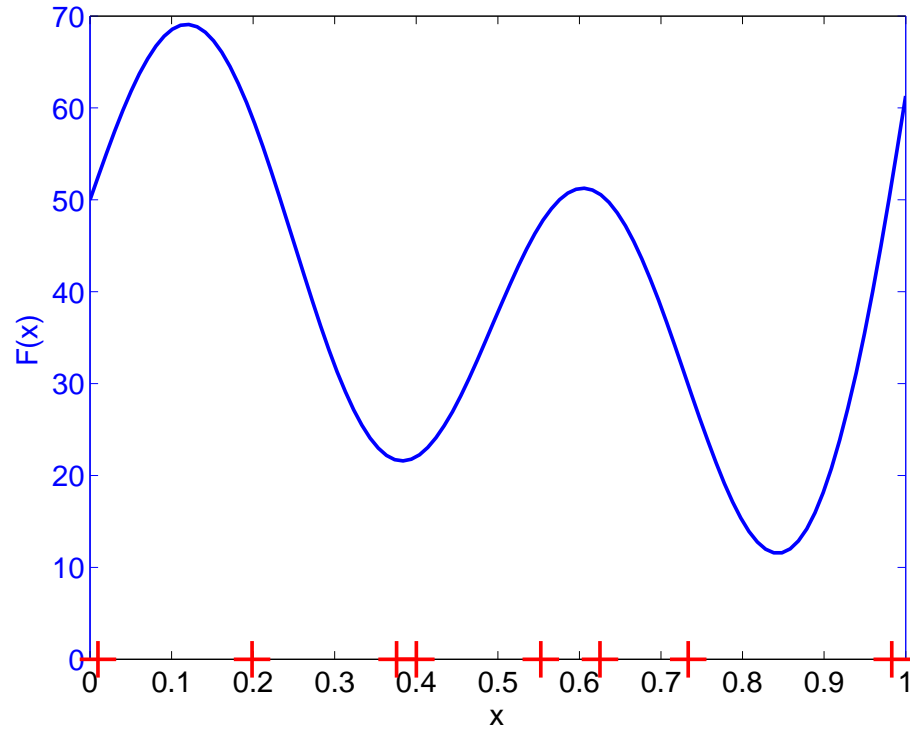
1. Use created points to infer statistical information about good regions $\Rightarrow p(\mathbf{x})$

The Estimation of Distribution Algorithm (EDA)



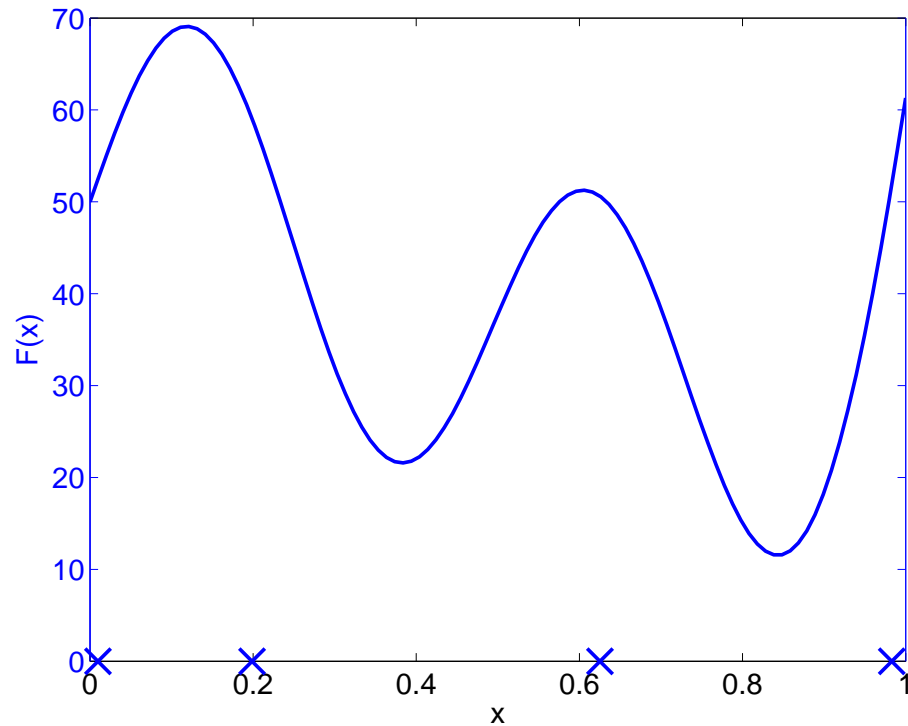
1. Use created points to infer statistical information about good regions $\Rightarrow p(\mathbf{x})$
2. Use $p(\mathbf{x})$ to create new points in promising regions

Estimation of Distribution Algorithm: Illustration



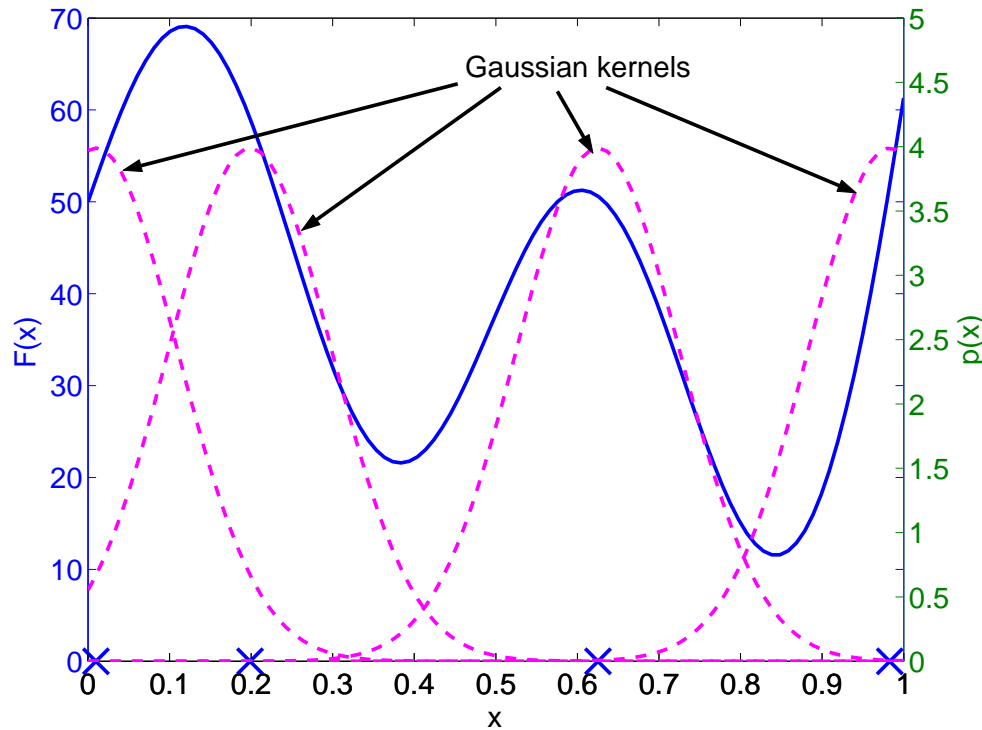
● Initial population: uniform $p(\mathbf{x})$

Estimation of Distribution Algorithm: Illustration



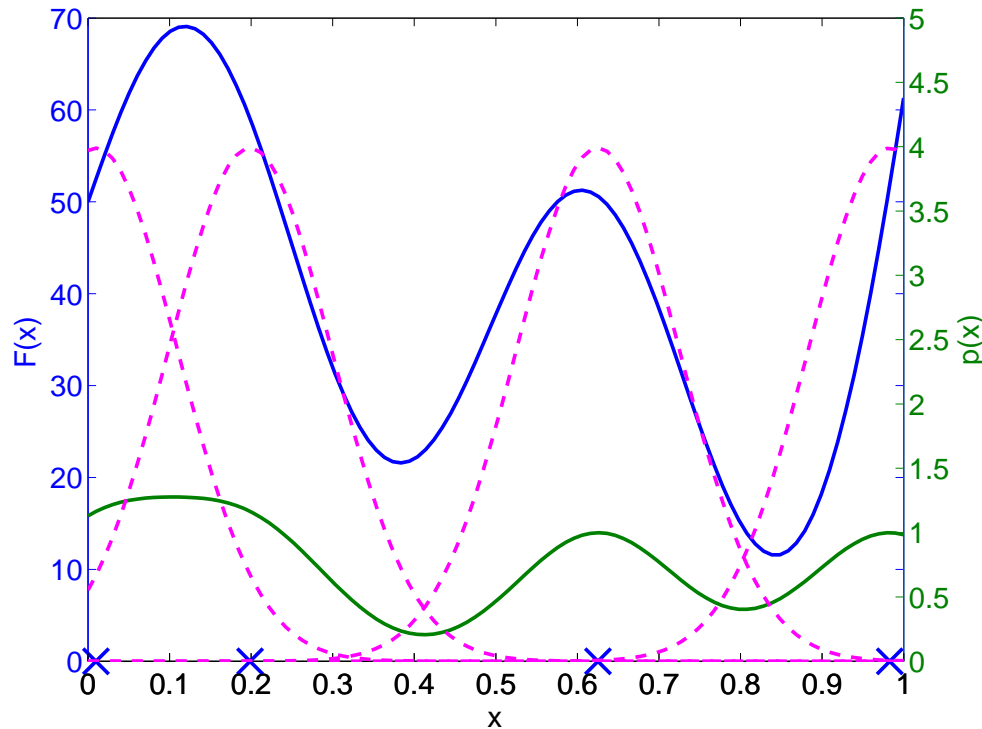
- Initial population: uniform $p(\mathbf{x})$
- Points obtained by selection

Estimation of Distribution Algorithm: Illustration



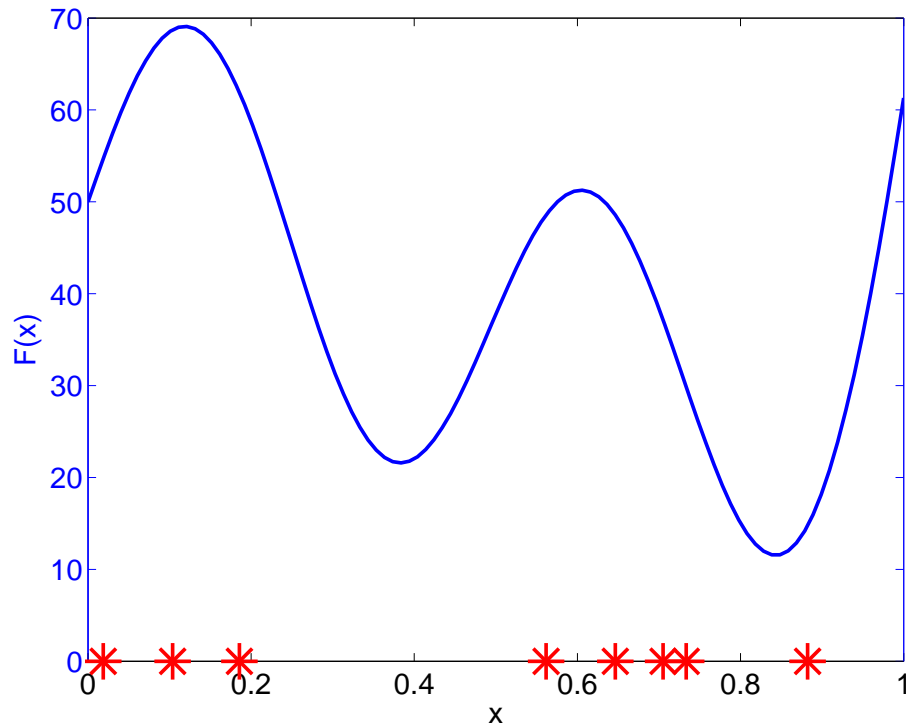
- Initial population: uniform $p(\mathbf{x})$
- Points obtained by selection
- Estimation of the distribution of good points $p(x)$
(continuous case, kernels,
 $p(x) = \frac{\text{const}}{N} \sum_{i=1}^N \exp\left(-\frac{(x-x_i)^2}{2\sigma^2}\right)$)

Estimation of Distribution Algorithm: Illustration



- Initial population: uniform $p(\mathbf{x})$
- Points obtained by selection
- Estimation of the distribution of good points $p(x)$
(continuous case, kernels,
 $p(x) = \frac{\text{const}}{N} \sum_{i=1}^N \exp\left(-\frac{(x-x_i)^2}{2\sigma^2}\right)$)
- Estimated distribution of good points $p(x)$

Estimation of Distribution Algorithm: Illustration



- Initial population: uniform $p(\mathbf{x})$
- Points obtained by selection
- Estimation of the distribution of good points $p(x)$ (continuous case, kernels, $p(x) = \frac{\text{const}}{N} \sum_{i=1}^N \exp\left(-\frac{(x-x_i)^2}{2\sigma^2}\right)$)
- Estimated distribution of good points $p(x)$
- New population obtained by sampling from $p(x)$

Estimating the distribution of good points

- Task: given a sample of μ selected points, infer distribution $p(\mathbf{x})$ of all the points of comparable fitness (“promising regions”)

Estimating the distribution of good points

- Task: given a sample of μ selected points, infer distribution $p(\mathbf{x})$ of all the points of comparable fitness (“promising regions”)
- Procedure:

Estimating the distribution of good points

- Task: given a sample of μ selected points, infer distribution $p(\mathbf{x})$ of all the points of comparable fitness (“promising regions”)
- Procedure:
 1. choose a model $\hat{p}(\mathbf{x}; m_1, \dots, m_r)$,

Estimating the distribution of good points

- Task: given a sample of μ selected points, infer distribution $p(\mathbf{x})$ of all the points of comparable fitness (“promising regions”)
- Procedure:
 1. choose a model $\hat{p}(\mathbf{x}; m_1, \dots, m_r)$,
 2. find the value of the model parameters m_j that maximizes the likelihood of the good observed points.

Estimating the distribution of good points

- Task: given a sample of μ selected points, infer distribution $p(\mathbf{x})$ of all the points of comparable fitness (“promising regions”)
- Procedure:
 1. choose a model $\hat{p}(\mathbf{x}; m_1, \dots, m_r)$,
 2. find the value of the model parameters m_j that maximizes the likelihood of the good observed points.
- The choice of the **model** is a compromise between

Estimating the distribution of good points

- Task: given a sample of μ selected points, infer distribution $p(\mathbf{x})$ of all the points of comparable fitness (“promising regions”)
- Procedure:
 1. choose a model $\hat{p}(\mathbf{x}; m_1, \dots, m_r)$,
 2. find the value of the model parameters m_j that maximizes the likelihood of the good observed points.
- The choice of the **model** is a compromise between
 1. the **exploitation** or **accuracy** of p , i.e. its ability to learn the distribution of selected points, and

Estimating the distribution of good points

- Task: given a sample of μ selected points, infer distribution $p(\mathbf{x})$ of all the points of comparable fitness (“promising regions”)
- Procedure:
 1. choose a model $\hat{p}(\mathbf{x}; m_1, \dots, m_r)$,
 2. find the value of the model parameters m_j that maximizes the likelihood of the good observed points.
- The choice of the **model** is a compromise between
 1. the **exploitation** or **accuracy** of p , i.e. its ability to learn the distribution of selected points, and
 2. the **generalization stability** of p in unvisited regions, in particular its ability to **explore** them.

Application of a Simple EDA to Laminate Optimization

Simple Model: Independent Variables

- General principle in machine learning: in the absence of information about the distribution, use simple models (cf. “Occam’s razor”)

Simple Model: Independent Variables

- General principle in machine learning: in the absence of information about the distribution, use simple models (cf. “Occam’s razor”)
- Simplest statistical model of selected points: independent variables:

$$p(x_1, x_2, \dots, x_n) = \prod_{k=1}^n p(x_k)$$

Simple Model: Independent Variables

- General principle in machine learning: in the absence of information about the distribution, use simple models (cf. “Occam’s razor”)
- Simplest statistical model of selected points: independent variables:

$$p(x_1, x_2, \dots, x_n) = \prod_{k=1}^n p(x_k)$$

Only the marginal distributions of the variables appear in the model:
discrete case = frequency of all possible values of each variable

Simple Model: Independent Variables

- General principle in machine learning: in the absence of information about the distribution, use simple models (cf. “Occam’s razor”)
- Simplest statistical model of selected points: independent variables:

$$p(x_1, x_2, \dots, x_n) = \prod_{k=1}^n p(x_k)$$

Only the marginal distributions of the variables appear in the model:
discrete case = frequency of all possible values of each variable

- Proposed by S. Baluja (PBIL, 1994) and H. Mühlenbein (1996) in the Univariate Marginal Distribution Algorithm (**UMDA**)

Simple Model: Independent Variables

- General principle in machine learning: in the absence of information about the distribution, use simple models (cf. “Occam’s razor”)
- Simplest statistical model of selected points: independent variables:

$$p(x_1, x_2, \dots, x_n) = \prod_{k=1}^n p(x_k)$$

Only the marginal distributions of the variables appear in the model:
discrete case = frequency of all possible values of each variable

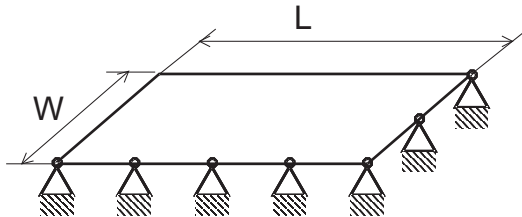
- Proposed by S. Baluja (PBIL, 1994) and H. Mühlenbein (1996) in the Univariate Marginal Distribution Algorithm (**UMDA**)
- Changes: non-binary alphabet, mutation to compensate for estimation error

Application to Laminates: Frequency problem

- Constrained maximization of the first natural frequency of a simply-supported rectangular laminated plate:

maximize $f_1(\theta_1, \dots, \theta_{15})$
such that $\nu_l \leq \nu_{\text{eff}} \leq \nu_u$

Poisson's ratio = deformation observed in the transverse direction when a unit deformation is applied in the longitudinal direction

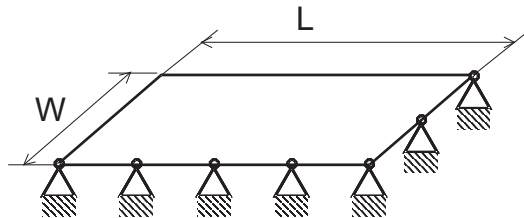


Application to Laminates: Frequency problem

- Constrained maximization of the first natural frequency of a simply-supported rectangular laminated plate:

maximize $f_1(\theta_1, \dots, \theta_{15})$
such that $\nu_l \leq \nu_{\text{eff}} \leq \nu_u$

