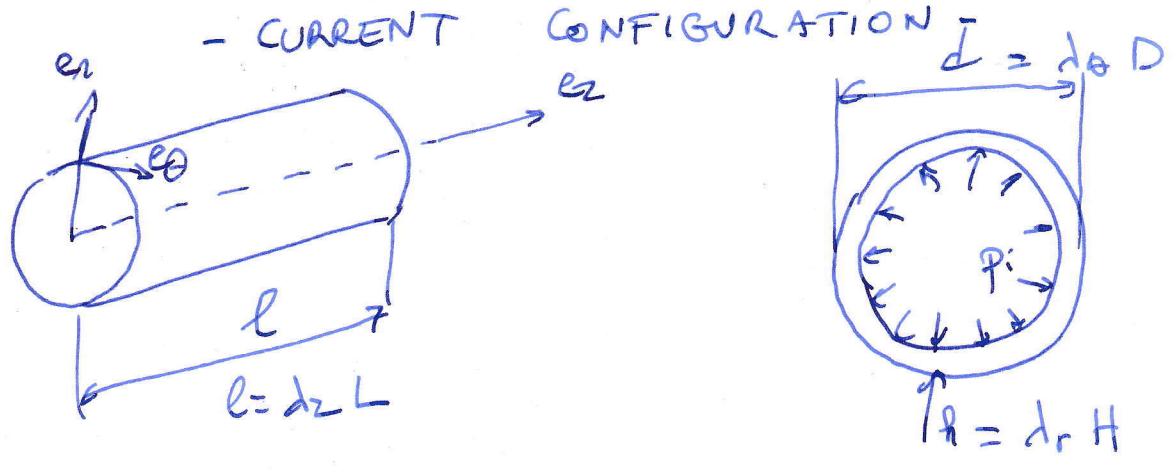


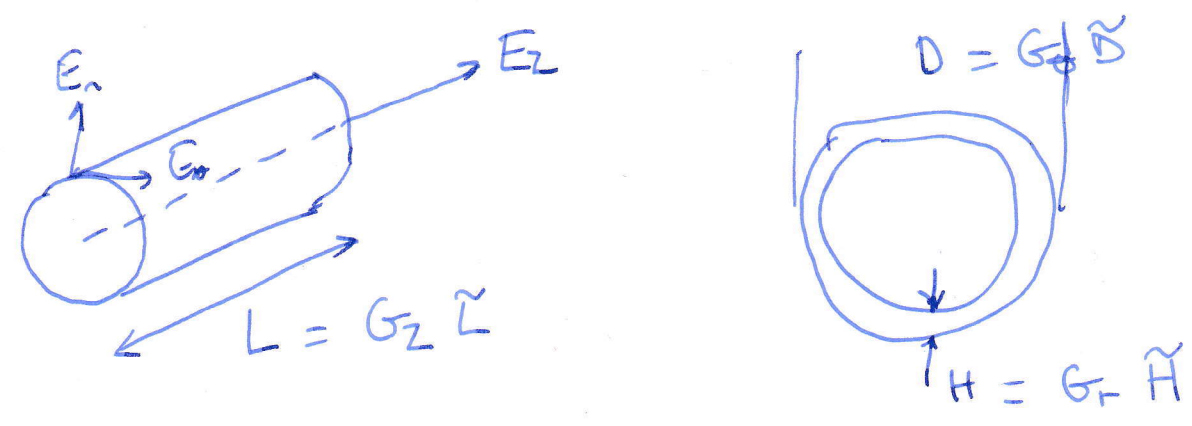
deformation gradient F (non growth related)



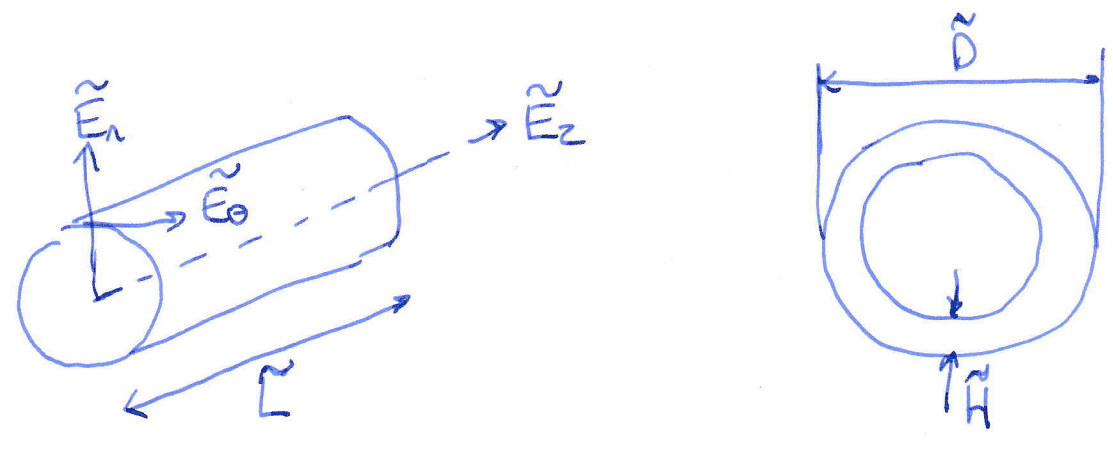
Laplace law : $\sigma_{\theta\theta} = \frac{p_i d}{2h}$