Poisson's ratio = deformation observed in the transverse direction when a unit deformation is applied in the longitudinal direction



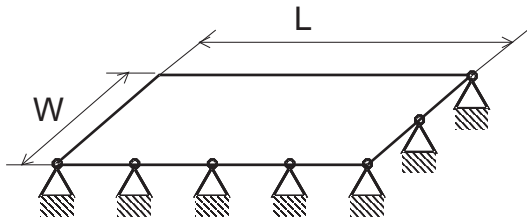
- $\theta_k \in \{0^\circ, 15^\circ, 30^\circ, 45^\circ, 60^\circ, 75^\circ, 90^\circ\}$

Application to Laminates: Frequency problem

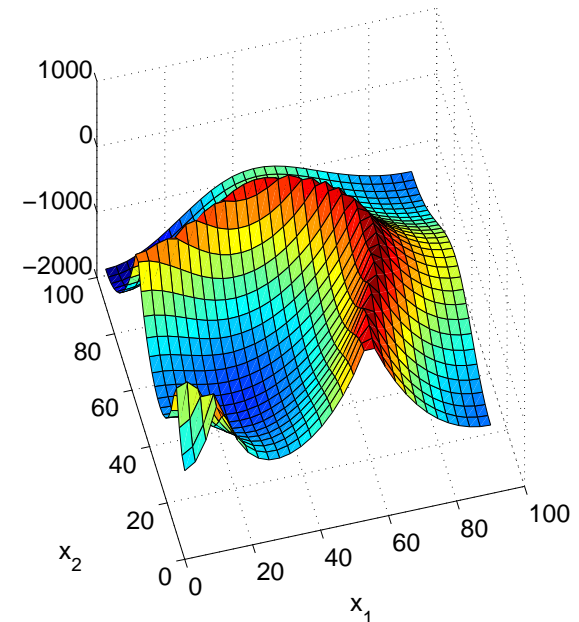
- Constrained maximization of the first natural frequency of a simply-supported rectangular laminated plate:

maximize $f_1(\theta_1, \dots, \theta_{15})$
such that $\nu_l \leq \nu_{\text{eff}} \leq \nu_u$

Poisson's ratio = deformation observed in the transverse direction when a unit deformation is applied in the longitudinal direction



- $\theta_k \in \{0^\circ, 15^\circ, 30^\circ, 45^\circ, 60^\circ, 75^\circ, 90^\circ\}$
- The constraints are enforced through a penalty approach

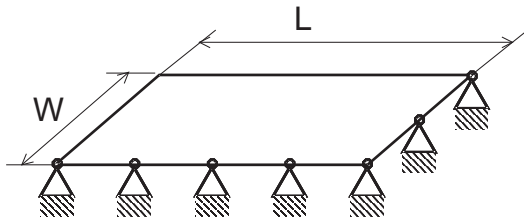


Application to Laminates: Frequency problem

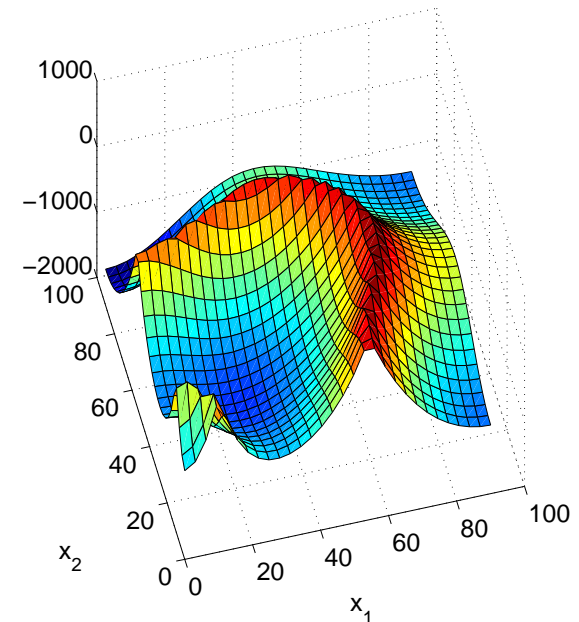
- Constrained maximization of the first natural frequency of a simply-supported rectangular laminated plate:

maximize $f_1(\theta_1, \dots, \theta_{15})$
such that $\nu_l \leq \nu_{\text{eff}} \leq \nu_u$

Poisson's ratio = deformation observed in the transverse direction when a unit deformation is applied in the longitudinal direction



- $\theta_k \in \{0^\circ, 15^\circ, 30^\circ, 45^\circ, 60^\circ, 75^\circ, 90^\circ\}$
- The constraints are enforced through a penalty approach
- The constraints create a narrow ridge in the design space



Results: reliability of the optimization

● Optimum:

$$[90_4 / \pm 75 / \pm 60_2 / \pm 45_5 / \pm 30_5]_s$$

Results: reliability of the optimization

- Optimum:

$[90_4 / \pm 75 / \pm 60_2 / \pm 45_5 / \pm 30_5]_s$

- Compare UMDA to a GA and a hill-climbing algorithm (SHC)

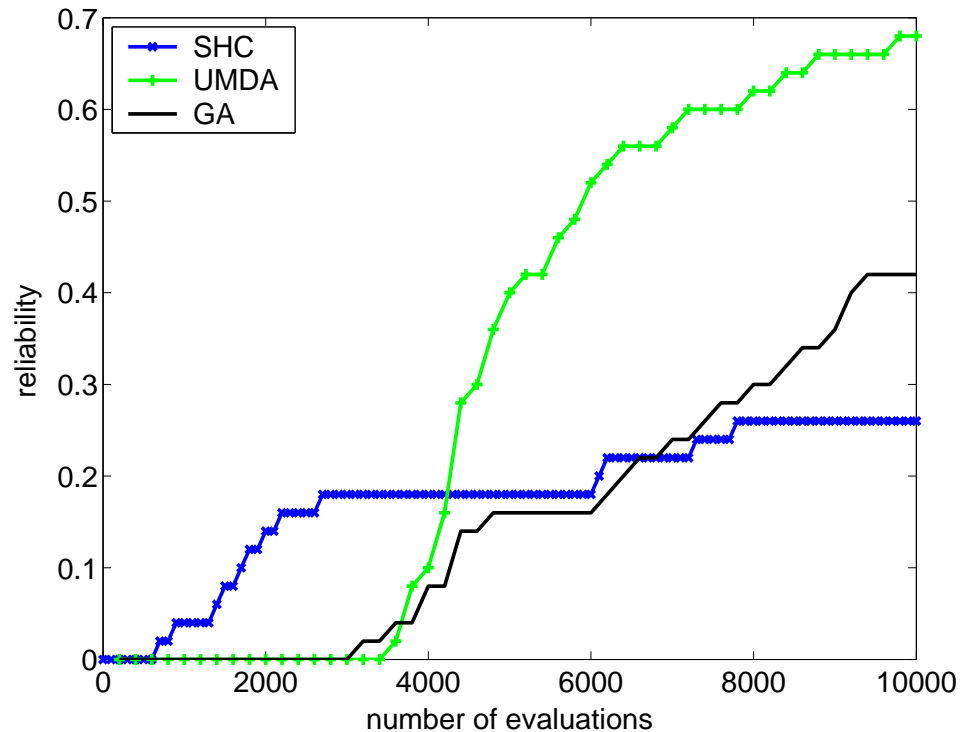
Results: reliability of the optimization

- Optimum:
 $[90_4 / \pm 75 / \pm 60_2 / \pm 45_5 / \pm 30_5]_s$
- Compare UMDA to a GA and a hill-climbing algorithm (SHC)
- UMDA and SHC: optimized parameters, GA: same setting as UMDA

Results: reliability of the optimization

- Optimum:
 $[90_4 / \pm 75 / \pm 60_2 / \pm 45_5 / \pm 30_5]_s$
- Compare UMDA to a GA and a hill-climbing algorithm (SHC)
- UMDA and SHC: optimized parameters, GA: same setting as UMDA

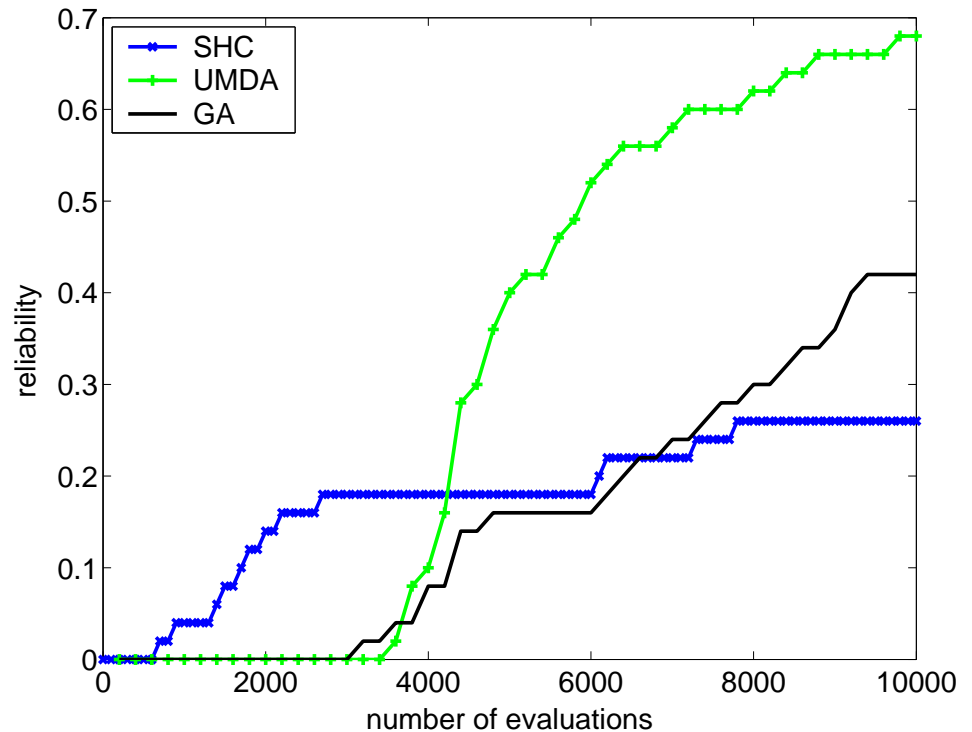
Reliability R : probability of finding the optimum in a given number of function evaluations.



Results: reliability of the optimization

- Optimum:
 $[90_4 / \pm 75 / \pm 60_2 / \pm 45_5 / \pm 30_5]_s$
- Compare UMDA to a GA and a hill-climbing algorithm (SHC)
- UMDA and SHC: optimized parameters, GA: same setting as UMDA

Reliability R : probability of finding the optimum in a given number of function evaluations.



- ⇒ UMDA outperforms SHC because its distribution approach (global) allows it to handle narrow search spaces
- ⇒ the performance of UMDA is substantially higher than that of GA for this problem

Improvement of the Statistical Model of Selected Points through Auxiliary Variables: the **Double-Distribution Optimization Algorithm**

Limitations of simple models

- Usual assumption: independent variables

$$p(x_1, x_2, \dots, x_n) = p(x_1)p(x_2) \dots p(x_n)$$

Limitations of simple models

- Usual assumption: independent variables

$$p(x_1, x_2, \dots, x_n) = p(x_1)p(x_2) \dots p(x_n)$$

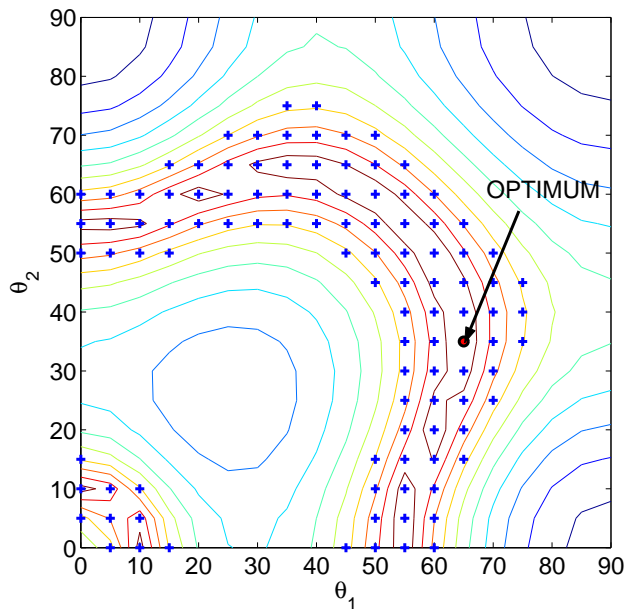
- Problem: does not work for problems with strong variable interactions

Limitations of simple models

- Usual assumption: independent variables

$$p(x_1, x_2, \dots, x_n) = p(x_1)p(x_2) \dots p(x_n)$$

- Problem: does not work for problems with strong variable interactions

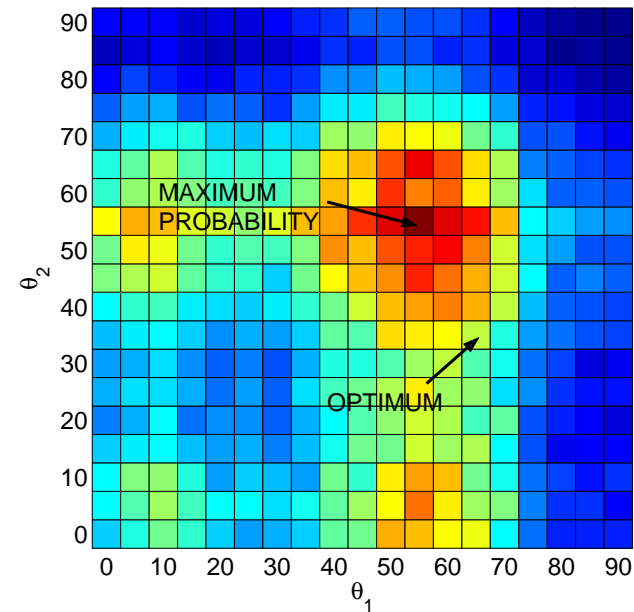
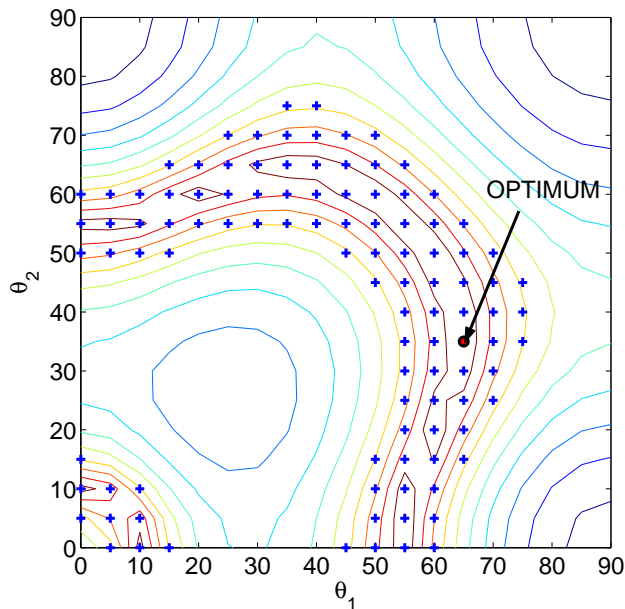


Limitations of simple models

- Usual assumption: independent variables

$$p(x_1, x_2, \dots, x_n) = p(x_1)p(x_2) \dots p(x_n)$$

- Problem: does not work for problems with strong variable interactions

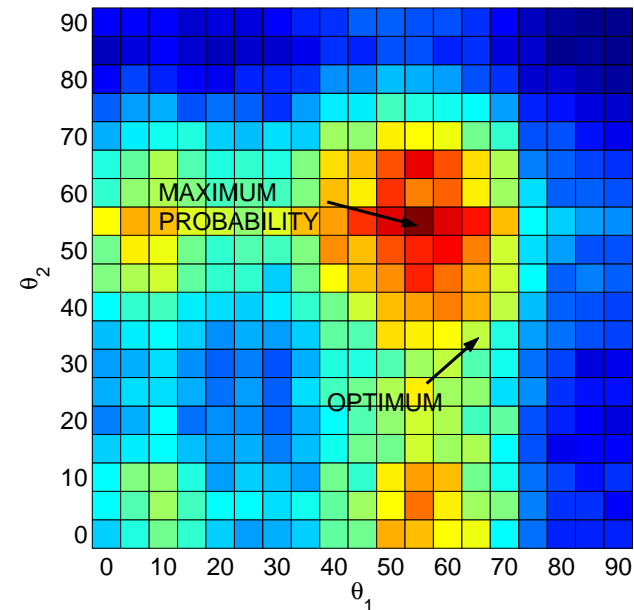
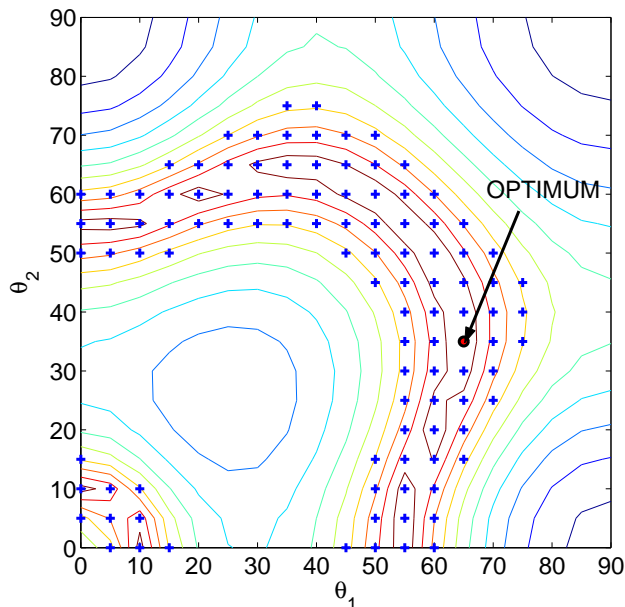


Limitations of simple models

- Usual assumption: independent variables

$$p(x_1, x_2, \dots, x_n) = p(x_1)p(x_2) \dots p(x_n)$$

- Problem: does not work for problems with strong variable interactions



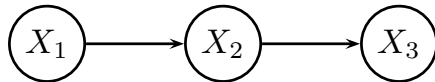
- High-probability areas do not coincide with high-fitness regions

Representation of variable dependencies

- Complex statistical models have been tried: chain models, tree models, full Bayesian networks (*Pelikan, 1999*)

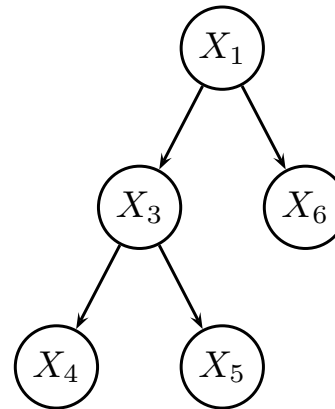
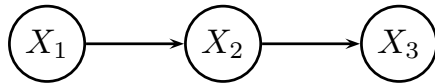
Representation of variable dependencies

- Complex statistical models have been tried: chain models, tree models, full Bayesian networks (*Pelikan, 1999*)



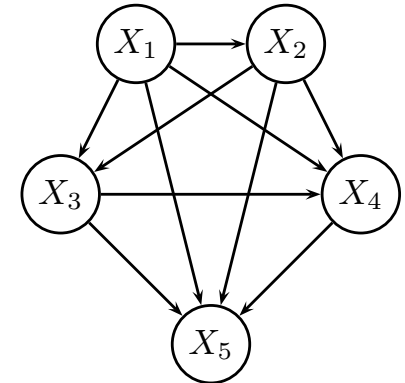
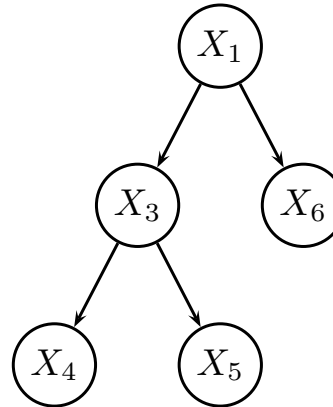
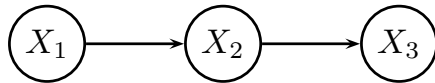
Representation of variable dependencies

- Complex statistical models have been tried: chain models, tree models, full Bayesian networks (*Pelikan, 1999*)



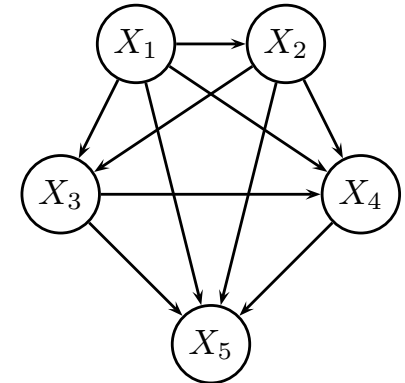
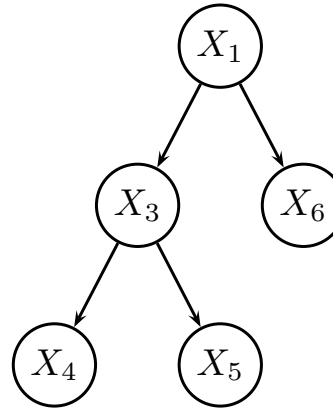
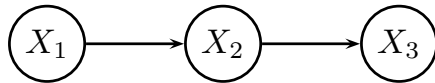
Representation of variable dependencies

- Complex statistical models have been tried: chain models, tree models, full Bayesian networks (*Pelikan, 1999*)



Representation of variable dependencies

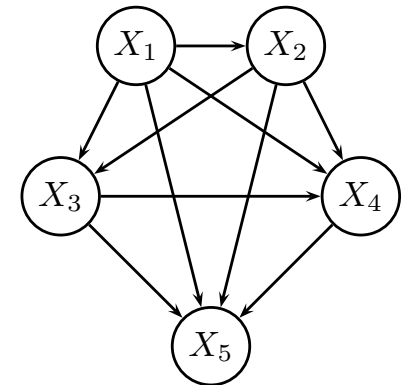
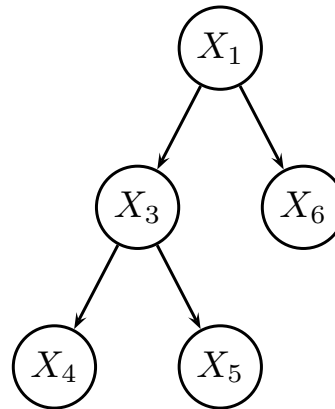
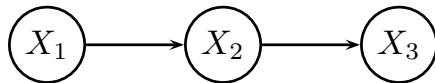
- Complex statistical models have been tried: chain models, tree models, full Bayesian networks (*Pelikan, 1999*)



- Disadvantages:

Representation of variable dependencies

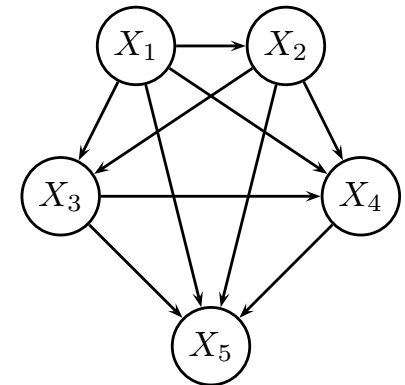
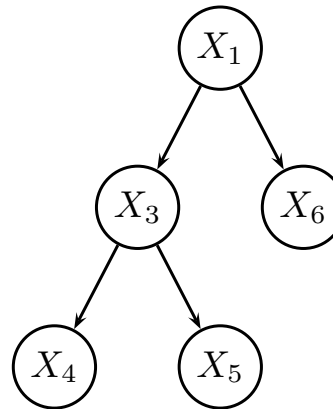
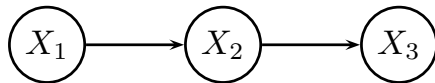
- Complex statistical models have been tried: chain models, tree models, full Bayesian networks (*Pelikan, 1999*)



- Disadvantages:
 - The number of parameters m_j to estimate increases rapidly with the model complexity

Representation of variable dependencies

- Complex statistical models have been tried: chain models, tree models, full Bayesian networks (*Pelikan, 1999*)



- Disadvantages:
 - The number of parameters m_j to estimate increases rapidly with the model complexity
 - ⇒ the **population size** needed to estimate these parameters ensure (with a constant confidence) **increases with the model complexity** because flexible models do not generalize well the information contained in the sample to other regions

Representation of joint actions of the variables via auxiliary variables

- **Observation** : in many situations, a small number of high order variables $\mathbf{V} = (V_1, V_2, \dots, V_m)$ partially determine the objective function

Representation of joint actions of the variables via auxiliary variables

- **Observation** : in many situations, a small number of high order variables $\mathbf{V} = (V_1, V_2, \dots, V_m)$ partially determine the objective function
- **Examples:**

Representation of joint actions of the variables via auxiliary variables

- **Observation** : in many situations, a small number of high order variables $\mathbf{V} = (V_1, V_2, \dots, V_m)$ partially determine the objective function
- **Examples**:
 - the dimensions of a beam determine its flexural behavior through the **moment of inertia** I ,

Representation of joint actions of the variables via auxiliary variables

- **Observation** : in many situations, a small number of high order variables $\mathbf{V} = (V_1, V_2, \dots, V_m)$ partially determine the objective function
- **Examples:**
 - the dimensions of a beam determine its flexural behavior through the **moment of inertia** I ,
 - the geometry of a vehicle influences its aerodynamic behavior via the **drag coefficient** C_V ,

Representation of joint actions of the variables via auxiliary variables

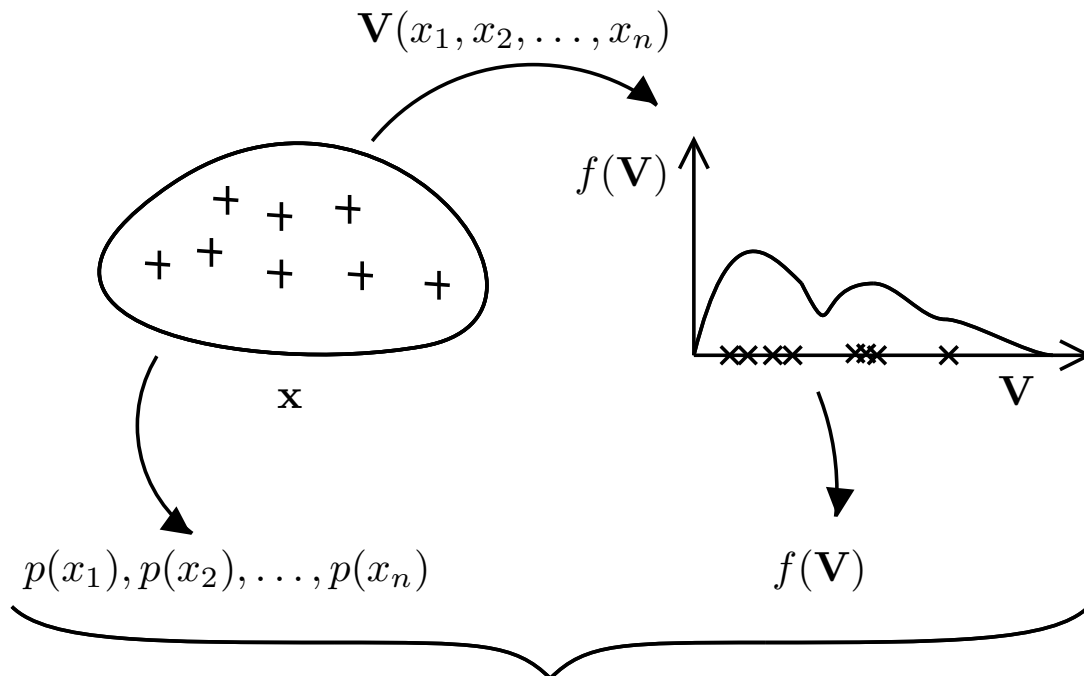
- **Observation** : in many situations, a small number of high order variables $\mathbf{V} = (V_1, V_2, \dots, V_m)$ partially determine the objective function
- **Examples:**
 - the dimensions of a beam determine its flexural behavior through the **moment of inertia** I ,
 - the geometry of a vehicle influences its aerodynamic behavior via the **drag coefficient** C_V ,
 - the locations of the holes/particles in a porous media affect the flow through the **permeability**.

Representation of joint actions of the variables via auxiliary variables

- **Observation** : in many situations, a small number of high order variables $\mathbf{V} = (V_1, V_2, \dots, V_m)$ partially determine the objective function
- **Examples**:
 - the dimensions of a beam determine its flexural behavior through the **moment of inertia** I ,
 - the geometry of a vehicle influences its aerodynamic behavior via the **drag coefficient** C_V ,
 - the locations of the holes/particles in a porous media affect the flow through the **permeability**.
- These meaningful quantities \mathbf{V} reflect **joint actions** of the variables \mathbf{x} and can be used as **auxiliary variables** to capture such interactions

Algorithm Principle

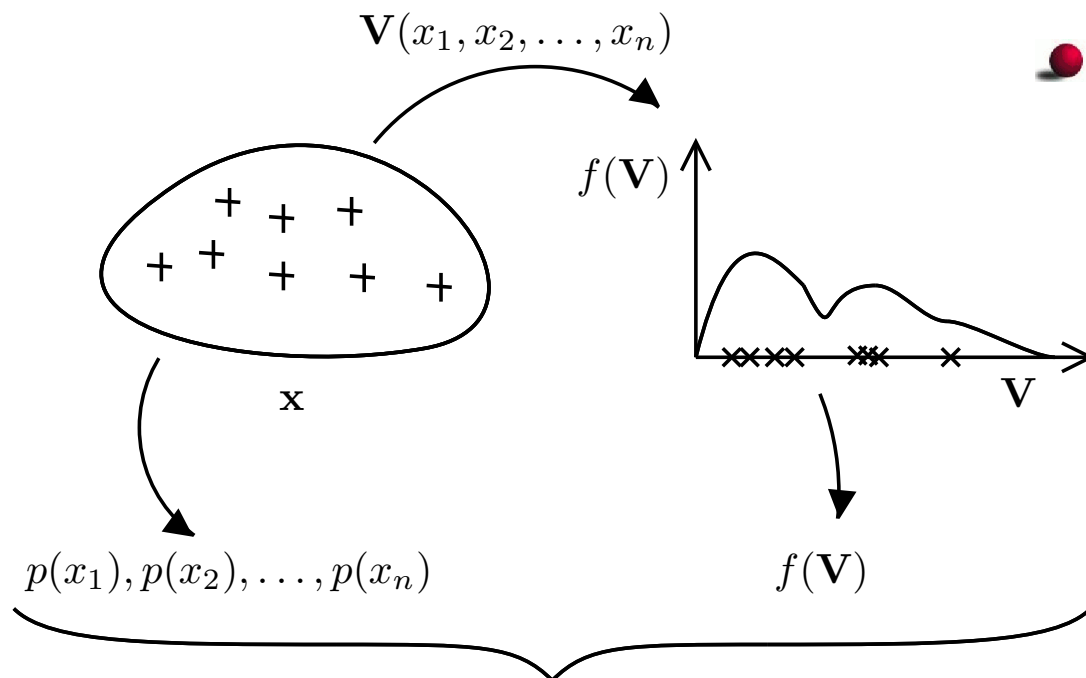
- The distribution $p(\mathbf{x})$ is represented by a **simple model** (UMDA)
- A simple distribution $f(\mathbf{V})$ is used to introduce variable dependencies



Two simple models \Rightarrow Complex model

Algorithm Principle

- The distribution $p(\mathbf{x})$ is represented by a **simple model** (UMDA)
- A simple distribution $f(\mathbf{V})$ is used to introduce variable dependencies

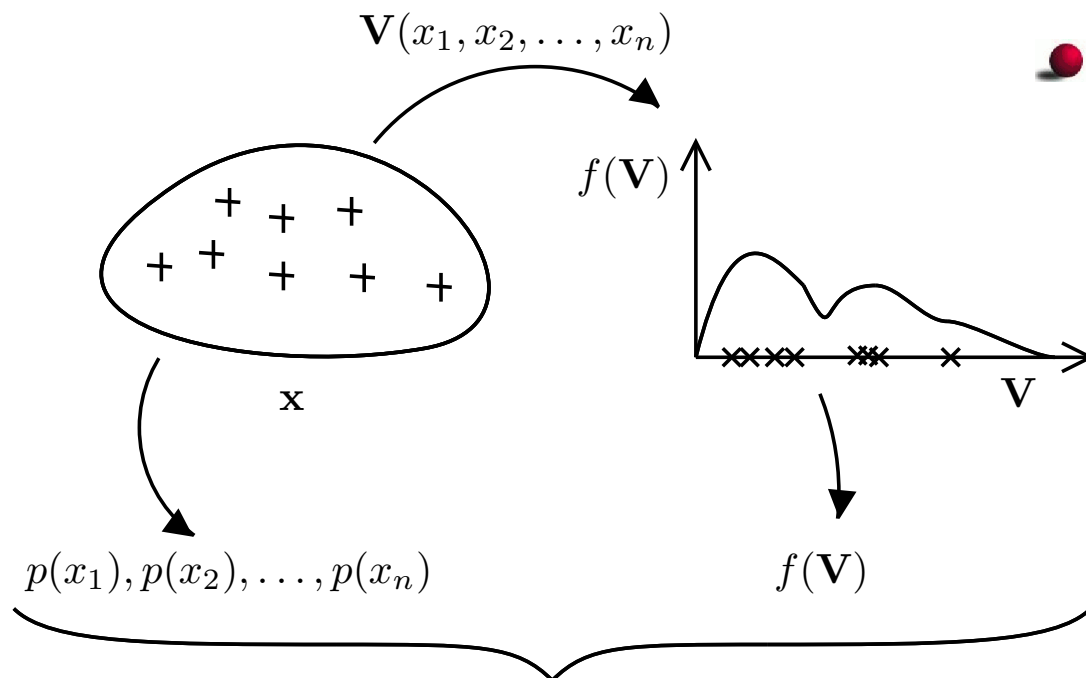


- Required attributes of the V 's:

Two simple models \Rightarrow Complex model

Algorithm Principle

- The distribution $p(\mathbf{x})$ is represented by a **simple model** (UMDA)
- A simple distribution $f(\mathbf{V})$ is used to introduce variable dependencies

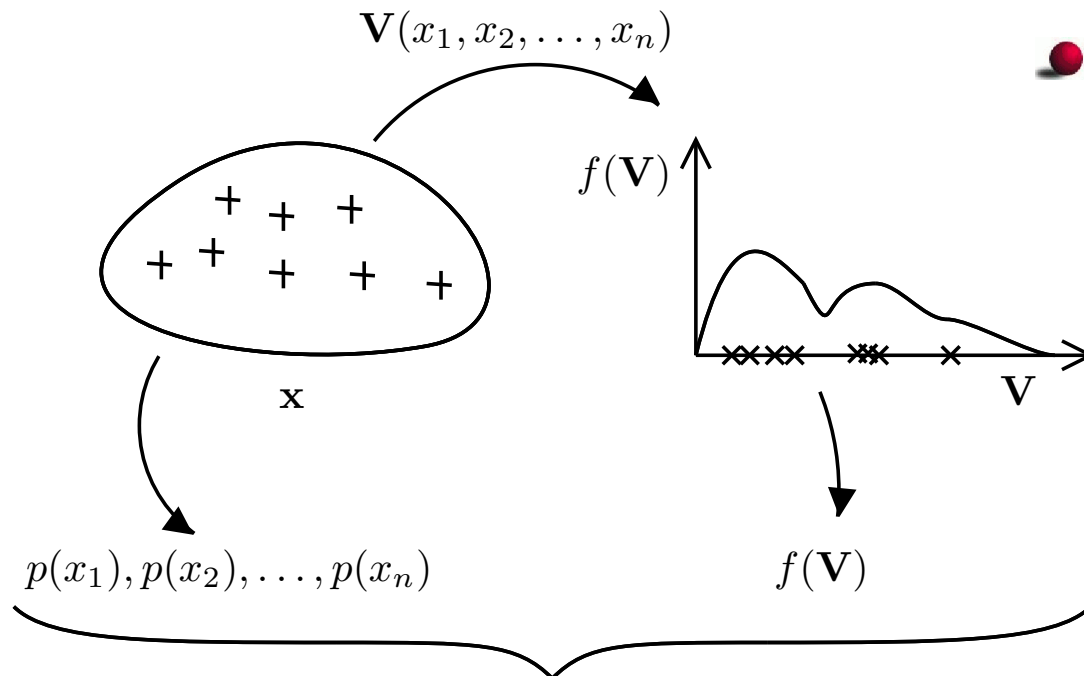


- Required attributes of the V 's:
 1. $m < n$

Two simple models \Rightarrow Complex model

Algorithm Principle

- The distribution $p(\mathbf{x})$ is represented by a **simple model** (UMDA)
- A simple distribution $f(\mathbf{V})$ is used to introduce variable dependencies