deformation gradient G

- INTERMEDIATE CONFIGURATION



- REFERENCE CONFIGURATION



a) G is the deformation gradient related to growth (from the reference to the intermediate configuration) ⁽²⁾

$$G = \begin{bmatrix} G_r & 0 & 0 \\ 0 & G_\theta & 0 \\ 0 & 0 & G_z \end{bmatrix}$$

$$= G_r E_r \otimes \tilde{E}_r + G_\theta E_\theta \otimes \tilde{E}_\theta + G_z E_z \otimes \tilde{E}_z$$

$$\begin{matrix} \downarrow & \downarrow & \downarrow \\ \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} & \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} & \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \end{matrix}$$

(Rk) The constant volume growth would be:

$$J = \det(G) = \text{constant}$$

$$\frac{\partial}{\partial t} (\det(G)) = 0$$

$$\text{Tr}(\dot{G}) = 0$$

(Rk) The constant density growth is:

$$\rho_0 = \text{constant} = \frac{1}{J} = \frac{1}{\det(G)}$$

$$\frac{\partial \rho_0}{\partial t} = \dot{\rho}_0 = 0$$

$$\Rightarrow \frac{\partial}{\partial t} \left(\frac{1}{\det G} \right) = 0$$

$$\Rightarrow \text{Tr}(\dot{G} G^{-1}) = 0$$

In the problem, the rate of volume change ⁽³⁾
 is \dot{S}_v .

This means $\dot{p}_0 = T_r (\dot{G} G^{-1}) = \dot{S}_v$

$$\Rightarrow G_0^{-1} \dot{G}_0 + G_z^{-1} \dot{G}_z + G_r^{-1} \dot{G}_r = \dot{S}_v$$

a:
$$\boxed{\frac{\dot{G}_r}{G_r} + \frac{\dot{G}_0}{G_0} + \frac{\dot{G}_z}{G_z} = \dot{S}_v}$$

if isotropic, $G_r = G_0 = G_z = G$, so $\boxed{\dot{S}_v = 3 \frac{\dot{G}}{G}}$

b) Non growth related deformation gradient:

$$F = \begin{bmatrix} dr & 0 & 0 \\ 0 & d\theta & 0 \\ 0 & 0 & dz \end{bmatrix}$$

$$J = 1$$

$$dr d\theta dz = 1$$

→ no change of volume

$$\rightarrow H = \frac{h}{dr} = d\theta dz h$$

The question is to relate \dot{S}_v and the non growth related deformation gradient for homostatic conditions.

The homostatic conditions means $\frac{p_i}{\sigma_0}$ is a constant k , such as $h = kd$ (Laplace law)

$$G_r = H/A = d\theta dz h/A = d\theta dz kd/A$$

isotropic: $G = G_r = d\theta^2 dz kd/A$

then $\dot{G} = 2 d\theta d\dot{\theta} dz kd/A \rightarrow *$

Finally:

$$\frac{\dot{G}}{G} = \frac{2 \lambda_0 \dot{\lambda}_0 \cancel{dz} \cancel{k} \cancel{A}}{\lambda_0^2 \cancel{dz} \cancel{k} \cancel{A}}$$

$$\frac{\dot{G}}{G} = 2 \frac{\dot{\lambda}_0}{\lambda_0}$$

$$\boxed{S_v = 3 \frac{\dot{G}}{G} = 6 \frac{\dot{\lambda}_0}{\lambda_0}}$$

* Note that the derivative of dz with time $\frac{dz}{dt}$ is zero ($\dot{z}=0$) as $z = l/L$ is a constant.

CONCLUSION.

For any elastic stretch variation λ_0 , the homeostasis is maintained if:

$$S_v = 6 \frac{\dot{\lambda}_0}{\lambda_0}$$