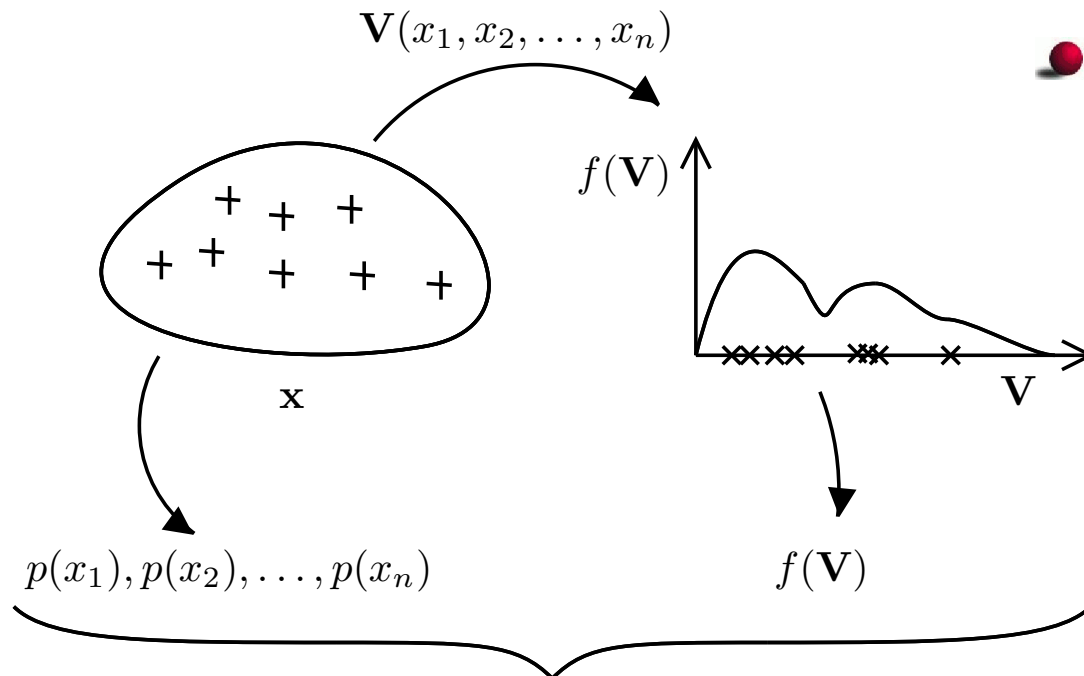


- Required attributes of the V 's:
 1. $m < n$
 2. m does not grow with n

Two simple models \Rightarrow Complex model

Algorithm Principle

- The distribution $p(\mathbf{x})$ is represented by a **simple model** (UMDA)
- A simple distribution $f(\mathbf{V})$ is used to introduce variable dependencies

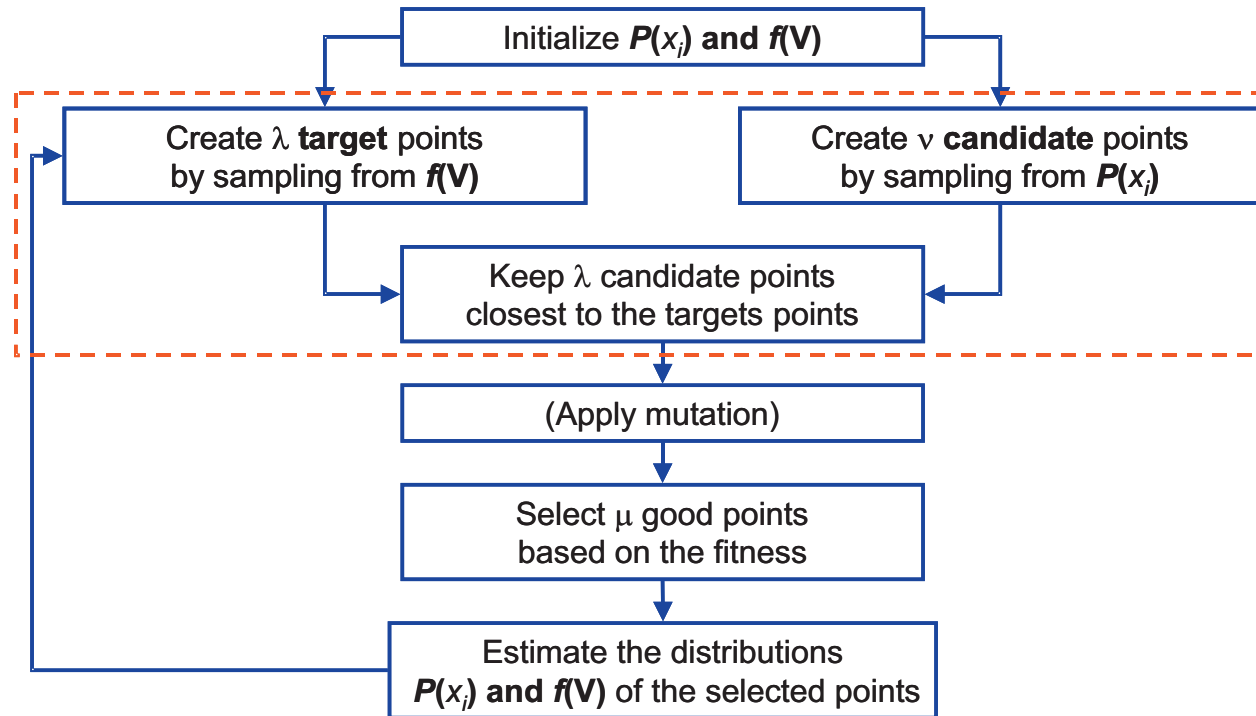


- Required attributes of the \mathbf{V} 's:

1. $m < n$
2. m does not grow with n
3. inexpensive to compute

Two simple models \Rightarrow Complex model

The Double-Distribution Optimization Algorithm



Goal: create points whose distribution that reflects both $p(\mathbf{x})$ and $f(\mathbf{V})$:

- $p(x_i)$ provides a pool of points that have correct marginal distributions.
- $f(\mathbf{V})$ is used as a filter that favors promising regions.
- The relative influence of the 2 distributions is adjusted through ν/λ

Application to Laminate Optimization Problems

Case of composite laminates:

Auxiliary variables = “Lamination Parameters”

- $V \equiv$ Lamination parameters = geometric contribution of the plies to the stiffness.

Case of composite laminates:

Auxiliary variables = “Lamination Parameters”

- $V \equiv$ Lamination parameters = geometric contribution of the plies to the stiffness.
- E.g. in-plane problem:

$$\begin{Bmatrix} A_{11} \\ A_{22} \\ A_{12} \\ A_{66} \end{Bmatrix} = h \begin{bmatrix} U_1 & U_2 & U_3 \\ U_1 & -U_2 & U_3 \\ U_5 & 0 & -U_3 \\ U_4 & 0 & -U_3 \end{bmatrix} \begin{Bmatrix} 1 \\ V_1^* \\ V_3^* \end{Bmatrix}$$

h : total laminate thickness, U_i 's: material invariants

Case of composite laminates:

Auxiliary variables = “Lamination Parameters”

- $V \equiv$ Lamination parameters = geometric contribution of the plies to the stiffness.
- E.g. in-plane problem:

$$\begin{Bmatrix} A_{11} \\ A_{22} \\ A_{12} \\ A_{66} \end{Bmatrix} = h \begin{bmatrix} U_1 & U_2 & U_3 \\ U_1 & -U_2 & U_3 \\ U_5 & 0 & -U_3 \\ U_4 & 0 & -U_3 \end{bmatrix} \begin{Bmatrix} 1 \\ V_1^* \\ V_3^* \end{Bmatrix}$$

h : total laminate thickness, U_i 's: material invariants

- Symmetric balanced laminates $[\pm\theta_1, \pm\theta_2, \dots, \pm\theta_n]_s$:

$$V_{\{1,3\}}^* = \frac{2}{h} \int_0^{h/2} \{\cos 2\theta, \cos 4\theta\} dz = \frac{1}{n} \sum_{k=1}^n \{\cos 2\theta_k, \cos 4\theta_k\}$$

Representation of the probability distributions

Distribution in the θ -domain

Representation of the probability distributions

Distribution in the θ -domain

 $\mathbf{x} \equiv \theta$

Representation of the probability distributions

Distribution in the θ -domain

- $\mathbf{x} \equiv \theta$
- Discrete univariate model
 - ⇒ estimate marginal frequencies

Representation of the probability distributions

Distribution in the θ -domain

- $\mathbf{x} \equiv \theta$
- Discrete univariate model
 - ⇒ estimate marginal frequencies

Distribution in the V -domain

Representation of the probability distributions

Distribution in the θ -domain

- $\mathbf{x} \equiv \theta$
- Discrete univariate model
 - ⇒ estimate marginal frequencies

Distribution in the \mathbf{V} -domain

- Continuous variables

Representation of the probability distributions

Distribution in the θ -domain

- $\mathbf{x} \equiv \theta$
- Discrete univariate model
 - ⇒ estimate marginal frequencies

Distribution in the \mathbf{V} -domain

- Continuous variables
- Use **kernel density estimate**:

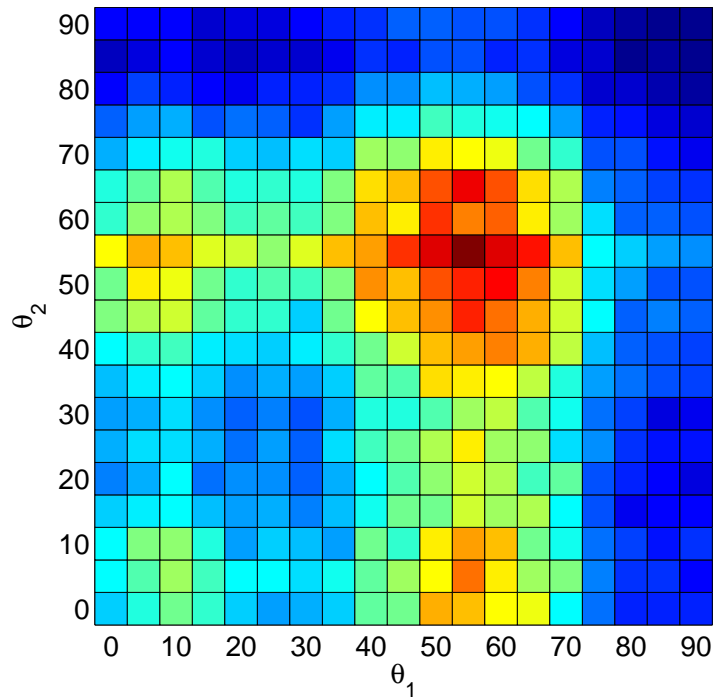
$$f(\mathbf{V}) = \frac{1}{\mu} \sum_{i=1}^{\mu} K(\mathbf{V} - \mathbf{V}_i)$$

In this work, we used Gaussian kernels:

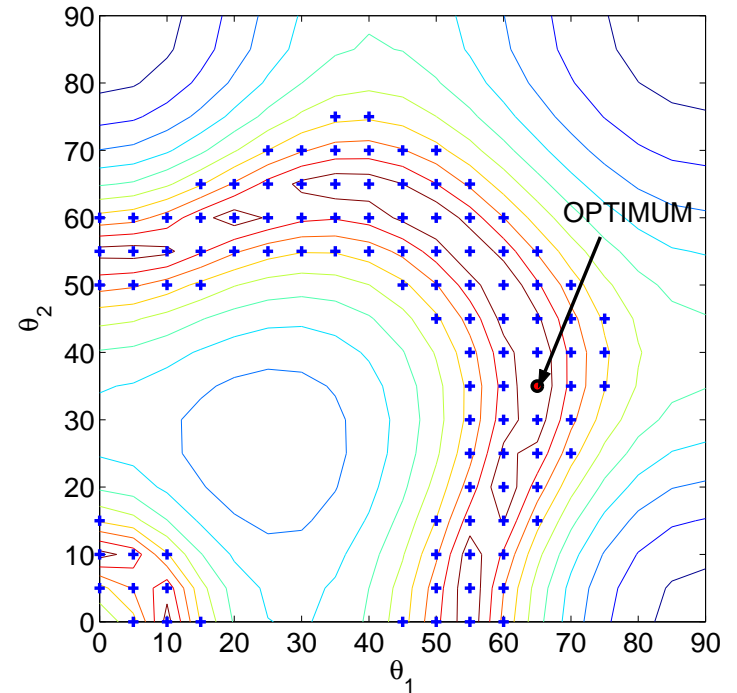
$$K(\mathbf{u}) = \frac{1}{(2\pi)^{d/2} \sigma^d} \exp\left(-\frac{\mathbf{u}^T \mathbf{u}}{\sigma^2}\right)$$

Estimated Distributions: UMDA and DDOA

UMDA: probability concentrated around (55, 55)

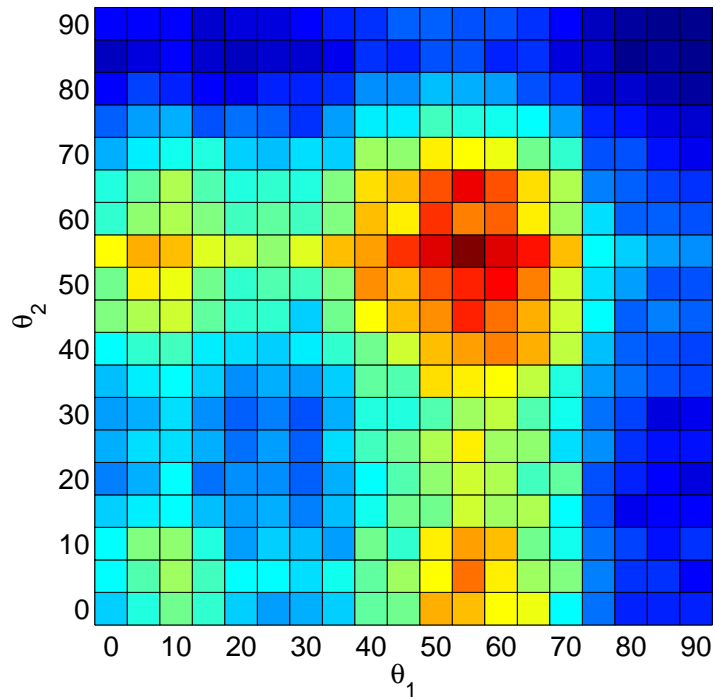


Fitness function and selected points

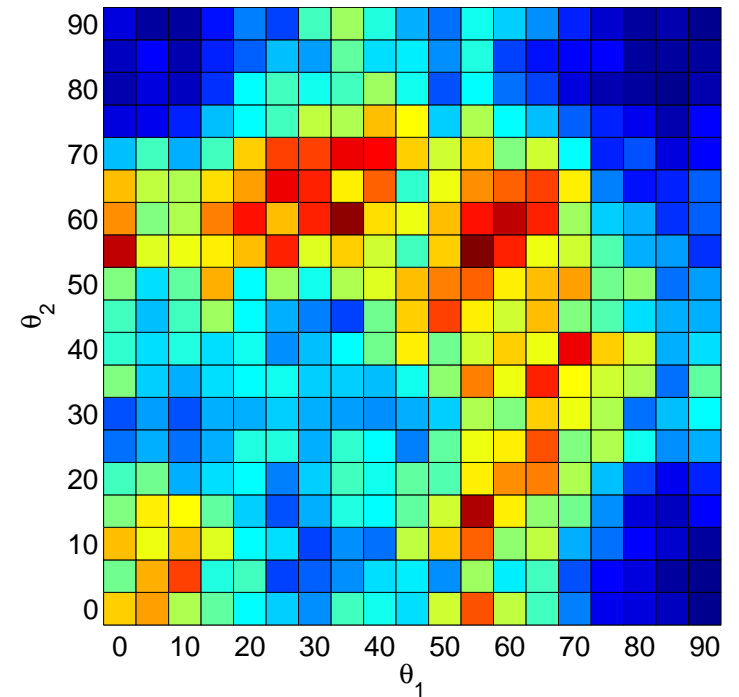


Estimated Distributions: UMDA and DDOA

UMDA: probability concentrated around (55, 55)

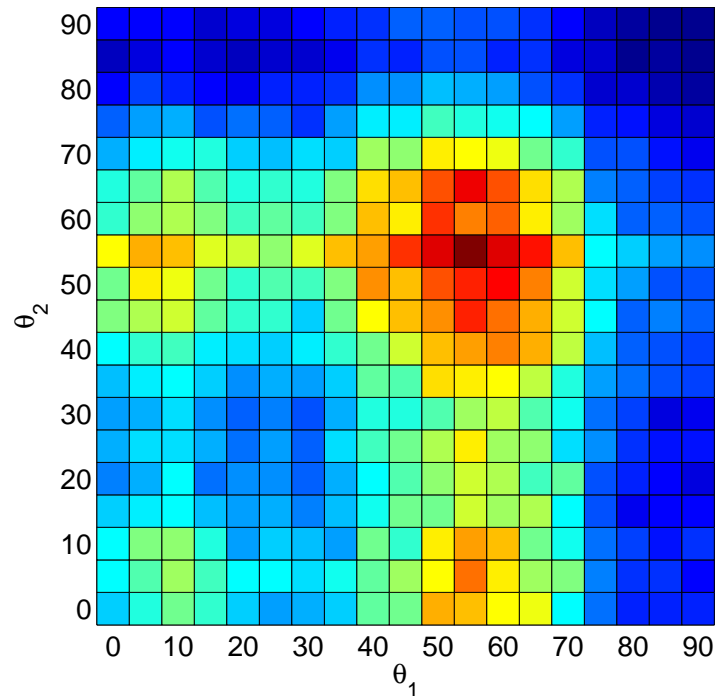


DDOA: the mass is distributed along the “tunnel”

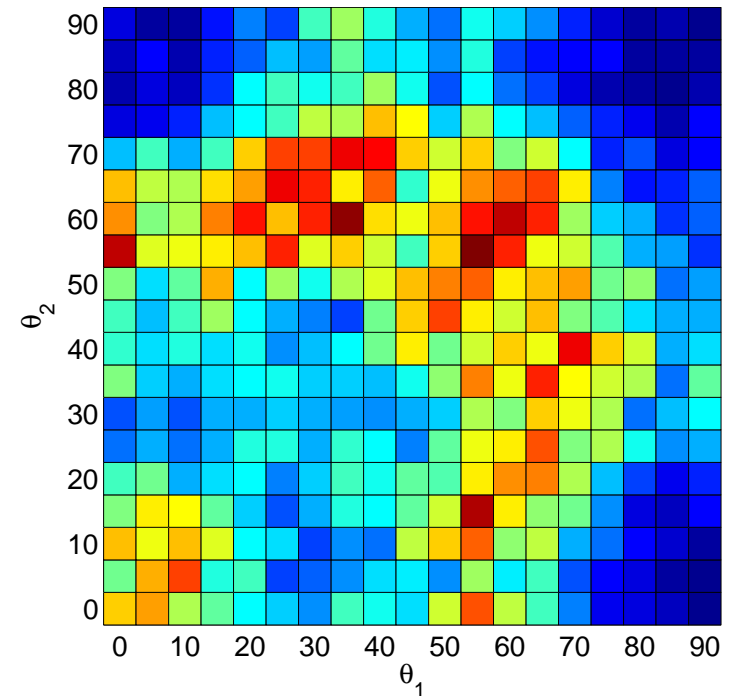


Estimated Distributions: UMDA and DDOA

UMDA: probability concentrated around (55, 55)



DDOA: the mass is distributed along the “tunnel”



- Sampling from $p(\theta_1), \dots, p(\theta_n)$ leads to an inaccurate distribution
- V-based selection improves the distribution by introducing variable dependencies

Application I: Design of “zero-CTE” laminates

- Objective: minimize the longitudinal coefficient of thermal expansion (CTE) subject to a constraint on the first natural vibration frequency, for a 50 in \times 15 in plate

$$\begin{aligned} &\text{minimize } |\bar{\alpha}_x| \\ &\text{such that } f_1 \geq f_{\min} \end{aligned}$$

Application I: Design of “zero-CTE” laminates

- Objective: minimize the longitudinal coefficient of thermal expansion (CTE) subject to a constraint on the first natural vibration frequency, for a 50 in × 15 in plate

$$\begin{aligned} &\text{minimize } |\bar{\alpha}_x| \\ &\text{such that } f_1 \geq f_{\min} \end{aligned}$$

- Constraint enforced through a penalty approach

Application I: Design of “zero-CTE” laminates

- Objective: minimize the longitudinal coefficient of thermal expansion (CTE) subject to a constraint on the first natural vibration frequency, for a 50 in × 15 in plate

$$\begin{aligned} &\text{minimize } |\bar{\alpha}_x| \\ &\text{such that } f_1 \geq f_{\min} \end{aligned}$$

- Constraint enforced through a penalty approach
- Possible values of the angles: $\theta_k \in \{0^\circ, 22.5^\circ, 45^\circ, 67.5^\circ, 90^\circ\}$

Application I: Design of “zero-CTE” laminates

- Objective: minimize the longitudinal coefficient of thermal expansion (CTE) subject to a constraint on the first natural vibration frequency, for a 50 in × 15 in plate

$$\begin{aligned} &\text{minimize } |\bar{\alpha}_x| \\ &\text{such that } f_1 \geq f_{\min} \end{aligned}$$

- Constraint enforced through a penalty approach
- Possible values of the angles: $\theta_k \in \{0^\circ, 22.5^\circ, 45^\circ, 67.5^\circ, 90^\circ\}$
- Case $n = 12$: optimum = $[90_4 / \pm 67.5 / 0_6 / \pm 22.5_6]_s$

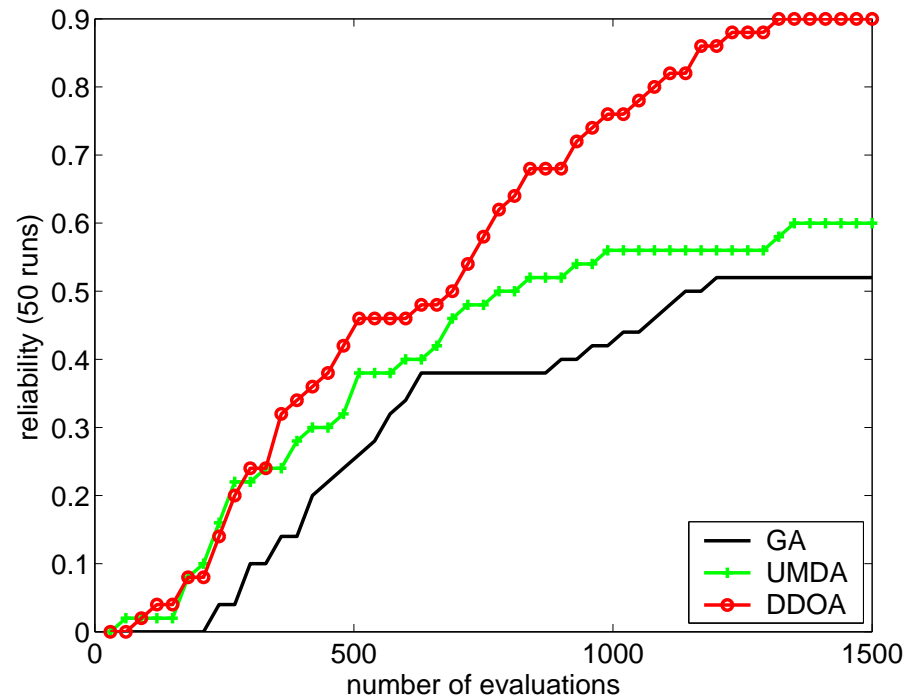
Application I: Design of “zero-CTE” laminates

- Objective: minimize the longitudinal coefficient of thermal expansion (CTE) subject to a constraint on the first natural vibration frequency, for a 50 in × 15 in plate

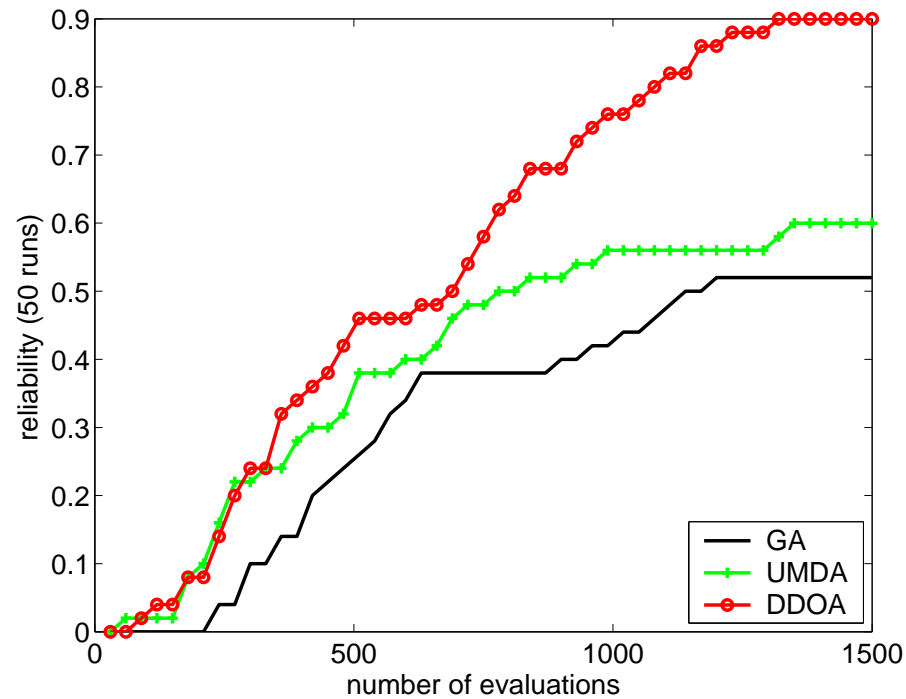
$$\begin{aligned} &\text{minimize } |\bar{\alpha}_x| \\ &\text{such that } f_1 \geq f_{\min} \end{aligned}$$

- Constraint enforced through a penalty approach
- Possible values of the angles: $\theta_k \in \{0^\circ, 22.5^\circ, 45^\circ, 67.5^\circ, 90^\circ\}$
- Case $n = 12$: optimum = $[90_4 / \pm 67.5 / 0_6 / \pm 22.5_6]_s$
- Particularity: **response is a function of the lamination parameters only**
⇒ V 's provide reliable information about the optimum

Comparison with UMDA and GA

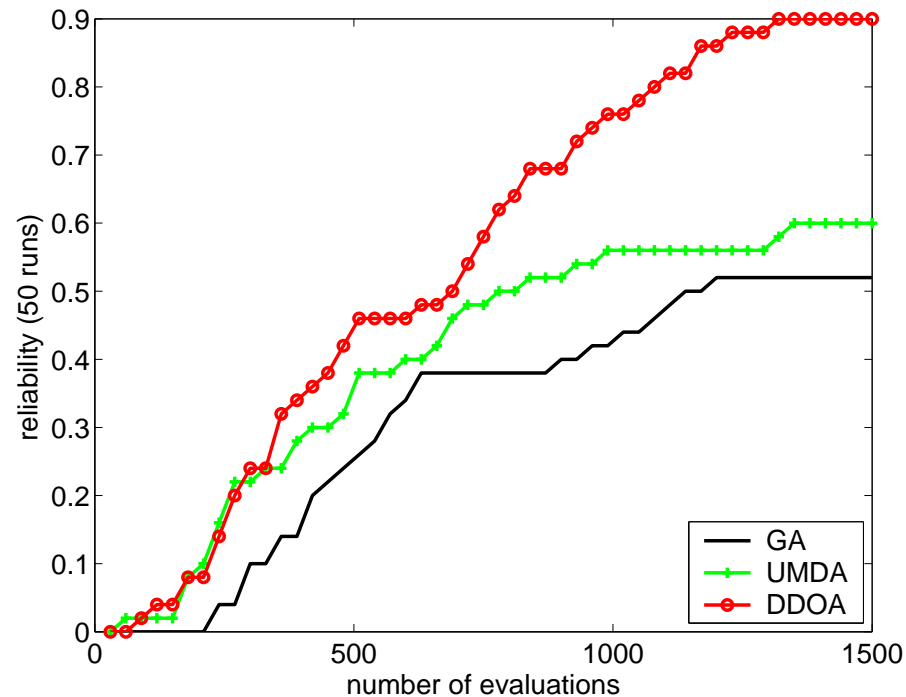


Comparison with UMDA and GA



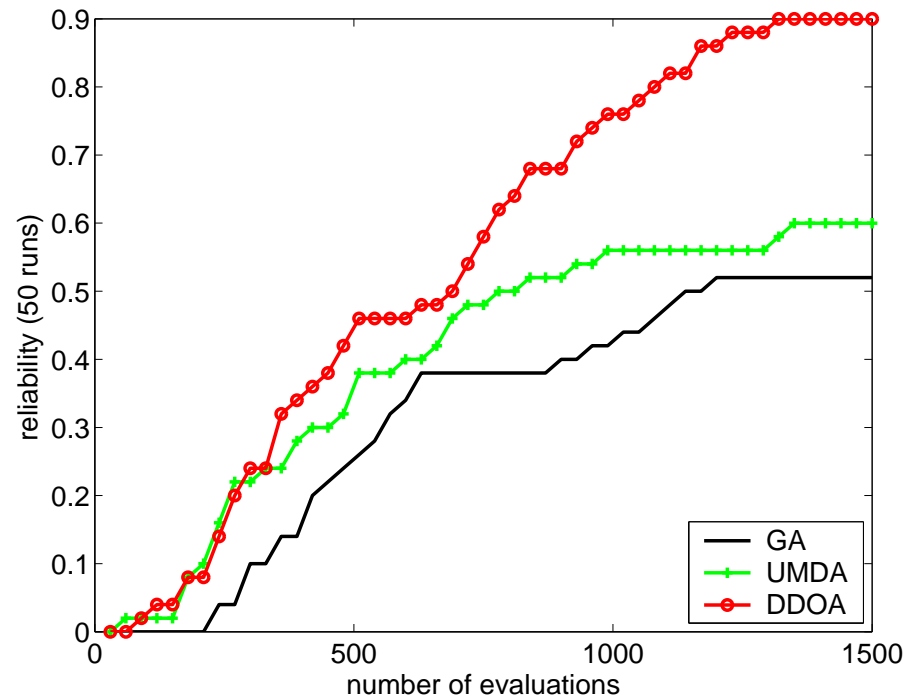
- GA and UMDA's progress falls off after 600 analyses

Comparison with UMDA and GA



- GA and UMDA's progress falls off after 600 analyses
- DDOA reaches high a reliability (90%)

Comparison with UMDA and GA

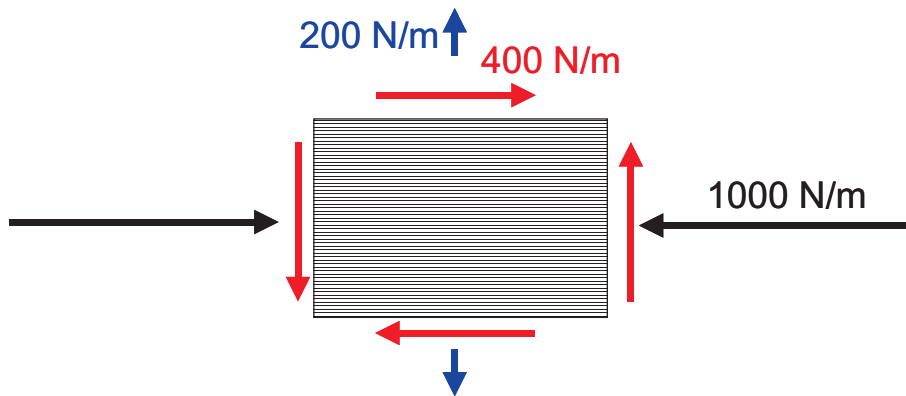


- GA and UMDA's progress falls off after 600 analyses
- DDOA reaches high a reliability (90%)
- ⇒ For this problem, **DDOA benefits from the use of auxiliary variables** (incorporation of physics-based information improves accuracy of $p(\mathbf{x})$)

Application II: Strength Maximization

- Strength maximization problem:

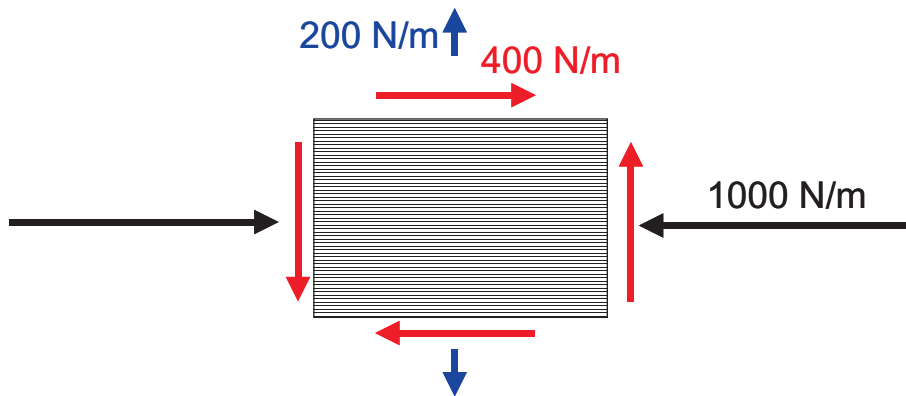
$$\text{maximize } \lambda_s = \min_{k=1}^n \left(\min \left(\frac{\epsilon_1^{\text{ult}}}{\epsilon_1(k)}, \frac{\epsilon_2^{\text{ult}}}{\epsilon_2(k)}, \frac{\gamma_{12}^{\text{ult}}}{\gamma_{12}(k)} \right) \right)$$



Application II: Strength Maximization

- Strength maximization problem:

$$\text{maximize } \lambda_s = \min_{k=1}^n \left(\min \left(\frac{\epsilon_1^{\text{ult}}}{\epsilon_1(k)}, \frac{\epsilon_2^{\text{ult}}}{\epsilon_2(k)}, \frac{\gamma_{12}^{\text{ult}}}{\gamma_{12}(k)} \right) \right)$$

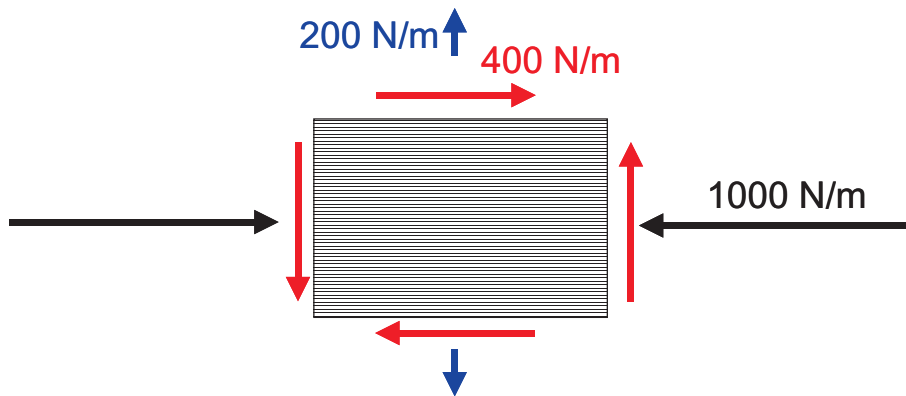


- Characteristics of this problem:

Application II: Strength Maximization

- Strength maximization problem:

$$\text{maximize } \lambda_s = \min_{k=1}^n \left(\min \left(\frac{\epsilon_1^{\text{ult}}}{\epsilon_1(k)}, \frac{\epsilon_2^{\text{ult}}}{\epsilon_2(k)}, \frac{\gamma_{12}^{\text{ult}}}{\gamma_{12}(k)} \right) \right)$$



- Characteristics of this problem:

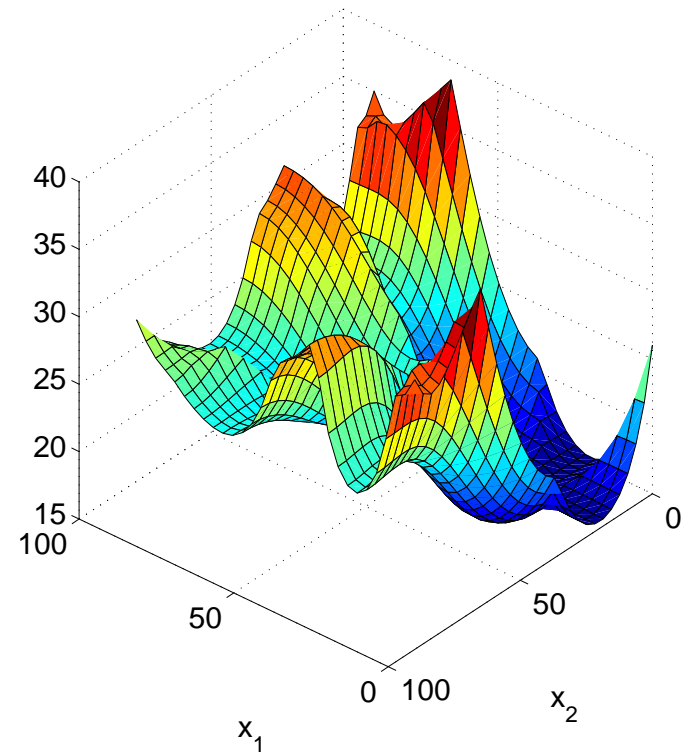
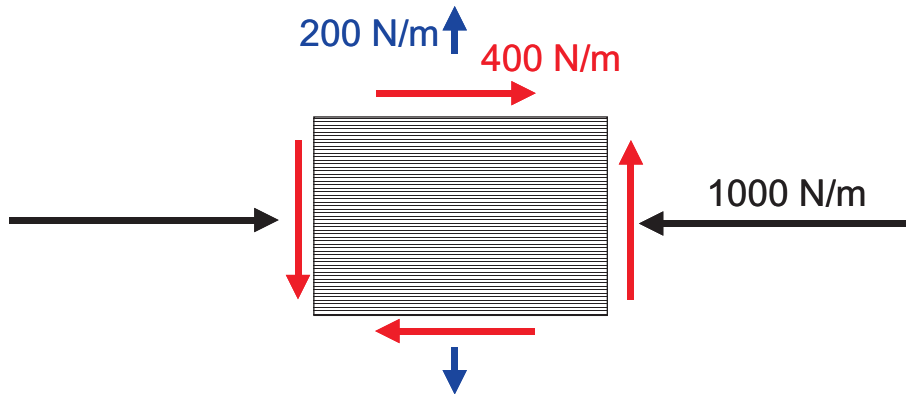
- the V 's do not capture all the response:

$$\lambda_s = \lambda_s(V_1, V_3, \theta_1, \dots, \theta_n)$$

Application II: Strength Maximization

- Strength maximization problem:

$$\text{maximize } \lambda_s = \min_{k=1}^n \left(\min \left(\frac{\epsilon_1^{\text{ult}}}{\epsilon_1(k)}, \frac{\epsilon_2^{\text{ult}}}{\epsilon_2(k)}, \frac{\gamma_{12}^{\text{ult}}}{\gamma_{12}(k)} \right) \right)$$



- Characteristics of this problem:
 - the V 's do not capture all the response:
 $\lambda_s = \lambda_s(V_1, V_3, \theta_1, \dots, \theta_n)$
 - many local optima

Comparison with UMDA and GA

- Case $n = 12$

Comparison with UMDA and GA

- Case $n = 12$
- $\theta_k \in \{0^\circ, 22.5^\circ, 45^\circ, 67.5^\circ, 90^\circ\}$

Comparison with UMDA and GA

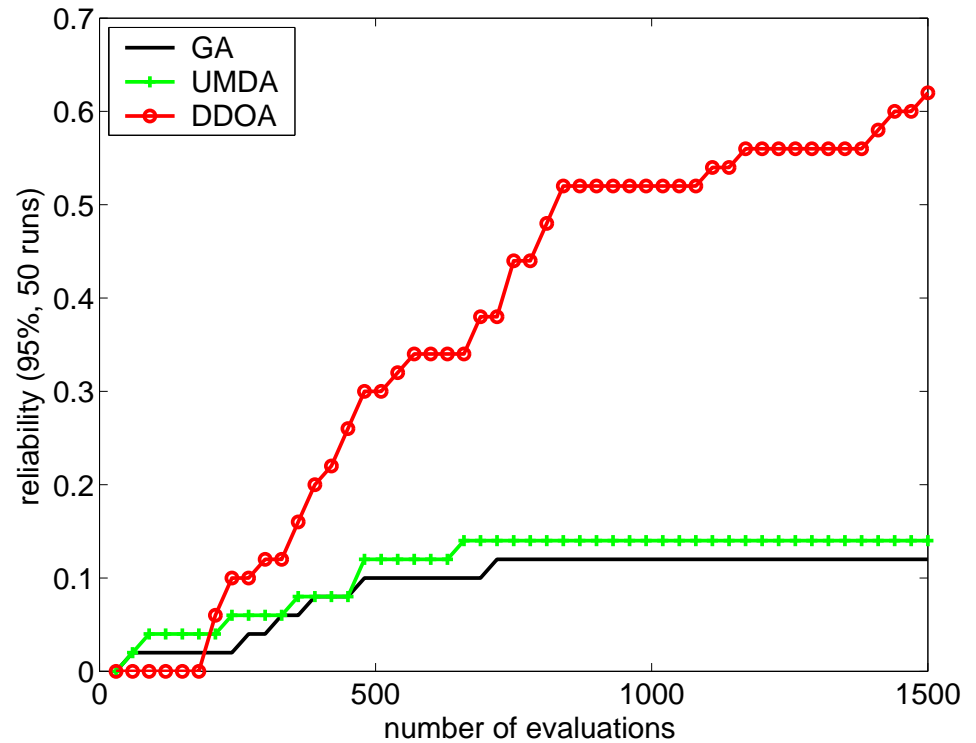
- Case $n = 12$
- $\theta_k \in \{0^\circ, 22.5^\circ, 45^\circ, 67.5^\circ, 90^\circ\}$
- Global optimum:
 $[0_{14}/ \pm 67.5_5]_s, \lambda_s = 4.74$

Comparison with UMDA and GA

- Case $n = 12$
- $\theta_k \in \{0^\circ, 22.5^\circ, 45^\circ, 67.5^\circ, 90^\circ\}$
- Global optimum:
 $[0_{14}/ \pm 67.5_5]_s, \lambda_s = 4.74$
- Parameters: $\lambda = \mu = 30$, linear ranking selection, $p_m = 0.02$

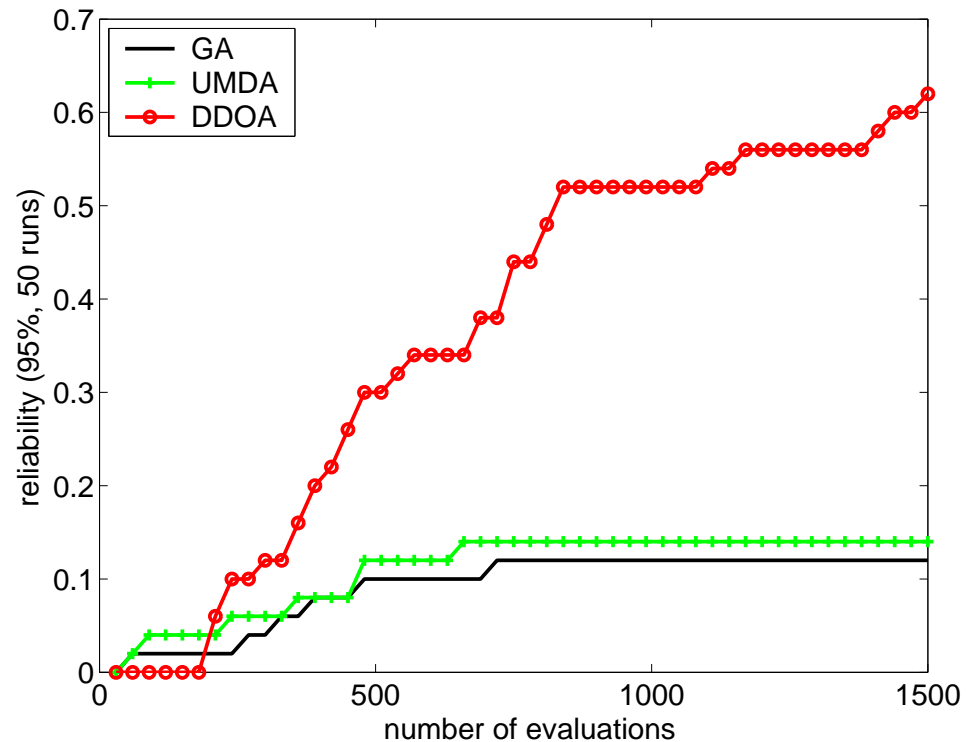
Comparison with UMDA and GA

- Case $n = 12$
- $\theta_k \in \{0^\circ, 22.5^\circ, 45^\circ, 67.5^\circ, 90^\circ\}$
- Global optimum:
 $[0_{14} / \pm 67.5_5]_s, \lambda_s = 4.74$
- Parameters: $\lambda = \mu = 30$, linear ranking selection, $p_m = 0.02$



Comparison with UMDA and GA

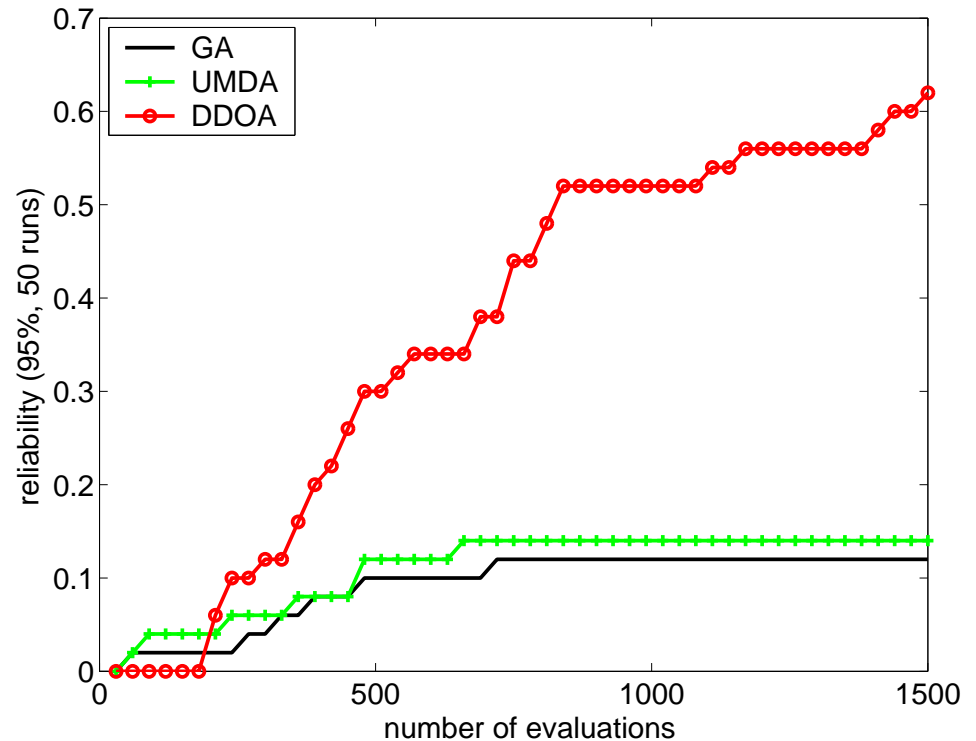
- Case $n = 12$
- $\theta_k \in \{0^\circ, 22.5^\circ, 45^\circ, 67.5^\circ, 90^\circ\}$
- Global optimum:
 $[0_{14} / \pm 67.5_5]_s, \lambda_s = 4.74$
- Parameters: $\lambda = \mu = 30$, linear ranking selection, $p_m = 0.02$



- ⇒ UMDA and GA locally improve the initial candidate solutions, but fail to converge to high-fitness solutions

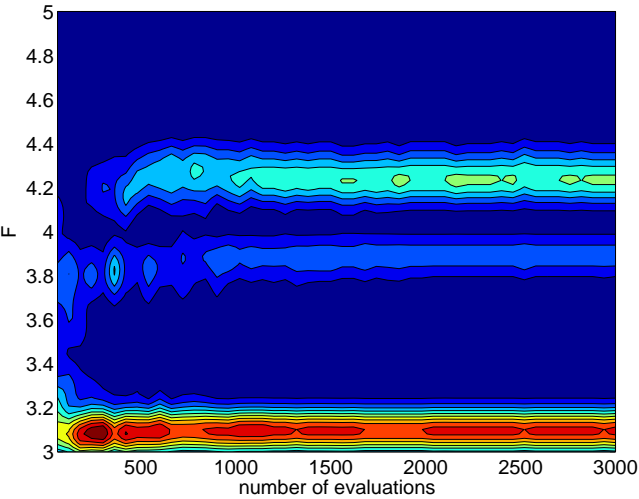
Comparison with UMDA and GA

- Case $n = 12$
- $\theta_k \in \{0^\circ, 22.5^\circ, 45^\circ, 67.5^\circ, 90^\circ\}$
- Global optimum:
 $[0_{14} / \pm 67.5_5]_s, \lambda_s = 4.74$
- Parameters: $\lambda = \mu = 30$, linear ranking selection, $p_m = 0.02$

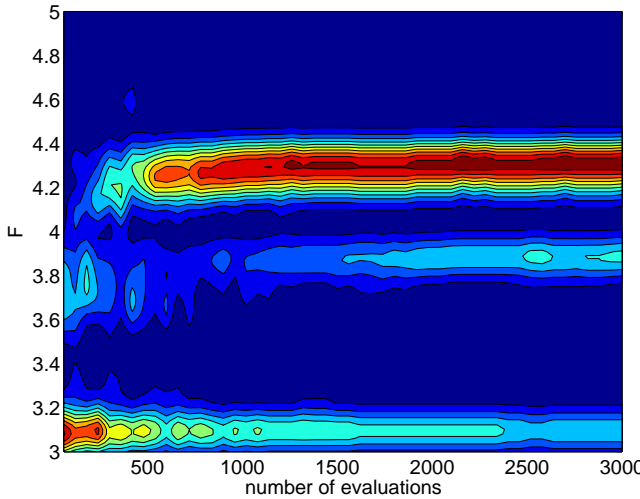


- ⇒ UMDA and GA locally improve the initial candidate solutions, but fail to converge to high-fitness solutions
- ⇒ DDOA reliably finds the optimum

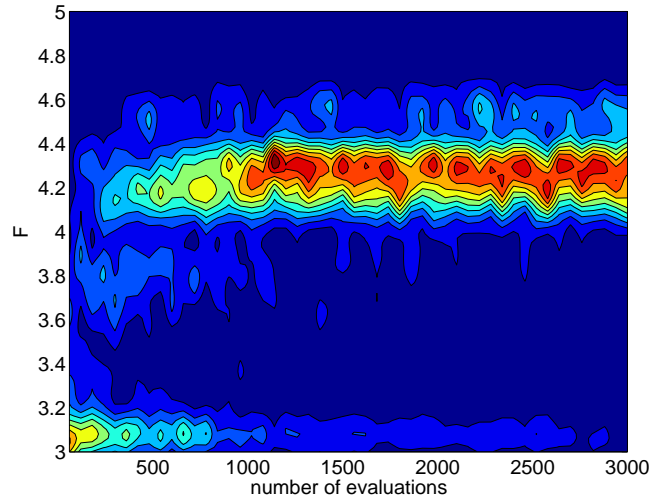
Distribution of the solutions found



UMDA

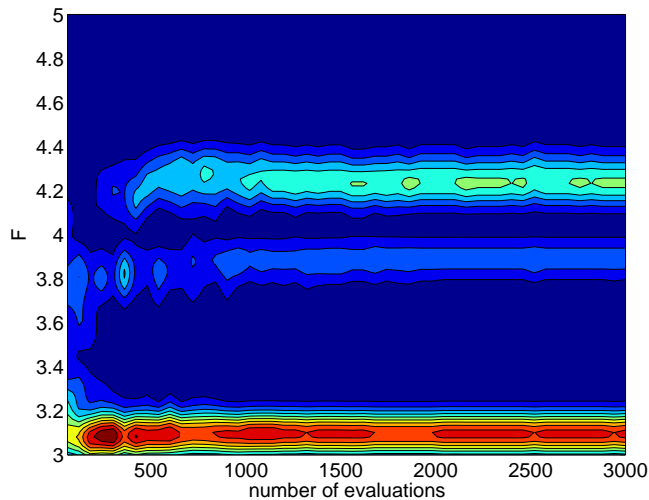


GA

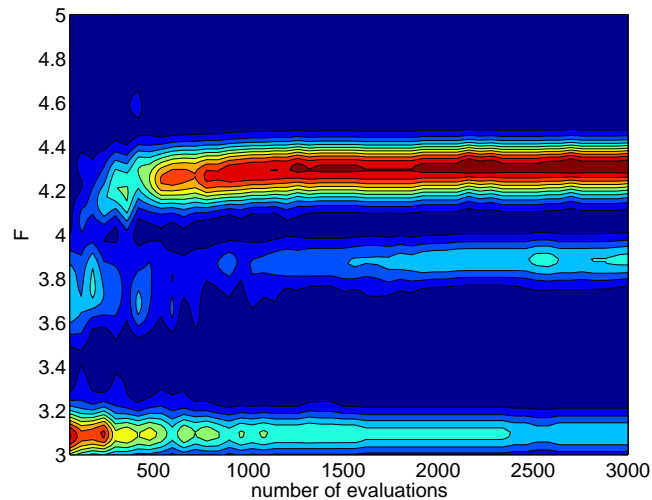


DDOA

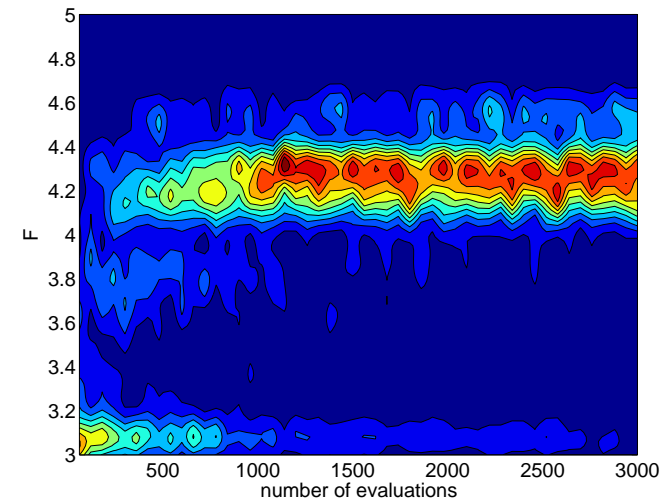
Distribution of the solutions found



UMDA



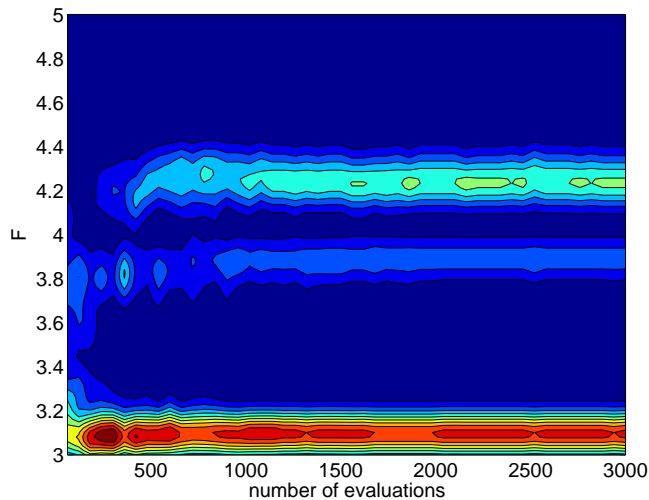
GA



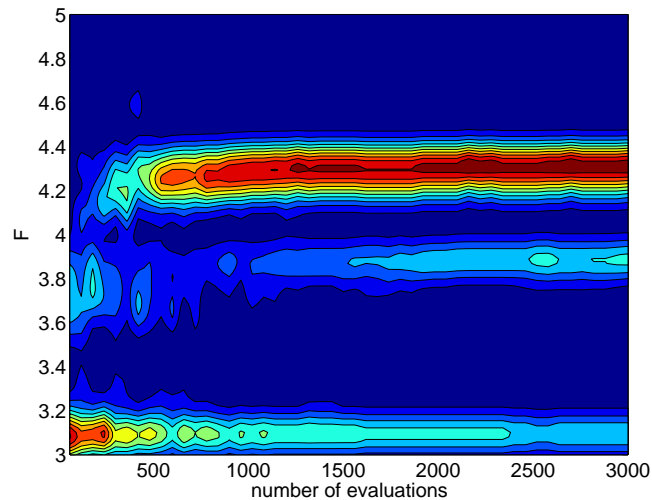
DDOA

- UMDA converges to poor solutions easy to find (e.g. $[0_4 / \pm 22.5_3 / \pm 45_3 / \pm 67.5 / 90_6]_s$): the univariate model cannot identify good regions

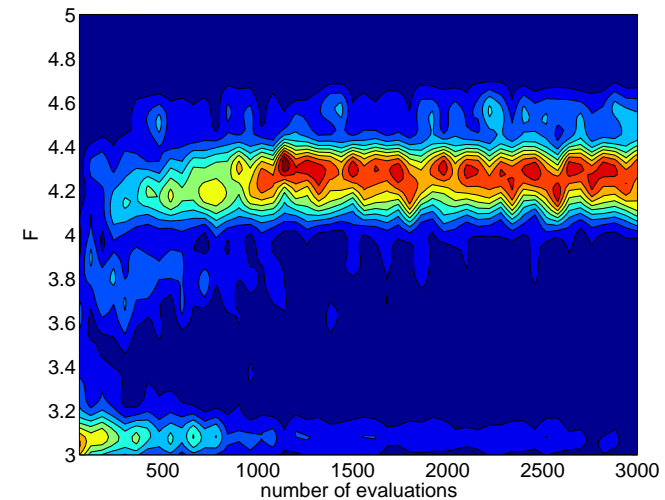
Distribution of the solutions found



UMDA



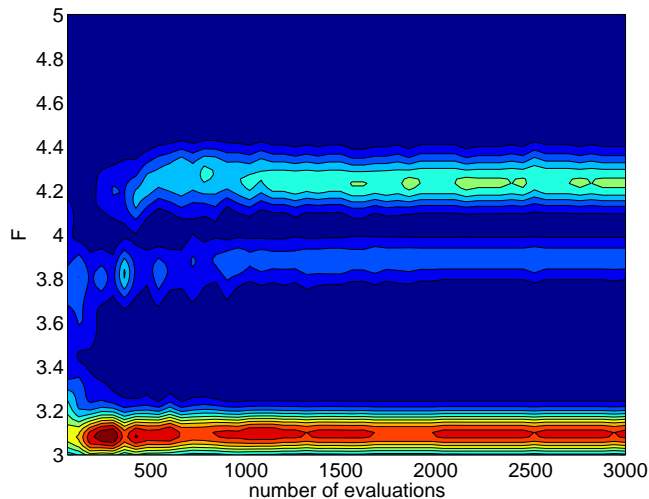
GA



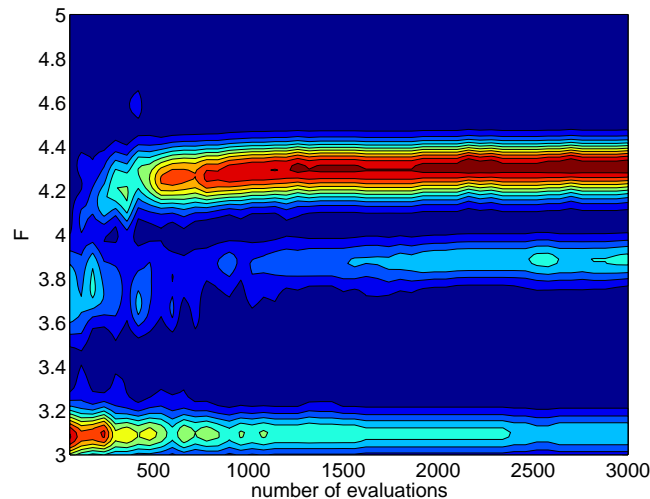
DDOA

- UMDA converges to poor solutions easy to find (e.g. $[0_4 / \pm 22.5_3 / \pm 45_3 / \pm 67.5 / 90_6]_s$): the univariate model cannot identify good regions
- GA correctly converges to the neighborhood of the global optimum, but does not explore it (small variance)

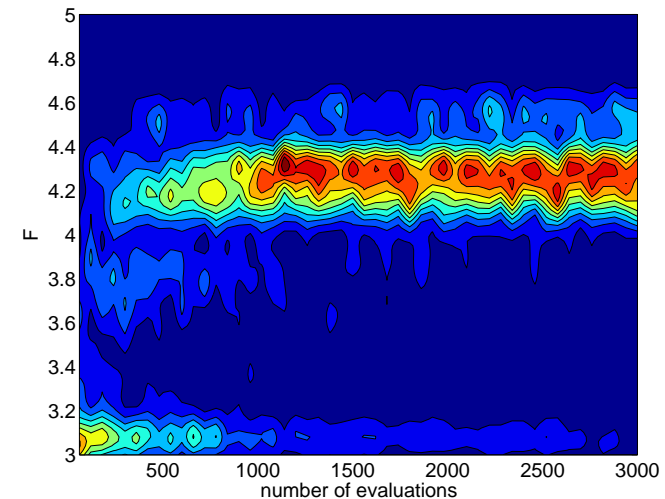
Distribution of the solutions found



UMDA



GA



DDOA

- UMDA converges to poor solutions easy to find (e.g. $[0_4 / \pm 22.5_3 / \pm 45_3 / \pm 67.5 / 90_6]_s$): the univariate model cannot identify good regions
- GA correctly converges to the neighborhood of the global optimum, but does not explore it (small variance)
- DDOA focuses the search on high-fitness regions. The two lower basins of attraction present in GA and UMDA barely appear

Diversity preservation mechanisms

- Theoretical EDA: infinite population λ

Diversity preservation mechanisms

- Theoretical EDA: infinite population λ
- Implementation: finite (small) population \Rightarrow estimation error on $p(\mathbf{x})$

Diversity preservation mechanisms

- Theoretical EDA: infinite population λ
- Implementation: finite (small) population \Rightarrow estimation error on $p(\mathbf{x})$
- Observation: tendency to underestimate p in unexplored regions (loss of variable values = “premature convergence”)

Diversity preservation mechanisms

- Theoretical EDA: infinite population λ
- Implementation: finite (small) population \Rightarrow estimation error on $p(\mathbf{x})$
- Observation: tendency to underestimate p in unexplored regions (loss of variable values = “premature convergence”)
- \Rightarrow Diversity preservation mechanisms must be implemented to compensate for lost points

Diversity preservation mechanisms

- Theoretical EDA: infinite population λ
- Implementation: finite (small) population \Rightarrow estimation error on $p(\mathbf{x})$
- Observation: tendency to underestimate p in unexplored regions (loss of variable values = “premature convergence”)
 - \Rightarrow Diversity preservation mechanisms must be implemented to compensate for lost points
- Two mechanisms:

Diversity preservation mechanisms

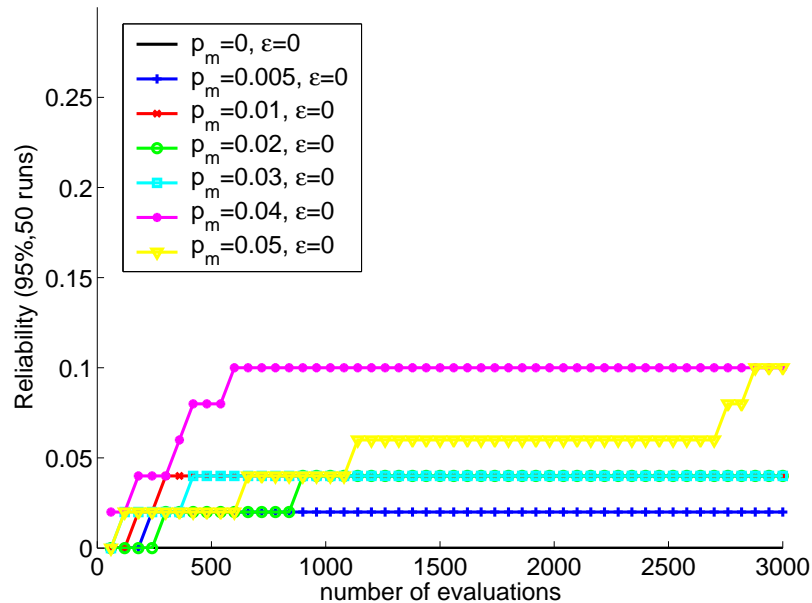
- Theoretical EDA: infinite population λ
- Implementation: finite (small) population \Rightarrow estimation error on $p(\mathbf{x})$
- Observation: tendency to underestimate p in unexplored regions (loss of variable values = “premature convergence”)
 - \Rightarrow Diversity preservation mechanisms must be implemented to compensate for lost points
- Two mechanisms:
 - **mutation**: a perturbation is applied with probability p_m to each variable θ_k of each of the λ created points

Diversity preservation mechanisms

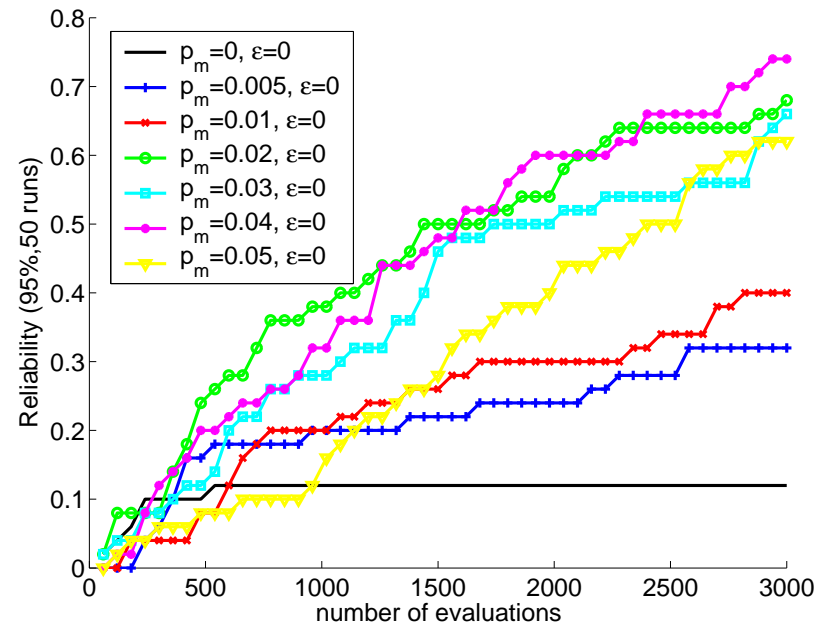
- Theoretical EDA: infinite population λ
- Implementation: finite (small) population \Rightarrow estimation error on $p(\mathbf{x})$
- Observation: tendency to underestimate p in unexplored regions (loss of variable values = “premature convergence”)
 - \Rightarrow Diversity preservation mechanisms must be implemented to compensate for lost points
- Two mechanisms:
 - **mutation**: a perturbation is applied with probability p_m to each variable θ_k of each of the λ created points
 - **lower bound on marginal probabilities**: the probability $p(\theta_k = c_l)$ is not allowed to fall below a threshold ϵ

Effect of mutation

UMDA

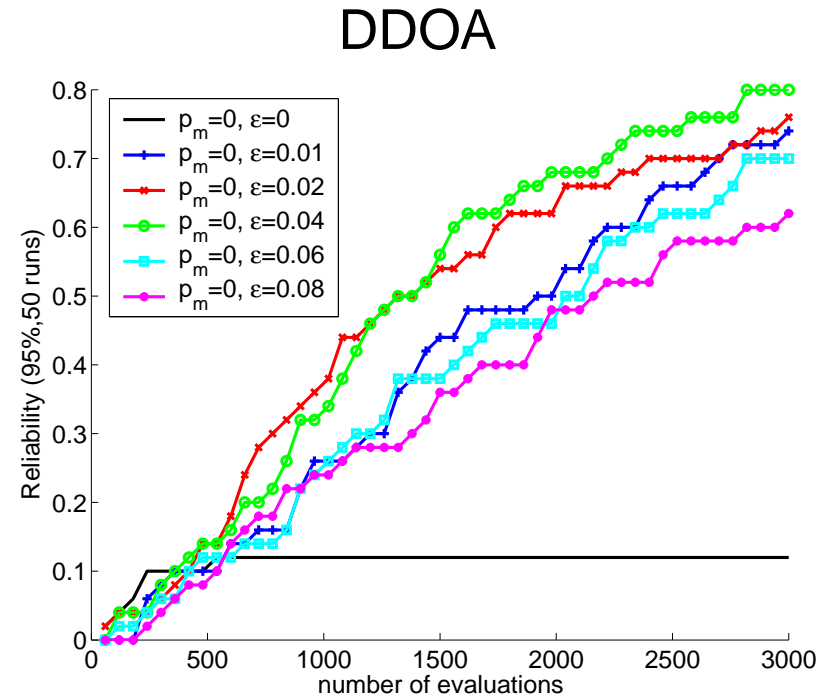
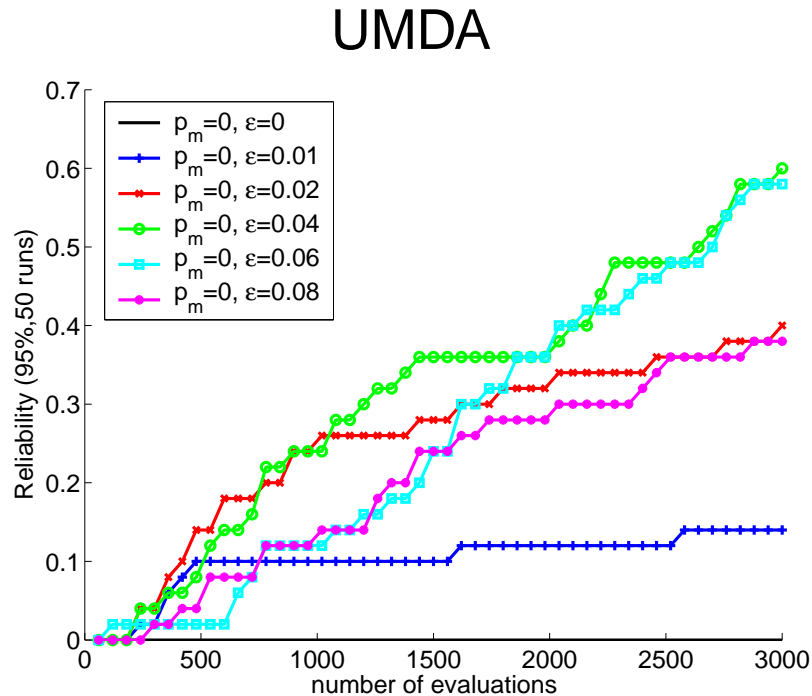


DDOA



- even with a large mutation rate, UMDA does not reliably find the optimum (probability of obtaining a good point by chance very low with $n = 12$)
- mutation greatly improve DDOA's performance: the auxiliary variable scheme filters out poor candidates created by mutation

Effect of the lower bound on marginal distributions



- preventing probabilities to vanish improves UMDA's reliability but it remains inferior to DDOA.
- DDOA greatly benefits from bounding the probabilities. The performance is not sensitive to the value of ϵ same explanation as for mutation

Performance with optimized parameters for the strength problem

- Parameter study for GA, UMDA, and DDOA

Performance with optimized parameters for the strength problem

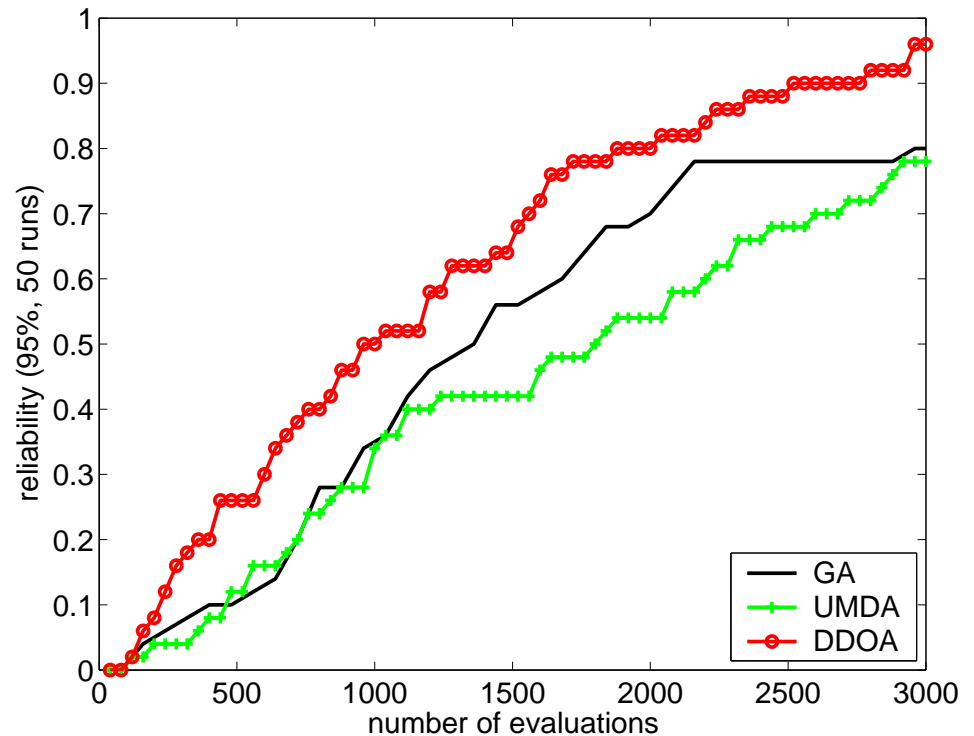
- Parameter study for GA, UMDA, and DDOA
- Let λ , ν , p_m , ϵ vary

Performance with optimized parameters for the strength problem

- Parameter study for GA, UMDA, and DDOA
- Let λ , ν , p_m , ϵ vary
- Best variants:
 - GA:** $\lambda = 80$, $p_m = 0.02$
 - UMDA:** $\lambda = 40$, $\epsilon = 0.06$
 - DDOA:** $\lambda = 40$, $\nu = 200$, $\epsilon = 0.06$

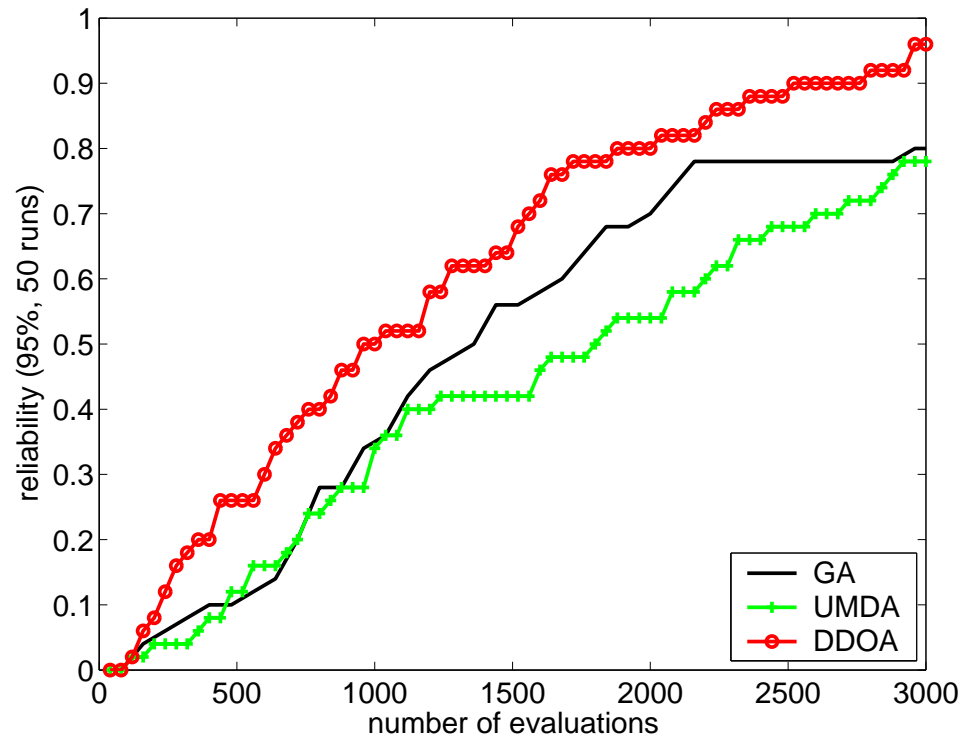
Performance with optimized parameters for the strength problem

- Parameter study for GA, UMDA, and DDOA
- Let λ , ν , p_m , ϵ vary
- Best variants:
GA: $\lambda = 80$, $p_m = 0.02$
UMDA: $\lambda = 40$, $\epsilon = 0.06$
DDOA: $\lambda = 40$, $\nu = 200$, $\epsilon = 0.06$



Performance with optimized parameters for the strength problem

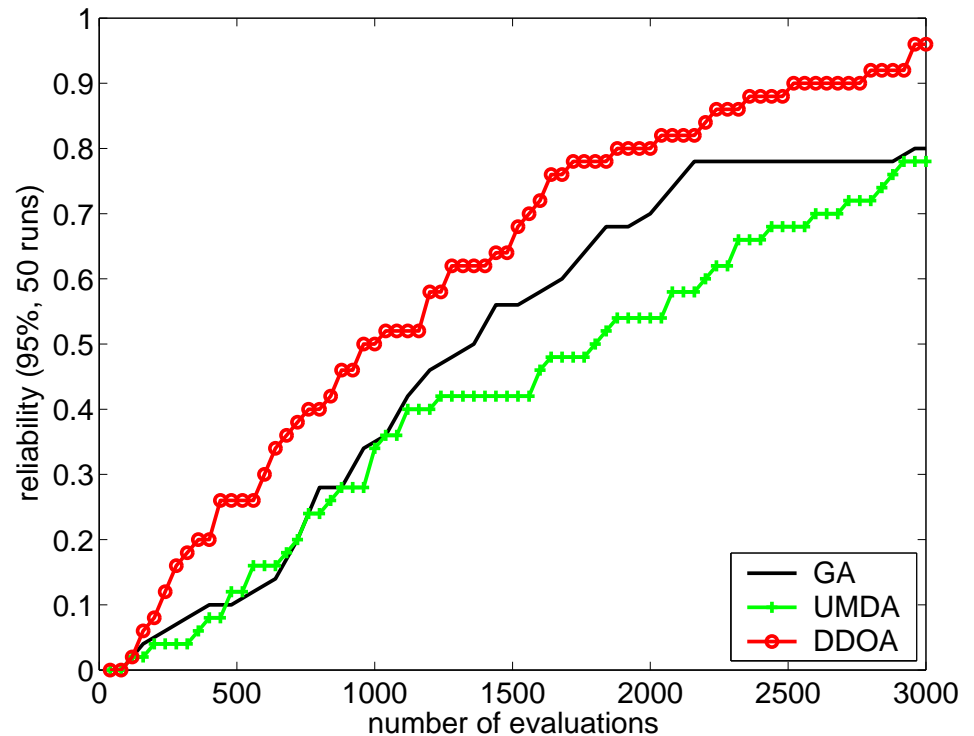
- Parameter study for GA, UMDA, and DDOA
- Let λ , ν , p_m , ϵ vary
- Best variants:
GA: $\lambda = 80$, $p_m = 0.02$
UMDA: $\lambda = 40$, $\epsilon = 0.06$
DDOA: $\lambda = 40$, $\nu = 200$, $\epsilon = 0.06$



⇒ Significant improvement over UMDA (variable dependencies)

Performance with optimized parameters for the strength problem

- Parameter study for GA, UMDA, and DDOA
- Let λ , ν , p_m , ϵ vary
- Best variants:
 - GA:** $\lambda = 80$, $p_m = 0.02$
 - UMDA:** $\lambda = 40$, $\epsilon = 0.06$
 - DDOA:** $\lambda = 40$, $\nu = 200$, $\epsilon = 0.06$



- ⇒ Significant improvement over UMDA (variable dependencies)
- ⇒ DDOA more efficient than GA even without mutation

General Conclusions

Concluding Remarks

- **Estimation of Distribution Algorithms** are a formalization of evolutionary algorithms: provide a sound statistical framework

Concluding Remarks

- **Estimation of Distribution Algorithms** are a formalization of evolutionary algorithms: provide a sound statistical framework
- Applicability to laminate optimization was demonstrated: UMDA displayed comparable to higher performance than other stochastic algorithms (SHC and GA)

Concluding Remarks

- **Estimation of Distribution Algorithms** are a formalization of evolutionary algorithms: provide a sound statistical framework
- Applicability to laminate optimization was demonstrated: UMDA displayed comparable to higher performance than other stochastic algorithms (SHC and GA)
- A strategy for improving the statistical model of promising regions through auxiliary variables was proposed: the **Double-Distribution Optimization Algorithm**

Concluding Remarks

- **Estimation of Distribution Algorithms** are a formalization of evolutionary algorithms: provide a sound statistical framework
- Applicability to laminate optimization was demonstrated: UMDA displayed comparable to higher performance than other stochastic algorithms (SHC and GA)
- A strategy for improving the statistical model of promising regions through auxiliary variables was proposed: the **Double-Distribution Optimization Algorithm**
- Application to laminate optimization showed the efficiency of the approach for problems with strong variable dependencies + greater stability to the value of the algorithm parameters

Concluding Remarks

- **Estimation of Distribution Algorithms** are a formalization of evolutionary algorithms: provide a sound statistical framework
- Applicability to laminate optimization was demonstrated: UMDA displayed comparable to higher performance than other stochastic algorithms (SHC and GA)
- A strategy for improving the statistical model of promising regions through auxiliary variables was proposed: the **Double-Distribution Optimization Algorithm**
- Application to laminate optimization showed the efficiency of the approach for problems with strong variable dependencies + greater stability to the value of the algorithm parameters
- A study of the diversity was conducted: proposed direct control of the distribution diversity

Future work

- Extension of DDOA to continuous problems (constraints as auxiliary variables): preliminary results are promising

Future work

- Extension of DDOA to continuous problems (constraints as auxiliary variables): preliminary results are promising
- Application to other fields where auxiliary variables are available

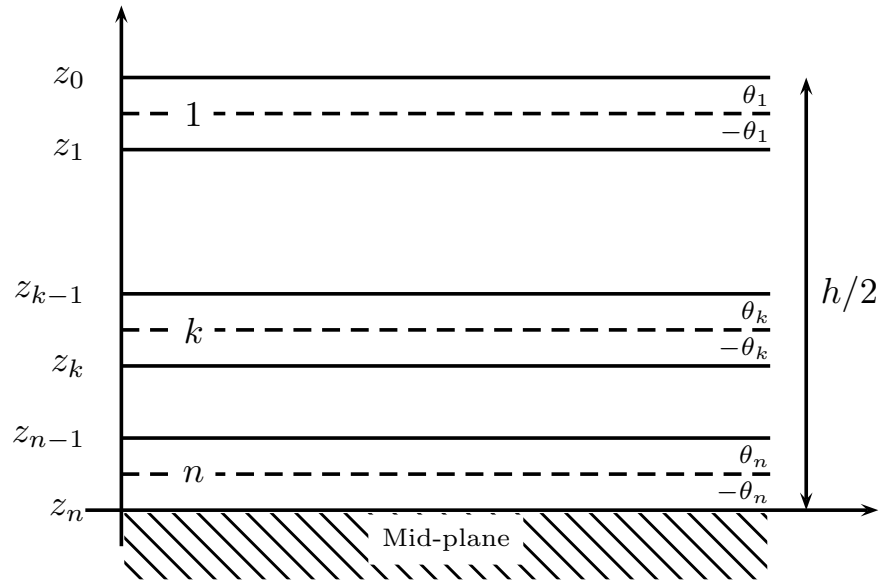
Future work

- Extension of DDOA to continuous problems (constraints as auxiliary variables): preliminary results are promising
- Application to other fields where auxiliary variables are available
- Detection of failure situations: how to check the validity of $p(\mathbf{x})$ and what to do when failure is detected?

Backup Slides

Balanced symmetric laminate

- Particular case: balanced symmetric laminates
 $[\pm\theta_1, \pm\theta_2, \dots, \pm\theta_n]_s$



Constraint enforcement through a penalty approach

- Consider the following optimization problem:

$$\begin{array}{ll} \text{maximize} & F(\mathbf{x}) \\ \text{such that} & g_j(\mathbf{x}) \geq 0, \quad j = 1, \dots, m \end{array}$$

Constraint enforcement through a penalty approach

- Consider the following optimization problem:

$$\begin{array}{ll} \text{maximize} & F(\mathbf{x}) \\ \text{such that} & g_j(\mathbf{x}) \geq 0, \quad j = 1, \dots, m \end{array}$$

- The penalty approach transforms this **constrained problem** into an **unconstrained problem** by decreasing the objective function proportionally to the constraint violation:

$$F_p(\mathbf{x}) = \begin{cases} F(\mathbf{x}) & \text{if } g_j(\mathbf{x}) \geq 0, \quad j = 1, \dots, m \\ F(\mathbf{x}) + p \min_{j=1}^m (g_j(\mathbf{x})) & \text{if } \exists k \in \{1, \dots, m\} \text{ s.t. } g_k(\mathbf{x}) < 0 \end{cases}$$

Kernel density estimate: principle

- $f(V)$ is continuous, low dimensional (2D or 4D in our problems) \Rightarrow A kernel density estimation approach is adopted:

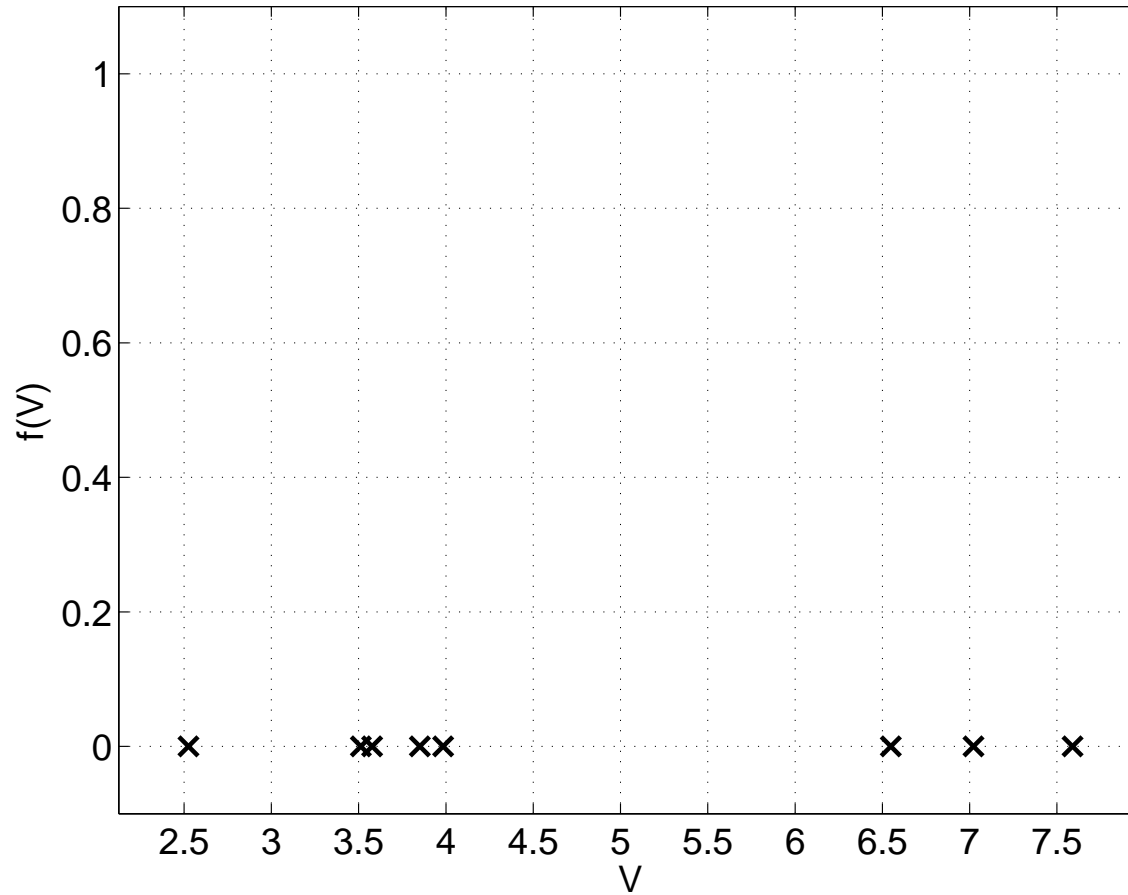
$$f(\mathbf{V}) = \frac{1}{\mu} \sum_{i=1}^{\mu} K(\mathbf{V} - \mathbf{V}_i)$$

In this work, we used Gaussian kernels:

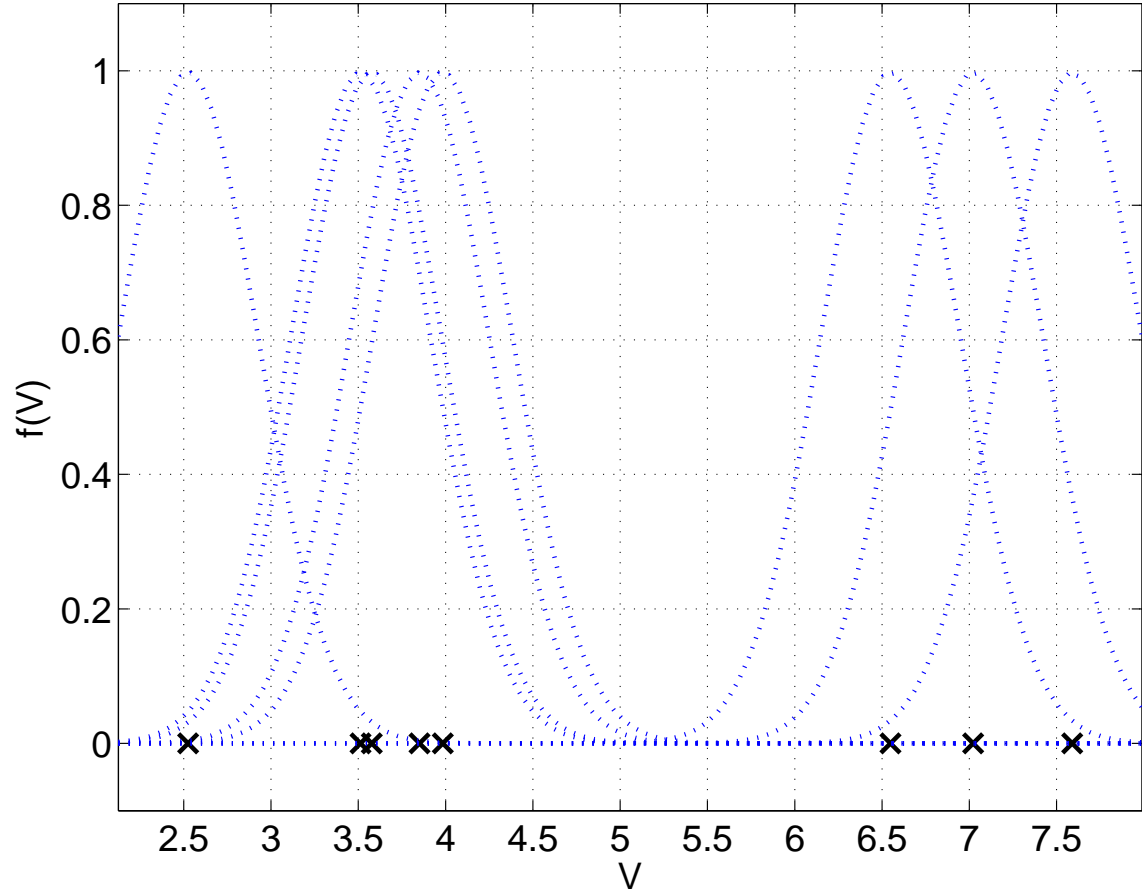
$$K(\mathbf{u}) = \frac{1}{(2\pi)^{d/2} \sigma^d} \exp\left(-\frac{\mathbf{u}^T \mathbf{u}}{\sigma^2}\right)$$

where σ determines the smoothness of the estimate

Kernel density estimate: illustration



Kernel density estimate: illustration



Kernel density estimate: illustration

